



Article The Influence of Ankle Mobility and Foot Stability on Jumping Ability and Landing Mechanics: A Cross-Sectional Study

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Abstract: Practicing physical activities or sports that involve frequent jumping and landing can strain the muscles and joints of the lower limbs, especially in those who do not have adequate physical preparation. The objective of this study was to (a) determine the correlation between ankle range of motion (ROM) and landing stability following jumps; (b) assess the association between the jump height in a counter-movement jump (CMJ) test and ankle ROM; and (c) examine the connection between stabilometry during specific jumps movements present in many sports and in ankle stabilization. Sixty-two healthy amateur volleyball players participated in the study (age: thirty-seven females and twenty-five males; age (years): 16.5 \pm 4.25; height (cm): 166 \pm 11.4; weight (Kg): 61.6 ± 13.7). Participants were recruited for the study in collaboration with student sports associations. The evaluations encompassed the measurement of ankle joint mobility for both lower limbs using an inertial sensor, a static baropodometric and stabilometric analysis using a pressure platform, and the CMJ test using the Microgate system. After the assessments, participants performed a "specific jump landing task". Significant correlations were found between foot range of motion (ROM) and counter-movement jump (CMJ) performance. Specifically, the ROM of the right foot had a strong correlation with the CMJ (r = 0.81, p < 0.001), while the left foot ROM showed a moderate correlation (r = 0.46, p < 0.001). The specific jump task revealed substantial changes in stabilometry parameters, particularly during forward hops compared to lateral jumps. Dorsiflexion ROM significantly impacts jumping ability. Evaluating landing patterns and stabilometry during targeted activities can help optimize training, improve dynamic balance, and reduce ankle injury risk.

Keywords: ankle injury; postural control; range of motion; balance

1. Introduction

In many sports and sports activities, repeated jumps and landings place significant stress on the lower limb muscles and joints, increasing the risk of musculoskeletal injuries [1]. In a study, Bahr et al. reported that in 78% of the cases, team players had a history of at least one prior ankle injury [2,3]. In a population of volleyball players, the authors showed that ankle injuries primarily happened during the act of landing after blocking,



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Copyright: © 2024 by the authors. Licensee MDPI, Basel, Switzerland. This article is an open access article distributed under the terms and conditions of the Creative Commons Attribution (CC BY) license (https:// creativecommons.org/licenses/by/ 4.0/). whereas most other injuries were linked to take-off, landing, or the spiking motion during an attack [3]. However, noteworthy relationships are also present in other sports gestures. Akbari H, et al. (2023) investigated the relationship between the ROM of ankle landing positions during a soccer-specific task [4]. The results showed that a reduced ROM of ankle dorsiflexion was associated with greater landing errors in a soccer-specific situation. For this reason, it could be possible to state that the assessment of ankle mobility is an important process to prevent faulty movements and potentially related injuries [4]. Similar athletic gestures are observed in other sports as well. Ungureanu AN, Beratto L. et al. demonstrated that rugby players also exhibit comparable kinematics. Their study revealed performance improvements, particularly in jumping, sprinting, and high-intensity running [5].

These risks are heightened in amateur sports and student leagues, where participants are at a greater risk of sustaining non-contact injuries [6]. Asperti AM et al. demonstrated that injury rates are significantly higher in amateur sports, particularly those focused on fitness improvement or student activities [6]. This can lead to prolonged interruptions or even withdrawal from physical activity. Adolescent sports injuries present a significant issue that can lead to withdrawal from physical activity. Further research is needed to better understand the impact of risk factors and improve prevention efforts [7].

The literature suggests the need for preventive strategies and training programs, but further research into the etiology of injuries is essential to develop effective measures. Injuries to the ankle and knee joints, particularly those to the anterior cruciate ligament (ACL), have been linked to ankle joint kinematics, such as dorsiflexion angles during landings [8–10].

In 2021, Cejudo A. presented evidence indicating potential disparities in range of motion (ROM) between genders. This study provides gender-specific scores for lower extremity flexibility profiles in basketball players. This study suggests that athletic trainers and conditioning coaches identify players who may be at high risk of injury due to abnormal ROM scores [11]. The study of Boden et al. (2009) evaluated the foot position and hip, knee, and ankle joint angles of athletes at the time of an ACL injury and compared these values with a control group of athletes who experienced no injuries [8]. The results of this study showed that athletes of the control group first contacted the ground with the forefoot while athletes of the experimental group had first ground contact with the hindfoot or entirely flatfooted.

Another study by Malloy et al. (2016) analyzed the association between ankle dorsiflexion flexibility and landing kinematics in female soccer players during a drop vertical jump [12]. The results showed that females with less ankle dorsiflexion flexibility exhibited greater peak knee abduction moments and angles as well as less peak knee flexion angles during landing, suggesting that ankle dorsiflexion may influence landing posture kinematics and kinetics, making its evaluation important for injury prevention [12]. A limitation of this study declared by the authors is that the ankle dorsiflexion was evaluated with the knee in the full extended position, and in this way, it was not possible to measure the soleus muscle, which can influence the dorsiflexion flexibility [12]. Another limitation of this study is the height of the box that was normalized and not weighted to the height of the subject. We hypothesize that the landing height concerning the anthropometric measurements of the tested subject are variable and should not be overlooked and indefinitely personalizing the evaluation task as much as possible is necessary. Other studies have also noted limitations such as not simulating sport-specific tasks or standardizing drop jump box heights [13,14]. The lateral cutting movements are very frequent in team sports like volleyball [15]. Over time, these pressures might result in persistent ankle instability caused by harm to the lateral ankle ligaments [16]. However, there are limited studies on stability strategies during unilateral jump-landing tasks [17].

Another interesting study showed that increasing the ROM of the ankle, particularly dorsiflexion, in addition to preventing injuries, showed an increase in performance on the single-leg vertical jump height of fifty-two recreational athletes of both genders [18]. Rabin,

A. et al. also confirmed this relationship in their study, highlighting the importance of evaluating ankle dorsiflexion [19].

The objective of this study was to examine the connection between ankle range of motion (ROM) and landing stability following jumps, evaluate the correlation between ankle ROM and jump height in the counter-movement jump (CMJ) test, and analyze stabilometry during specific jumping movements and landing by introducing a customizable task tailored to the subject's characteristics.

2. Materials and Methods

2.1. Study Design

This is a cross-sectional study. Given the study's purpose, a cross-sectional design was deemed more appropriate, as it is useful for assessing the prevalence of conditions, behaviors, or outcomes and is well suited for evaluating associations between variables by analyzing multiple outcomes.

2.2. Subjects

This study recruited a total of seventy-two students who play volleyball at an amateur level. However, only sixty-two individuals (thirty-seven females and twenty-five males; age (years): 16.5 ± 4.25 ; height (cm): 166 ± 11.4 ; weight (Kg): 61.6 ± 13.7 ; dominant foot (n): right 55 subjects and left 7 subjects) fulfilled the inclusion requirements. The remaining 10 were excluded due to not having played or exercised regularly for at least six months (Table 1). An a priori sample size power analysis with an α error of 0.05 and an effect size of 0.5 revealed that sixty-two participants would be sufficient to reach a power of 99% [20]. The STROBE guidelines were used to ensure a high-quality presentation of the conducted observational study (Figure 1) [21]. Consistent with the recommendations of the literature and comparable research [10,22–24], we included in the study those who met the following inclusion criteria:

- (a) Participants had no leg injuries in the past six months.
- (b) All participants had been playing and exercising regularly for at least six months.
- (c) There were no post-surgical subjects.

Table 1. Subject demographics.

| | Subjects (n) | Age (y) | Height (cm) | Weight (kg) |
|-----------|--------------|---------|-------------|-------------|
| Maan | F (37) | 16.0 | 161 | 55.9 |
| Mean | M (25) | 17.2 | 174 | 69.9 |
| Standard | F (37) | 4.78 | 8.57 | 11.7 |
| deviation | M (25) | 3.27 | 10.6 | 12.4 |

M: Male; F: female; n: numbers; y: years; cm: centimeters; Kg: kilograms.

Researchers collected demographics and sports injury history, and participants signed written informed consent forms. Parental consent was also obtained for minors (<18 years). The subjects were invited to the gymnasium, where they were briefed on the research and evaluations without disclosing the study's objectives to avoid influencing performance. Anthropometric data were collected from the same research unit between September 2022 and December 2022. We also obtained written informed consent from parents of minors (<18 years). The study was carried out in compliance with the principles of the Declaration of Helsinki and approved by the Bioethics Committee of the University of Palermo (n. 94/2022-Prot. 70310; 4 July 2022).



Figure 1. Experimental design: STROBE Flow diagram.

2.3. Procedures

Prior to the evaluations, participants engaged in a standardized warm-up regimen consisting of gentle jogging and a combination of static and dynamic stretching exercises to prime the muscles and joints. The evaluations were carried out in the team gymnasium on a conventional wooden floor from 5:00 to 8:00 PM. All participants were required to have a minimum recovery interval of 72 h since their last game to ensure they were not fatigued. The initial evaluation focused on assessing ankle joint mobility by measuring both the range and quality of movement in each ankle. Participants then performed a countermovement jump (CMJ). Following 30 min of rest, participants had stabilometric analysis, which was especially conducted during the jump-landing phase to evaluate their balance and postural control in dynamic situations. This analysis offered valuable perspectives on the post-landing stability management strategies.

2.3.1. The Measure of the Ankle Range of Motion

One small Bluetooth sensor was used to measure the joint mobility of the ankle (internal sampling up to 1000 Hz; Bluetooth 4.0 and 2.0—USB connection 2.0; weight: 28 gr; dimensions: $65 \times 45 \times 18$ mm; resolution: accelerometer = ± 2 G to ± 16 G gyroscope = $\pm 200^{\circ}$ /s to $\pm 2000^{\circ}$ /s magnetometer = $\pm 44000 \mu$ T). BEYOND Inertial used the Beyond framework software (Motustech SRL, Guidonia Montecelio, Roma, Italy). BEYOND Inertial was attached to the foot's dorsum of each participant using ad hoc straps [25] to limit their oscillations relative to the underlying segment [26] (Figure 2). Once the accelerometer was set, the subject, who was in a sitting position with flexed knee, was asked to actively perform a maximum plantar flexion movement and a maximum back flexion movement. In line with similar studies, we recorded ankle ROM after a single evaluation, following familiarization sessions in previous days. This approach aimed to replicate the natural ankle adaptation during game phases, where multiple flexions typically do not occur before a jump [27].



Figure 2. Measurement of joint mobility with accelerometer.

Data acquired by the BEYOND Inertial were transmitted via Bluetooth to a laptop. The parameters considered for the statistical analysis were as follows:

- Range of motion (ROM°): It represents the angular excursion carried out by the segment that rotates from its starting point to its arrival point.
- Angular speed (°/s): It represents the average angular velocity over the entire range of motion.
- Fluency Index: An index ranging from 0 to 1 indicates the movement's quality. The closer it is to 1, the smoother the movement. The dorsiflexion, plantar flexion, eversion, and inversion of both feet of all the subjects analyzed were evaluated on these three parameters (Figure 2).

2.3.2. Counter-Movement Jump (CMJ)

The Microgate system (Bolzano, Italy) was used to manage this test. The system allows for the quantity of flight and contact times during the execution of a series of jumps, with a precision of 1/1000 of a second. It is an optical detection system constituted of a transmitting and a receiving bar starting from these fundamental basic data; the dedicated software allows for obtaining a series of parameters related to performance with maximum precision and in real time [28]. After fully explaining experimental procedures, subjects completed a warm-up consisting of running (5 min), stretching of lower extremity muscles, and submaximal vertical jumping for the familiarization (3 min) [29]. For the test, athletes began from the upright standing position with their hands on the hips; they flexed their knees (about 90°) as fast as possible and then leaped as high as possible in the next maximum extensory phase [29]. Subjects were to leave the floor with knees and ankles extended and land in an extended position. Three measurements were administered per subject, 2 min were allowed between jump repetitions, and the best performance was considered for the study analysis [30].

2.3.3. Specific Jump-Landing Task

The study published by Butler, R. J. et al. inspired the method for performing this test [31]. However, it was adapted to suit the specific requirements of subjects engaged in sporting activities. In this modified test, athletes jumped from the ground to a stabilometric platform positioned at a distance equal to half their height. An obstacle set at 70% of their previously recorded CMJ performance was placed between the take-off point and the platform. This adaptable modification was designed to individualize testing based on each athlete's performance level, more closely replicating sporting situations. The subjects landed on the platform with only one leg seeking the best stabilization in the

shortest possible time. Participants performed single-leg landings on the platform and were instructed to stabilize for 20 s post-landing, during which stabilometric data were recorded [32]. The tests included one-legged landings after forward jumps for both legs and lateral jumps (side-step cutting) for both legs. Participants were required to adhere to predefined conditions regarding platform distance and obstacle height for all jumps. A 120 s rest period was provided between trials, and each trial was repeated three times, with the best performance on single-leg landings selected for analysis. Throughout the tests, participants' hands remained free. A trial was considered a failure if the athlete did not maintain balance for the required 20 s, jumped or moved the affected foot on the platform, dismounted with the opposite limb, or landed with the affected foot not fully on the platform [32]. The 20 s duration was chosen based on the study by Fransz, D. P. et al., which identified a stabilization period of 3–5 s following a single-leg jump. However, we adopted the maximum duration analyzed by the authors [33]. These tests were administered using the FreeMed system (FreeStep v.1.0.3 software, Sensor Medica, Guidonia Montecelio, Roma, Italy). The following parameters of the statokinesigram were considered: sway path length of the center of pressure (CoP) (mm); ellipse surface area (mm²); coordinates of the CoP along the frontal (X; right–left; x-mean) and sagittal (Y; forward–backward; y-mean) planes; and maximum oscillation and average speed of movement (mm/s) [34]. The platform's sensors are 24 K gold, allowing for high reliability.

2.4. Statistical Analyses

All data were recorded in an Excel file. Statistical analysis was performed with Jamovi (2.3.21.0).

The distribution of quantitative data was assessed with the Shapiro–Wilk test (p > 0.05). For the objectives of the study, the Pearson correlation test (r) was used to analyze the relationship among the dorsiflexion, the plantarflexion, and the eversion and inversion of the right and left feet with the entire battery of tests used. The r values are distributed as follows: r = 0.10-0.29, small or low correlation; r = 0.30-0.49, medium or moderate correlation; r = 0.50-1.0, large or high or strong correlation [35]. The independent samples *t*-test was used to compare and evaluate performance differences between female and male subjects. Paired samples *t*-test was used to evaluate if there are differences between the performance of the left leg and the right leg and between the landing after a forward jump right vs. left on jump-landing task. A multiple linear regression was used with the vertical jump height as dependent variables and the right and left dorsiflexion ROM, the right and left plantarflexion ROM foot size, right and left sway path length, and average speed of movement of both feet as independent variables that could be predictors. Statistical significance was set a priori at p < 0.05.

3. Results

Table 1 presents the demographic description. Tables 2–5 describe the correlation between the ankle valuation (right and left) and other parameters. A correlation was present between the right foot ROM° vs. vertical jump height (r = 0.81, p < 0.001) and the left foot ROM° vs. vertical jump height (r = 0.46, p < 0.001; Table 2). The analysis of dates showed interesting results, particularly with the foot's dorsiflexion. Table 6 is a comparison of parameters between males and females using the independent samples *t*-test. Data analysis showed differences in jumping performance.

| | | | Dorsiflexion of Foot | | | | | |
|------------|--|--|------------------------|------------------------------|------------------|------------------------|------------------------------|--------------------|
| | | | | Left Foot | | | Right Foot | |
| | | | Angular Speed (°/s) | Range of Motion (ROM°) | Fluency Index | Angular Speed (°/s) | Range of Motion (ROM°) | Fluency Index |
| | Dorsiflexion | Angular speed (°/s) Range of motion (ROM°) | | | | | | |
| | Dentarflorian | Fluency Index Angular speed (°/s) Panga of motion | 0.400 ** 0.360 ** | | 0.275 * | | -0.281 * | |
| | Plantarflexion | (ROM°) | | | | | | |
| Left foot | | Fluency Index | 0.540 *** | | 0.487 *** | 0.356 ** | | 0.000 # |
| | Eversion | Angular speed (°/s) Range of motion (ROM°) | 0.378 ** | | 0.261 * | 0.443 *** | | 0.293 * 0.250 * |
| | | Fluency Index | | | 0.395 ** | 0.334 ** | | |
| | Inversion | Angular speed (°/s) Range of motion (ROM°) | 0.449 *** | | | 0.597 *** | | 0.287 * |
| | | Fluency Index | 0.422 *** | | | | | |
| | Dorsiflexion | Angular speed (°/s) Range of motion (ROM°) | | 0.538 *** | 0.334 ** | | | |
| | | Fluency Index Angular speed (°/s) | 0.308 * | | 0.355 ** | 0.403 ** 0.585 *** | | 0.345 ** |
| Right foot | Plantarflexion | Range of motion (ROM°) | | 0.452 *** | | | | |
| | | Fluency Index | 0.321 * | | 0.267 * | 0.312 * | -0.287 * | 0.262 * |
| | | Angular speed (°/s) | 0.294 * | | 0.280 * | 0.627 *** | | 0.494 *** |
| | Eversion | Range of motion (ROM°) | | 0.274 * | | | 0.322 * | 0.355 ** |
| | | Fluency Index | | | 0.339 ** | 0.309* | | 0.251 * |
| | Inversion | Range of motion | | | | 0.381 ** | | 0.337 |
| | | Fluency Index | | | 0.308 * | 0.267 * | | 0.263 * |
| | | Ellipse Surface Area (mm ²) | | | | -0.315 * | | -0.406 ** |
| Left foot | One-legged landing after a forward | Maximum oscillation Average speed of movement (mm/s) | | | | | | |
| | Jump | X-mean (mm) Y-mean (mm) | | | 0.363 ** | 0.308 * | | 0.530 *** |
| | | Ellipse Surface Area (mm ²) | | | | | | -0.310 * |
| Right foot | One-legged landing after a forward | Maximum oscillation Average speed of movement (mm/s) | | | | 0.254 * | | |
| | Jump | X-mean (mm) Y-mean (mm) | | | | | | 0.305 * |
| | | Ellipse Surface Area (mm ²) | | | | | | -0.352 ** |
| | One-logged | Maximum oscillation | | | | | | |
| Left foot | landing on a lateral jump | Average speed of movement (mm/s) | | | | | | |
| | , <u> </u> | X-mean (mm) | | | 0.279 * | | | |
| | | Y-mean (mm) | | | | | | |

Table 2. Correlation between the dorsiflexion of the foot and all parameters.

Table 2. Cont.

| | | | | | Dorsiflex | ion of Foot | | |
|------------|--|--|------------------------|------------------------------|------------------|------------------------|------------------------------|------------------|
| | | | Left Foot Right Foot | | | | | |
| | | | Angular Speed (°/s) | Range of Motion (ROM°) | Fluency Index | Angular Speed (°/s) | Range of Motion (ROM°) | Fluency Index |
| | | Ellipse Surface Area (mm ²) | | | | | | |
| | One-legged landing on a lateral jump | Maximum oscillation | | | | | | |
| Right foot | | Average speed of movement (mm/s) | | | | | | |
| |) [| X-mean (mm) | | | | | | |
| | | Y-mean (mm) | | | | | | |
| | | CMJ | | 0.464 *** | | | 0.810 *** | |

The threshold for significant differences between performances is defined as: * p < 0.05, ** p < 0.01, *** p < 0.001.

 Table 3. Correlation between the plantarflexion of the foot and all parameters.

| | | | Plantarflexion of Foot | | | | | |
|------------|----------------|--------------------------------|------------------------|------------------------------|------------------|------------------------|------------------------------|------------------|
| | | | | Left Foot | | | Right Foot | |
| | | | Angular Speed (°/s) | Range of Motion (ROM°) | Fluency Index | Angular Speed (°/s) | Range of Motion (ROM°) | Fluency Index |
| | | Angular speed (°/s) | | | | | | |
| | Dorsiflexion | Range of motion (ROM°) | | | | | | |
| | | Fluency Index | | | | | | |
| | | Angular speed (°/s) | | | | | | |
| Left foot | Plantarflexion | Range of motion (ROM°) | | | | | | |
| | | Fluency Index | 0.483 *** | | | | | |
| | Eversion | Angular speed (°/s) | 0.428 *** | | 0.382 ** | | | |
| | | Range of motion (ROM°) | | 0.399 ** | | | | |
| | | Fluency Index | 0.355 ** | | 0.403 ** | | | |
| | | Angular speed (°/s) | 0.405 ** | | 0.453 *** | | | |
| | Inversion | Range of motion (ROM°) | | 0.499 *** | | | | |
| | | Fluency Index | | | 0.303 * | | | |
| | | Angular speed ($^{\circ}$ /s) | | | | | | |
| | Dorsiflexion | Range of motion (ROM°) | | | | | | |
| | | Fluency Index | | | | | | |
| | | Angular speed (°/s) | 0.466 *** | | 0.436 *** | | | |
| | Plantarflexion | Range of motion (ROM°) | | 0.585 *** | | | | |
| Right foot | | Fluency Index | 0.478 *** | | 0.464 ** | 0.626 *** | | |
| Right 100t | | Angular speed (°/s) | 0.379 ** | 0.280 * | 0.320 * | 0.715 *** | | 0.380 ** |
| | Eversion | Range of motion (ROM°) | | 0.303 * | | | 0.290 * | |
| | | Fluency Index | | | 0.290* | 0.378 ** | | 0.359 ** |
| | | Angular speed (°/s) | 0.252 * | | 0.300* | 0.656 ** | | 0.497 *** |
| | Inversion | Range of motion (ROM°) | | 0.377 ** | | 0.270 * | 0.309 * | |
| | | Fluency Index | | | 0.369 ** | 0.298 * | | |

Table 3. Cont.

| | | | Plantarflexion of Foot | | | | | |
|------------|------------------------------|--|------------------------|------------------------------|------------------|------------------------|------------------------------|------------------|
| | | | | Left Foot | | | Right Foot | |
| | | | Angular Speed (°/s) | Range of Motion (ROM°) | Fluency Index | Angular Speed (°/s) | Range of Motion (ROM°) | Fluency Index |
| | | Ellipse Surface Area (mm ²) | | | | | | |
| | One-legged | Maximum oscillation | | | | | | |
| Left foot | landing after a forward | Average speed of movement (mm/s) | | | | | | |
| | Jump | X-mean (mm) | | | | | | |
| | | Y-mean (mm) | | | | | | |
| | | Ellipse Surface Area (mm ²) | | | | | | |
| Right foot | One-legged | Maximum oscillation | | | | | | |
| | a forward | Average speed of movement (mm/s) | | | | | | |
| | Jump | X-mean (mm) | | | | | | |
| | | Y-mean (mm) | | | | | | |
| | | Ellipse Surface Area (mm ²) | | | | | | |
| | One-legged | Maximum oscillation | | | | | | |
| Left foot | landing on a lateral jump | Average speed of movement (mm/s) | | | | | | |
| | , I | X-mean (mm) | | | | | | |
| | | Y-mean (mm) | | | | | | |
| | | Ellipse Surface Area (mm ²) | | | | | | |
| | One-legged | Maximum oscillation | | | | | | |
| Right foot | landing on a lateral jump | Average speed of movement (mm/s) | | | | | | |
| | , 1 | X-mean (mm) | | | | | | |
| | | Y-mean (mm) | | | | | | |
| | | CMJ | | | | | | |

The threshold for significant differences between performances is defined as: * p < 0.05, ** p < 0.01, *** p < 0.001.

 Table 4. Correlation between the eversion of the foot and all parameters.

| | | | | | Eversio | n of Foot | | |
|-----------|----------------|--|------------------------|------------------------------|------------------|------------------------|------------------------------|------------------|
| | | | | Left Foot | | | Right Foot | |
| | | | Angular Speed (°/s) | Range of Motion (ROM°) | Fluency Index | Angular Speed (°/s) | Range of Motion (ROM°) | Fluency Index |
| | | Angular speed (°/s) | | | | | | |
| | Dorsiflexion | Range of motion (ROM°) | | | | | | |
| | | Fluency Index | | | | | | |
| | Plantarflexion | Angular speed (°/s) | | | | | | |
| | | Range of motion (ROM°) | | | | | | |
| | | Fluency Index | | | | | | |
| Left foot | Eversion | Angular speed (°/s) Range of motion (ROM°) | | | | | | |
| | | Fluency Index | 0.579 *** | | | | | |
| | | Angular speed (°/s) | 0.684 *** | | 0.352 ** | | | |
| | Inversion | Range of motion (ROM°) | | 0.307 * | | | | |
| | | Fluency Index | 0.298 * | | 0.255 * | | | |

Table 4. Cont.

| | | | Eversion of Foot | | | | | |
|------------|------------------------------|--|------------------------|------------------------------|------------------|------------------------|------------------------------|------------------|
| | | | | Left Foot | | | Right Foot | |
| | | | Angular Speed (°/s) | Range of Motion (ROM°) | Fluency Index | Angular Speed (°/s) | Range of Motion (ROM°) | Fluency Index |
| | | Angular speed (°/s) | | | | | | |
| | Dorsiflexion | Range of motion (ROM°) | | | | | | |
| | | Fluency Index | | | | | | |
| | | Angular speed (°/s) | 0.671 *** | | 0.585 *** | | | |
| | Plantarflexion | Range of motion (ROM°) | | 0.314 * | | | | |
| Right foot | | Fluency Index | 0.489 *** | | 0.465 *** | | | |
| rugin ioot | | Angular speed (°/s) | 0.695 *** | | 0.380 ** | | | |
| | Eversion | Range of motion (ROM°) | | 0.629 *** | | | | |
| | | Fluency Index | 0.314 * | | 0.480 *** | 0.464 *** | | |
| | Inversion | Angular speed (°/s) | 0.673 *** | | 0.461 *** | 0.637 *** | | 0.300 * |
| | | Range of motion (ROM°) | | | | 0.347 ** | | |
| | | Fluency Index | 0.462 *** | | 0.433 *** | 0.288 * | | 0.459 *** |
| | | Ellipse Surface Area (mm ²) | | | | | | |
| | One-legged | Maximum oscillation | | | | | | |
| Left foot | landing after | Average speed of | | | | | | |
| | a forward | movement (mm/s) | | | | | | |
| | Jump | X-mean (mm) | | | | | | |
| | | Y-mean (mm) | | | | | | |
| | | Ellipse Surface Area (mm ²) | | | | | | |
| | One-legged | Maximum oscillation | | | | | | |
| Right foot | a forward | Average speed of movement (mm/s) | | | | | | |
| | Jump | X-mean (mm) | | | | | | |
| | | Y-mean (mm) | | | | | | |
| | | Ellipse Surface Area (mm ²) | | | | | | |
| | One-legged | Maximum oscillation | | | | | | |
| Left foot | landing on a lateral jump | Average speed of movement (mm/s) | | | | | | |
| | , 1 | X-mean (mm) | | | | | | |
| | | Y-mean (mm) | | | | | | |
| | | Ellipse Surface Area (mm ²) | | | | | | |
| | One-legged | Maximum oscillation | | | | | | |
| Right foot | landing on a | Average speed of | | | | | | |
| U | lateral jump | movement (mm/s) | | | | | | |
| | lateral junip | X-mean (mm) | | | | | | |
| | | Y-mean (mm) | | | | | | |
| | | CMJ | | | | | | |

The threshold for significant differences between performances is defined as: * p < 0.05, ** p < 0.01, *** p < 0.001.

| | | | Inversion of Foot | | | | | |
|------------|--|--|------------------------|------------------------------|------------------|------------------------|------------------------------|------------------|
| | | | | Left Foot | | | Right Foot | |
| | | | Angular Speed (°/s) | Range of Motion (ROM°) | Fluency Index | Angular Speed (°/s) | Range of Motion (ROM°) | Fluency Index |
| | Dorsiflexion | Angular speed (°/s) Range of motion (ROM°) | | | | | | |
| | Plantarflexion | Fluency Index Angular speed (°/s) Range of motion (ROM°) | | | | | | |
| Left foot | Eversion | Fluency Index Angular speed (°/s) Range of motion (ROM°) | | | | | | |
| | Inversion | Angular speed (°/s) Range of motion (ROM°) | 0 382 ** | | | | | |
| | Dorsiflexion | Angular speed (°/s) Range of motion | | | | | | |
| | Plantarflexion | Fluency Index Angular speed (°/s) Range of motion | 0.633 *** | 0.476 *** | 0.265 * | | | |
| Right foot | Eversion | Fluency Index Angular speed (°/s) Range of motion (ROM°) | 0.413 *** 0.684 *** | 0.290 * | | | | |
| | Inversion | Fluency Index Angular speed (°/s) Range of motion (ROM°) | 0.757 *** 0.298 * | 0.657 *** | | 0.288 * | | |
| | | Fluency Index Ellipse Surface Area | | | | 0.36 ** | | |
| Left foot | One-legged landing after a forward jump | Maximum oscillation Average speed of movement (mm/s) X-mean (mm) Y-mean (mm) | | | | | | |
| | One-legged | Ellipse Surface Area (mm ²) Maximum oscillation | | | | | | |
| Right foot | a forward jump | Average speed of movement (mm/s) X-mean (mm) Y-mean (mm) | | | | | | |
| Left foot | One-legged landing on a lateral jump | Ellipse Surface Area (mm ²) Maximum oscillation Average speed of movement (mm/s) X-mean (mm) Y-mean (mm) | | | | | | |

Table 5. Correlation between the inversion of the foot and all parameters.

Table 5. Cont.

| | | | | | Inversio | on of Foot | | |
|------------|--------------|--|------------------------|------------------------------|------------------|------------------------|------------------------------|------------------|
| | | | Left Foot Right Foot | | | | | |
| | | | Angular Speed (°/s) | Range of Motion (ROM°) | Fluency Index | Angular Speed (°/s) | Range of Motion (ROM°) | Fluency Index |
| | | Ellipse Surface Area (mm ²) | | | | | | |
| | One-legged | Maximum oscillation | | | | | | |
| Right foot | landing on a | Average speed of movement (mm/s) | | | | | | |
| | <i>y</i> 1 | X-mean (mm) | | | | | | |
| | | Y-mean (mm) | | | | | | |
| | | CMI | | | | | | |

The threshold for significant differences between performances is defined as: * p < 0.05, ** p < 0.01, *** p < 0.001.

| | Description | ı | Gender | n | Mean | SD | р | Cohen's d |
|-------------|--------------|------------------------|--------|----|-----------|----------|--------|-----------|
| | Ago | | F | 37 | 16.027 | 4.775 | | |
| | Age | | М | 25 | 17.240 | 3.270 | ns | |
| | Unight | | F | 37 | 160.730 | 8.568 | -0.001 | 1 47 |
| | Tielgin | | М | 25 | 174.080 | 10.571 | <0.001 | -1.4/ |
| | Waight | | F | 37 | 55.946 | 11.723 | -0.001 | 1 1 (|
| | weight | | М | 25 | 69.880 | 12.364 | <0.001 | -1.16 |
| | | * Ellipse Surface Area | F | 37 | 67,044.45 | 36,620.1 | 20 | |
| | | (mm ²) | М | 25 | 82,007.7 | 66,993.9 | 115 | |
| | | * Sway path length | F | 37 | 845.427 | 281.710 | ns | |
| | | (mm) | М | 25 | 943.225 | 333.231 | 115 | |
| | | * Maximum | F | 37 | 42.056 | 63.484 | 0.007 | 0.61 |
| Laftfaat | One-legged | oscillation | М | 25 | 99.247 | 125.736 | 0.007 | -0.01 |
| Left foot | forward jump | * Average speed of | F | 37 | 42.774 | 14.492 | ns | |
| | | movement (mm/s) | М | 25 | 47.860 | 17.984 | 115 | |
| | | * V moon | F | 37 | -31.809 | 13.256 | ne | |
| | | | М | 25 | -30.845 | 18.738 | 115 | |
| | | Y-mean | F | 37 | 9.493 | 14.314 | – ns | |
| | | | М | 25 | 16.026 | 19.085 | – ns | |
| | | * Ellipse Surface Area | F | 37 | 77,004.3 | 38,035.4 | ns | |
| | | (mm ²) | М | 25 | 85,871.6 | 48,083.5 | 115 | |
| | | * Sway path length | F | 37 | 923.166 | 349.061 | ns | |
| | | (mm) | М | 25 | 876.222 | 284.824 | 115 | |
| | | * Maximum | F | 37 | 95.330 | 152.405 | ne | |
| Right foot | One-legged | oscillation | М | 25 | 72.798 | 132.586 | 115 | |
| idgitt 1001 | forward jump | * Average speed of | F | 37 | 46.846 | 17.650 | ne | |
| | | movement (mm/s) | М | 25 | 45.978 | 18.437 | 115 | |
| | | Y moon | F | 37 | -29.909 | 11.828 | ns | |
| | | A-IIIedii | М | 25 | -28.670 | 12.373 | 115 | |
| | | Y-mean | F | 37 | 10.631 | 10.952 | ne | |
| | | | М | 25 | 12.533 | 16.041 | 115 | |

Table 6. Comparison of parameters between males and females using the independent samples *t*-test.

| Fellipse Surises Are (mm ²) F (37) (32,48,8) (36,00,43) h_{1} *Sway pathengin (mm) *Sway pathengin (mm) M 25 1007,96 24,493 h_{2} *Sway pathengin (mer) F 37 1090,288 24,493 h_{1} *Maximum (scillation) F 37 55,68 12193 h_{1} *Average speed of movement (mm/) M 25 52,162 16,778 21,913 *Average speed of movement (mm/) M 25 94,07 11,178 h_{1} *Average speed of movement (mm/) F 37 0.962,1044 32,125 h_{2} *Average speed of movement (mm/) M 25 94,67 11,178 h_{2} *Meran F 37 0.962,1044 32,242,685 h_{1} M 25 94,67 11,378 h_{2} h_{2} h_{2} Maximum swap F 37 0.962,1044 32,242,885 h_{2} h_{2} Range of motion (Rom) | | Description | n | Gender | n | Mean | SD | р | Cohen's d | | | | | | |
|--|-------------------|----------------|------------------------|--------|----|------------|------------|-------|-----------|---|----|-------|-------|-----|--|
| $ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \$ | | | * Ellipse Surface Area | F | 37 | 72,284.882 | 38,690.435 | 20 | | | | | | | |
| $ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \$ | | | (mm ²) | М | 25 | 74,317.066 | 32,100.34 | 115 | | | | | | | |
| $ \begin{tabular}{ c c c c c c c } & c c c c c c c c c c c c c c c c c c$ | | | * Sway path length | F | 37 | 1090.288 | 442.459 | | | | | | | | |
| $ \begin{tabular}{ c c c c c c } & $$ $$ $$ $$ $$ $$ $$ $$ $$ $$ $$ $$ $$ | | | (mm) | М | 25 | 1007.506 | 284.450 | 115 | | | | | | | |
| One-legged ladening on alternal jumposcillation (mm/) MM2575708120.193ININ*Average speed of movement (mm/) MF3755.65825.46NSNS*X-meanF373.272825.125NSNS*Y-meanM25-55.67914.173NSM259.46714.173NSM259.46714.173NSM259.46714.173NSM259.46714.173NSM259.46714.173NSM259.46731.330.0270.58Sign path length indergenF37101.488144.399NSMaching are alateral jump*Maximum swing movement (mm/s)F37101.488144.399*Maximum swing indergen d indergen dF3720.566175.341NS*Marge speed of movement (mm/s)F377.660175.341NS*Average speed of movement (mm/s)F377.6609.082NS*Average speed of movement (mm/s)F377.6609.082NS*Average speed of movement (mm/s)F377.6609.082NS*Average speed of (ROM')F377.6609.082NS | | | * Maximum | F | 37 | 76.547 | 110.790 | ne | | | | | | | |
| Idea of all of all of all of all of novement (mm/s) F 37 55658 23.406 na *Average speed of movement (mm/s) M 25 52.162 16.79 n *Xmean T 37 -0.228 52.162 16.79 n *Xmean T 37 -0.228 52.162 16.79 n *Ymean F 37 -0.569 17.210 ns - Ymean F 37 69.621.044 37.426.65 ns - Ymean F 37 69.621.044 37.426.65 ns - Sway path length F 37 101.488 144.37 0.027 0.38 Sway path length M 25 51.333 60.799 ns - ahdring on al landing on a | I aft fact | One-legged | oscillation | М | 25 | 75.708 | 120.193 | 115 | | | | | | | |
| Invorment (mm/s) M 25 52.162 16.778 ins *X-mean F 37 -32.728 25.125 ns *X-mean F 37 5.659 17.210 ns *Y-mean F 37 69.621.044 37.224.855 ns (mm ³) M 25 94.67 14.178 ns *(mm ³) M 25 94.67 14.178 ns *(mm ³) M 25 94.67 31.244 .0.07 .0.58 Sway path length (mm ³) M 25 51.333 0.789 .0.68 *Maximum swing F 37 101.488 144.439 .0.07 .0.58 *Average speed of movement (mn/s) M 25 51.333 0.0789 .0.68 *Average speed of movement (mn/s) M 25 72.2628 175.341 .0.27 *Average speed of movement (mn/s) M 25 72.633 10.088 .0.161 *Average speed of (MoV) M 25 10.980 25.371 .0.371 *Average speed of (KOM') M 25 43.860 9.922 .0.161 *Average speed of (KOM') M 25 43.800 <td< td=""><td>Left foot</td><td>lateral jump</td><td>* Average speed of</td><td>F</td><td>37</td><td>55.658</td><td>23.406</td><td>ne</td><td></td></td<> | Left foot | lateral jump | * Average speed of | F | 37 | 55.658 | 23.406 | ne | | | | | | | |
| F 37 -32.728 25.125 n N 25 -35.727 15957 n Y-mean N 25 9.467 14.178 n Y-mean N 25 9.467 14.178 n Y-mean N 25 9.467 14.178 n Version M 25 9.467 14.178 n Sway path lengh (mm) N 25 868.578 186.447 0.027 0.58 Sway path lengh (mm) F 37 101.488 144.399 n 1 *Maximum swing F 67 51.333 60.799 1 1 *Average speed of movement (mn/s) M 25 43.969 9.822 ns 1 *X-mean F 37 7.660 9.008 n 1 1 1 *Average speed of movement (mn/s) M 25 10.980 21.543 n 1 1 1 1 | | | movement (mm/s) | М | 25 | 52.162 | 16.778 | 115 | | | | | | | |
| $ \begin{array}{ c c c c c c c } \label{eq:harmonic} \begin{tabular}{ c c c c } \hline \begin{tabular}{ c c c c } \hline \begin{tabular}{ c c c c c c c } \hline \begin{tabular}{ c c c c c c } \hline \begin{tabular}{ c c c c c c c } \hline \begin{tabular}{ c c c c c c c } \hline \begin{tabular}{ c c c c c c c } \hline \begin{tabular}{ c c c c c c c c c c c } \hline \begin{tabular}{ c c c c c c c c c c c c c c c c c c c$ | | | * V maan | F | 37 | -32.728 | 25.125 | ns | | | | | | | |
| Y_{mean} F 37 5.659 17.210 ns M 259.467 $14.17s$ ns mm^2 mm^2 $69.621.044$ $37.242.685$ ns mm^2 mm^2 mm^2 $69.621.044$ $37.242.685$ ns mm^2 mm^2 mm^2 $69.621.044$ $37.242.685$ ns mm^2 mm^2 mm^2 1034.607 31.264 0.027 0.38 mm^2 mm^2 101.488 144.359 $notenotemm^2mm^2101.488144.359notenotemm^2mm^2101.488144.359notenotemm^2mm^2101.488144.359notenotemm^2mm^2101.488144.359notenotemm^2mm^210.488144.359notenotemm^2mm^210.488144.359notenotemm^2mm^210.58011.570notenotemm^2mm^210.89021.543notenotemm^2mm^210.89021.543notenotemm^2mm^210.89021.54310.98021.543notemm^2mm^210.89010.89010.21note10.89010.148mm^210.89010.89010.89010.89010.89010.99010000$ | | | A-mean | М | 25 | -35.727 | 15.995 | 115 | | | | | | | |
| $ \begin{array}{ c c c c c c c } \label{eq:heads} \begin{tabular}{ c c c c c } \label{eq:heads} \end{tabular} \\ \begin{tabular}{ c c c c c c c } \label{eq:heads} \end{tabular} \\ \end{tabuar} \\ \end{tabular} \\ tab$ | | | Vmaan | F | 37 | 5.659 | 17.210 | ne | | | | | | | |
| Fight foot Filips Surface Area (nm ²) Filips Surface | | | 1-inean | М | 25 | 9.467 | 14.178 | 115 | | | | | | | |
| $ \begin{array}{ c c c c c c } & c c c c c c c } & c c c c c c c c c c c c c c c c c c$ | | | * Ellipse Surface Area | F | 37 | 69,621.044 | 37,242.685 | ne | | | | | | | |
| Swap path length (mm) F 37 1034.607 331.264 0.027 0.58 Right foot *Maximum swing lateral jum) F 37 101.488 144.359 ns *Maximum swing lateral jum, interpreter F 37 101.488 144.359 ns | | | (mm ²) | М | 25 | 79,571.328 | 77,463.133 | 115 | | | | | | | |
| $ \begin{array}{ c c c c c c } \label{eq:response} \begin{split} & & & & & & & & & &$ | | | Sway path length | F | 37 | 1034.607 | 331.264 | 0.027 | 0 59 | | | | | | |
| Right foot*Maximum swing lateral jumpF37101.488144.359 144.359ns*Marinum swing lateral jumpM2551.33360.789model*Average speed of morement (mm/s)F3752.63617.541 Mns*X-meanF37-27.62817.750 27.710ns*X-meanF377.6609.008 9.008ns*Y-meanF377.6609.008 9.008ns*Y-meanF3744.83834.791 9.012ns*Angular speed (°/s) (ROM')F3744.83834.791 9.012ns*Angular speed (°/s) (ROM')F370.860.156 0.156ns*Huency IndexF370.860.156 0.161ns*Huency IndexF3746.70336.325 9.012ns*Huency IndexF3746.70336.325ns*Huency IndexF3746.70336.325ns*Huency IndexF370.830.112ns*Huency IndexF370.830.142ns*Huency IndexF370.830.142ns*Huency IndexF370.830.142ns*Huency IndexF370.830.142ns*Huency IndexF370.860.141ns*Huency IndexF370.820.145ns*Huen | | | (mm) | М | 25 | 868.578 | 186.447 | 0.027 | 0.58 | | | | | | |
| $ \begin{array}{ c c c c c c } \mbox{Normal strains} & M & 25 & 51.333 & 60.789 & 10 & 10 & 10 & 10 & 10 & 10 & 10 & 1$ | | | * Maximum swing | F | 37 | 101.488 | 144.359 | ne | | | | | | | |
| $\begin{split} \begin root & \begin root $ | Right foot | One-legged | Maximum swing | М | 25 | 51.333 | 60.789 | 115 | | | | | | | |
| $ \begin{array}{ c c c c c c } \label{eq:harmon} & M & 25 & 43.969 & 9.822 & M & M & M & M & M & M & M & M & M &$ | Aight foot | lateral jump | * Average speed of | F | 37 | 52.636 | 175.341 | ne | | | | | | | |
| $ \frac{\begin{tabular}{ c c c c } & F & 37 & -27.628 & 17.70 & $$$$$$$$$$$$$$$$$$$$$$$$$$$$$$$$$$$$ | | | movement (mm/s) | М | 25 | 43.969 | 9.822 | 115 | | | | | | | |
| $\begin{array}{ c c c c c c } \label{eq:harmonic} \begin{tabular}{ c c c c } \label{eq:harmonic} \end{tabular} \\ & & & & & & & & & & & & & & & & & & $ | | | * V mean | F | 37 | -27.628 | 17.750 | ne | | | | | | | |
| $ \begin{array}{ c c c c c c } & F & 37 & 7.60 & 9.08 & & & & & & & & & & & & & & & & & & &$ | | | X-inean | М | 25 | -29.159 | 27.710 | 115 | | | | | | | |
| $\frac{1}{10000000000000000000000000000000000$ | | | * Y-mean | F | 37 | 7.660 | 9.008 | - ns | | | | | | | |
| $\begin{array}{c c c c c c c c c c c } \mbox{Hermitian Provided (°/s) } & F & 37 & 44.88 & 34.791 \\ \hline M & 25 & 42.800 & 23.272 \\ \hline M & 25 & 42.800 & 23.272 \\ \hline Range of motion (ROM°) & M & 25 & 30.896 & 6.269 \\ \hline & & & & & & & & & & & & & & & & & &$ | | | 1-1110411 | М | 25 | 10.980 | 21.543 | 115 | | | | | | | |
| $ \begin{array}{c c c c c c c c c c c c c c c c c c c $ | | | * Angular speed (° /s) | F | 37 | 44.838 | 34.791 | ne | | | | | | | |
| $ \begin{array}{c c c c c c c c c c c c c c c c c c c $ | | | | М | 25 | 42.800 | 23.272 | 115 | | | | | | | |
| $ \begin{array}{ c c c c c c c c } \mbox{Leff foot} & Le$ | I oft foot | Domiflavion | Range of motion | F | 37 | 29.754 | 5.913 | ns | | | | | | | |
| $\frac{F}{Fluency Index} = \frac{F}{M} = \frac{37}{0.86} + \frac{0.156}{0.156} + \frac{1}{M} = \frac{1}{100} + $ | Left foot | Dorsinexion | (ROM°) | М | 25 | 30.896 | 6.269 | 115 | | | | | | | |
| $\frac{1}{10000000000000000000000000000000000$ | | | * Fluency Index | F | 37 | 0.86 | 0.156 | ns | | | | | | | |
| $ \begin{array}{c c c c c c c c c c c c c c c c c c c $ | | | Theney maex | М | 25 | 0.88 | 0.116 | 115 | | | | | | | |
| $ \begin{array}{c c c c c c c c c c c c c c c c c c c $ | | | * Angular speed (°/s) | F | 37 | 46.703 | 36.325 | ne | | | | | | | |
| $ \begin{array}{c c c c c c c c c c c c c c c c c c c $ | | | Aliguiai specu (73) | М | 25 | 47.520 | 45.710 | 115 | | | | | | | |
| $\frac{(\text{ROM}^{\circ})}{\text{Fluency Index}} = \frac{M}{M} = \frac{25}{46.088} + \frac{11.211}{1.211} = \frac{113}{1.211} = \frac{113}{1.21$ | I oft foot | Plantarflovion | Range of motion | F | 37 | 44.935 | 9.012 | ne | | | | | | | |
| $\frac{F}{M} = \frac{F}{M} = \frac{F}$ | Left loot | Tantamexion | (ROM°) | М | 25 | 46.088 | 11.211 | 115 | | | | | | | |
| $\frac{M}{M} = \frac{25}{0.82} = 0.145$ $\frac{M}{M} = \frac{25}{0.82} = \frac{0.145}{0.145}$ $\frac{M}{M} = \frac{25}{0.82} = \frac{0.145}{0.1255}$ $\frac{M}{M} = \frac{25}{0.82} = \frac{0.145}{0.1255}$ $\frac{M}{M} = \frac{25}{0.82} = \frac{0.145}{0.826}$ $\frac{M}{M} = \frac{25}{0.82} = \frac{0.145}{0.826}$ $\frac{M}{M} = \frac{0.145}{0.825} = \frac{0.145}{0.826}$ $\frac{M}{M} = \frac{0.145}{0.826} = \frac{0.141}{0.141}$ $\frac{M}{M} = \frac{0.145}{0.141} = \frac{0.145}{0.141}$ | | | * Fluency Index | F | 37 | 0.83 | 0.142 | ns | | | | | | | |
| $ \begin{array}{c c c c c c c c c c c c c c c c c c c $ | | | Theney much | М | 25 | 0.82 | 0.145 | 10 | | | | | | | |
| Left foot Eversion M 25 40.040 21.255 Range of motion (ROM°) F 37 32.205 9.936 M 25 32.824 7.925 * Fluency Index F 37 0.866 0.141 M 25 0.858 0.134 | Loft foot Eversio | | Angular speed (°/s) | F | 37 | 47.730 | 25.941 | ne | | | | | | | |
| $ \begin{array}{c c c c c c c c c c c c c c c c c c c $ | | | | М | 25 | 40.040 | 21.255 | 115 | | | | | | | |
| (ROM°) M 25 32.824 7.925 * Fluency Index F 37 0.866 0.141 M 25 0.858 0.134 ns | | Eversion | Range of motion | F | 37 | 32.205 | 9.936 | ne | | | | | | | |
| * Fluency Index F 37 0.866 0.141 ns | Lett 1001 | LICISION | (ROM°) | М | 25 | 32.824 | 7.925 | 10 | | | | | | | |
| M 25 0.858 0.134 | | | * Fluency Index | F | 37 | 0.866 | 0.141 | ns | | | | | | | |
| | | | | | | | | | | М | 25 | 0.858 | 0.134 | 113 | |

Table 6. Cont.

| | Descriptio | n | Gender | n | Mean | SD | p | Cohen's d |
|----------------------|----------------|------------------------|--------|--------|--------|--------|---------|-----------|
| | | * Angular speed (° /s) | F | 37 | 54.757 | 22.869 | ns | |
| | | Aliguiai speed (75) | М | 25 | 47.920 | 19.455 | - 115 | |
| T - (L (L | Invention | Range of motion | F | 37 | 37.970 | 8.495 | ns | |
| Left foot | Inversion | (ROM°) | М | 25 | 39.092 | 11.572 | - 115 | |
| | | * Eluonav Indov | F | 37 | 0.907 | 0.098 | 20 | |
| | | Fidency fidex | М | 24 | 0.838 | 0.206 | - 115 | |
| | | * Angular speed (° /s) | F | 37 | 45.973 | 27.046 | 20 | |
| | | Aliguiai speed (75) | М | 25 | 45.640 | 20.512 | - 115 | |
| Right foot | Danaidanian | Range of motion | F | 37 | 29.827 | 6.193 | ns | |
| Right foot | Dorsinexion | (ROM°) | М | 25 | 31.520 | 6.754 | - 115 | |
| | | * Eluonav Indov | F | 37 | 0.860 | 0.120 | ns | |
| | | Fidency fidex | М | 25 | 0.917 | 0.107 | - 115 | |
| | | * Angular speed (° /s) | F | 37 | 50.351 | 25.588 | 20 | |
| | | Aliguiai speed (75) | М | 25 | 41.840 | 20.134 | - 115 | |
| Right foot | Discharding | Range of motion | F | 37 | 43.543 | 8.861 | 20 | |
| | Plantarflexion | (ROM°) | М | 25 | 42.776 | 9.620 | - 115 | |
| | | * Fluency Index | F | 37 | 0.843 | 0.116 | – ns | |
| | | | М | 25 | 0.824 | 0.101 | - 115 | |
| | | * Angular speed (° /s) | F | 37 | 51.054 | 27.993 | ns | |
| | | Aliguiai speed (75) | М | 25 | 48.640 | 28.110 | - 115 | |
| Right foot | Exercice | Range of motion | F | 37 | 33.030 | 8.463 | ns | |
| Right foot | Eversion | (ROM°) | М | 25 | 34.380 | 12.373 | - 115 | |
| | | * Eluonav Indov | F | 37 | 0.879 | 0.183 | ns | |
| | | Theney maex | М | 25 | 0.863 | 0.125 | - 115 | |
| | | * Angular speed (° /s) | F | 37 | 53 | 25.970 | 20 | |
| | | Aliguiai speed (75) | М | 25 | 48 | 22.856 | - 115 | |
| Right foot | T | Range of motion | F | 37 | 37.924 | 8.3194 | ns | |
| Right foot Inversion | Inversion | (ROM°) | М | 25 | 42.056 | 13.204 | - 115 | |
| | | * Eluonav Indov | F | 37 | 0.869 | 0.176 | ns | |
| | | М | 25 | 0.901 | 0.105 | - 115 | | |
| CMI | | F | 37 | 18.735 | 4.805 | 0.001 | 0.80 | |
| | CMJ | | | 25 | 23.324 | 5.609 | - 0.001 | -0.07 |

Table 6. Cont.

*: U of Mann-Whitney analysis; ns: not significant, SD: Standard deviation.

Furthermore, the multiple linear regression showed a significant regression with the dependent variable vertical jump height (cm) and the independent variables' Right Dorsiflexion Range of Mov. °, foot size, right sway path length, right average speed of movement, and Right Plantarflexion Range of Mov.° (regression *p*-value < 0.001; adjusted R² = 0.078; Table 7). A similar tendency was found on the left foot with a significant regression with the dependent variable vertical jump height (Cm) and the independent variable: foot size, left sway path length, left average speed of movement, and Left Plantarflexion Range of Mov.° (regression *p*-value < 0.001; adjusted R² = 0.33 (Table 8)). In addition, we analyzed the differences between the subjects who claimed to be with the right dominant foot (55 subjects) vs. left dominant foot (7 subjects), but no significant differences in dominant foot interaction were present. The specific task volley test showed significant differences between the left ellipse surface area after a forward jump vs. the left ellipse surface area after a lateral jump (884.86 ± 304.7 mm² vs. 1056.91 ± 386.1 mm²; *p* < 0.001); between the left

average speed of movement after a forward jump vs. the left average speed of movement after a lateral jump (44.82 \pm 16 mm/s vs. 54.25 \pm 20.9 mm/s; *p* < 0.001); and between the left y-mean after a forward jump vs. left y-mean after a lateral jump (12.13 \pm 16.6 mm vs. 7.19 \pm 16; *p* < 0.05). The test did not show significant differences on the right foot (Table 9).

Table 7. Multiple linear regression (dependent variable: Performance CMJ (Cm); independent variable: Right Dorsiflexion Range of Mov.°, foot size, right sway path length, right average speed of movement, and Right Plantarflexion Range of Mov.°). Regression *p*-value < 0.001; Adjusted $R^2 = 0.78$.

| Multiple Linear Regression—CMJ (cm) | | | | | | | |
|---|----------|-------|--------|---------|--|--|--|
| Predictor | Estimate | SE | t | р | | | |
| Intercept | -24.694 | 6.143 | -4.019 | < 0.001 | | | |
| Right Dorsiflexion Range of Mov. $^\circ$ | 0.674 | 0.057 | 11.672 | < 0.001 | | | |
| Foot size | 0.605 | 0.127 | 4.767 | < 0.001 | | | |
| Right sway path length (mm) | 0.017 | 0.006 | 2.890 | 0.005 | | | |
| Right average speed of movement (mm/s) | -0.322 | 0.107 | -3.018 | 0.004 | | | |
| Right Plantarflexion Range of Mov.° | -0.006 | 0.041 | -0.145 | 0.885 | | | |

Table 8. Multiple linear regression (dependent variable: Performance CMJ (Cm); independent variable: Left Dorsiflexion Range of Mov.°, foot size, left sway path length, left average speed of movement and Left Plantarflexion Range of Mov.°). Regression *p*-value < 0.001; Adjusted $R^2 = 0.33$.

| Multiple Linear Regression—CMJ (cm) | | | | | | |
|--|----------|-------|--------|---------|--|--|
| Predictor | Estimate | SE | t | p | | |
| Intercept | -16.919 | 9.644 | -1.754 | 0.085 | | |
| Left Dorsiflexion Range of Mov. $^\circ$ | 0.489 | 0.108 | 4.545 | < 0.001 | | |
| Foot size | 0.634 | 0.211 | 3.007 | 0.004 | | |
| Left sway path length (mm) | 0.002 | 0.017 | 0.102 | 0.919 | | |
| Left average speed of movement (mm/s) | -0.066 | 0.327 | -0.200 | 0.842 | | |
| Left Plantarflexion Range of Mov.° | -0.031 | 0.065 | -0.471 | 0.639 | | |

Table 9. Pair *t*-test between landing after a forward jump right vs. left and on a lateral jump (l).

| | Measurements | | p |
|---|--------------|---|---------|
| Left ellipse surface area (mm ²) | vs. | Right ellipse surface area (mm ²) | 0.147 |
| Left sway path length (mm) | vs. | Right sway path length (mm) | 0.603 |
| Left maximum oscillation | vs. | Right maximum swing | 0.363 |
| Left x-mean | vs. | Right x-mean | 0.305 |
| Left y-mean | vs. | Right y-mean | 0.655 |
| Left ellipse surface area (mm ²) | vs. | (l)—Left ellipse surface area (mm ²) | 0.997 |
| Left sway path length (mm) | vs. | (l)—Left sway path length (mm) | < 0.001 |
| Left maximum oscillation | vs. | (l)—Left maximum oscillation | 0.589 |
| Left average speed of movement (mm/s) | vs. | (l)—Left average speed of movement (mm/s) | <0.001 |
| Left x-mean | vs. | (l)—Left x-mean | 0.420 |
| Left y-mean | vs. | (l)—Left y-mean | 0.014 |
| Right ellipse surface area (mm ²) | vs. | (l)—Right ellipse surface area (mm ²) | 0.313 |
| Right sway path length (mm) | vs. | (l)—Right sway path length (mm) | 0.154 |
| Right maximum swing | vs. | (l)—Right maximum oscillation | 0.839 |
| Right average speed of movement (mm/s) | vs. | (l)—Right average speed of movement (mm/s) | 0.288 |
| Right x-mean | vs. | (l)—Right x-mean | 0.671 |
| Right y-mean | vs. | (l)—Right y-mean | 0.146 |

4. Discussion

This study aimed to identify predictive indicators of future instability using a specific task-test jump. Correlations between ankle range of motion (ROM) and the specific jump-landing task (SJLT) yielded interesting findings. Dorsiflexion parameters were particularly significant in predicting chronic ankle instability [36]. In line with the results of Donovan et al., a reduced range of motion correlates with decreased strength, impaired neuromuscular control, and altered functional movement patterns [36].

Our results showed that the Dorsiflexion Fluency Index of the right foot, which is an index ranging from 0 to 1 and which indicates the movement quality of the ankle, significant inverse correlation with stability parameters of the foot after a one-legged landing on a forward jump. Stability is represented by the size of the ellipse surface area [37]. In addition, this parameter showed a significative positive correlation with the x-mean parameter after a one-legged landing after a forward jump and on a lateral jump both on the right foot and left foot. The x-mean parameter represented the coordinates of the CoP along the frontal planes [38]. These findings are along the same lines as the conclusions showed by Brown et al. [39]. The authors demonstrated that the mechanically unstable subjects displayed differences in frontal plane ankle motion [39]. In 2023, Han et al. provided insights into ankle dorsiflexion ranges, distinguishing between Hypo-DFROM (below 40 degrees), Normal-DFROM, and Hyper-DFROM [40]. Our results described a mean of ROM° below 40 degrees in the whole sample analyzed. None of the subjects enrolled in the study reported chronic ankle problems; this indicates the importance of regular and ongoing assessments of the ankle in athletes to prevent latent ankle impairments and future injuries. Furthermore, the data showed by Han et al. confirm our conclusions on how limited dorsiflexion negatively affects the landing/cutting task [40].

Regarding limb dominance, our study found no significant differences, though leftfoot dominant subjects were underrepresented and warrant further investigation. However, significant differences were observed in performance after the specific jump-landing task, particularly in the left limb. After lateral jumps, the left foot showed a significantly greater sway path length, average speed of movement, and lower y-mean, indicating greater difficulty in stabilization compared to the right foot. Our results seem to indicate that the left foot is more difficult to stabilize on a one-legged landing task after a lateral jump than the right foot. These results are in line with the conclusions of the study by Simpson, J.D. et al. (2018) [17]. The authors demonstrated that individuals with chronic ankle instability showed dynamic postural stability deficits and reduced neuromuscular control during unilateral jump-landings [17].

Our results also highlighted reduced ankle sagittal plane displacement after lateral jumps compared to forward jumps (Table 9), a strategy observed in subjects with chronic ankle instability to reduce impact forces on the ankle complex [39,41]. As suggested by the literature, the reduction in ankle sagittal plane range is an ankle strategy during the post-landing period that decreases impact forces imposed on the ankle complex, but a greater reliance is transmitted to the proximal segments [42,43]. Furthermore, our data analysis demonstrated a significant correlation between dorsiflexion ROM and performance on the counter-movement jump (CMJ) test, particularly with the right leg (Table 2). In 2021, Panoutsakopoulos V. et al. found similar results, the authors hypothesized that individuals with a larger ankle dorsiflexion angle can more efficiently utilize the additional work provided by the arm swing in the vertical squat jump compared to individuals with a less flexible ankle joint [44].

Multiple linear regression analysis further confirmed dorsiflexion as a predictor of vertical jump height, with significant associations observed for variables such as right sway path length and average speed of movement (Table 7). Similar trends were observed for the left leg but to a lesser extent (Table 8).

The study is not without limitations. Some subjects were slightly older than eighteen, which may have introduced greater heterogeneity to the sample; the BEYOND Inertial has demonstrated reliability, and similar instruments of lower technical specifications

have undergone extensive validation [25]. However, while its previous version is welldocumented in the literature [45,46], the validation of the current version is still in progress. Moreover, the sample analyzed specifically consisted of students who played volleyball on an amatorial level. Nevertheless, we were unable to evaluate the impact of prior years of playing experience on the individuals. Insufficient control over the prior experience of each participant may have resulted in a certain level of variability in the findings. Thus, it is recommended that future studies give priority to selecting a more homogeneous sample with similar levels of experience in physical exercise to reduce the impact of this factor. To validate the reliability of the findings, it would be beneficial to expand the parameters for selecting participants or include a mandatory minimum number of years of expertise as a controlled factor.

5. Conclusions

This study is the first to propose a jump-landing task that tries to simulate real sports movement to be customized for specific anthropometric characteristics and performance. This may show altered adaptation strategies during a landing/cutting activity like in the play actions. Dorsiflexion ROM has a very high influence on jumping performance, and exercises to improve ankle joint mobility are essential not only to prevent injuries but also for the performance itself. Future studies should investigate the connections between lower limb movement patterns, neuromuscular control, and joint kinematics to gain a better understanding of the causes of recurring lateral ankle sprains in populations that frequently engage in repetitive jump-landings. These studies are particularly important in amateur and student settings, where injury rates are higher, and could help reduce post-injury dropout from physical activity.

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