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Quasilinear Dirichlet Problems with Degenerated p -Laplacian and Convection Term

Dumitru Motreanu ^{1,*}  and Elisabetta Tornatore ²¹ Department of Mathematics, University of Perpignan, 66860 Perpignan, France² Department of Mathematics and Computer Science, University of Palermo, 90123 Palermo, Italy; elisa.tornatore@unipa.it

* Correspondence: motreanu@univ-perp.fr

Abstract: The paper develops a sub-supersolution approach for quasilinear elliptic equations driven by degenerated p -Laplacian and containing a convection term. The presence of the degenerated operator forces a substantial change to the functional setting of previous works. The existence and location of solutions through a sub-supersolution is established. The abstract result is applied to find nontrivial, nonnegative and bounded solutions.

Keywords: quasilinear elliptic problem; degenerated p -Laplacian; convection term; sub-supersolution; nonnegative solution

1. Introduction

In this paper, we study the following quasilinear elliptic problem

$$\begin{cases} -\operatorname{div}(a(x)|\nabla u|^{p-2}\nabla u) = f(x, u, \nabla u) & \text{in } \Omega \\ u = 0 & \text{on } \partial\Omega \end{cases} \quad (P)$$

on a bounded domain $\Omega \subset \mathbb{R}^N$ with $N \geq 2$ and $p \in (1, N)$. We assume that the boundary $\partial\Omega$ of Ω is locally Lipschitzian, i.e., each point of $\partial\Omega$ has a neighborhood whose intersection with $\partial\Omega$ is the graph of a Lipschitz continuous function. Throughout the text we denote by $|\cdot|$ and \cdot the standard Euclidean norm and scalar product on \mathbb{R}^N , respectively. A main feature of the present work is that the leading part of the equation in (P) is the differential operator in divergence form $\operatorname{div}(a(x)|\nabla u|^{p-2}\nabla u)$ known as the degenerated p -Laplacian with the weight $a \in L^1_{\text{loc}}(\Omega)$. It is supposed that the function a be positive almost everywhere in Ω and that the following condition holds

$$a^{-s} \in L^1(\Omega) \text{ for some } s \in \left(\frac{N}{p}, +\infty\right) \cap \left[\frac{1}{p-1}, +\infty\right). \quad (1)$$

In the case where $a(x) \equiv 1$ we recover the ordinary p -Laplacian. Various examples of useful weights meeting the requirement (1) are given in [1]. For instance, it is obvious that defining $a(x) = \operatorname{dist}(x, S)$ for $x \in \Omega$, with a nonempty closed subset S of $\partial\Omega$, one obtains a function a on Ω for which (1) holds true with any listed s .

The natural space associated with problem (P) is $W_0^{1,p}(a, \Omega)$ that is the closure of $C_0^\infty(\Omega)$ in the weighted Sobolev space $W^{1,p}(a, \Omega)$. In Section 2 we briefly survey the spaces $W^{1,p}(a, \Omega)$ and $W_0^{1,p}(a, \Omega)$. The (negative) degenerated p -Laplacian with the weight $a \in L^1_{\text{loc}}(\Omega)$ under condition (1) is defined on $W_0^{1,p}(a, \Omega)$ and takes values in the dual space $(W_0^{1,p}(a, \Omega))^*$.



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Corresponding to the constant s in (1) we set

$$p_s = \frac{ps}{s+1}$$

and the Sobolev critical exponent $p_s^* = \frac{Np_s}{N-p_s}$ (we note that $1 \leq p_s < N$). There is a continuous embedding $W^{1,p}(a, \Omega) \hookrightarrow L^{p_s^*}(\Omega)$, so a continuous embedding $L^{(p_s^*)'}(\Omega) \hookrightarrow (W_0^{1,p}(a, \Omega))^*$, where $(p_s^*)'$ stands for the Hölder conjugate of p_s^* , i.e., $(p_s^*)' = \frac{p_s^*}{p_s^*-1}$. In order to handle problem (P) the idea is to arrange that the right-hand side $f(x, u, \nabla u)$ become an element of $L^{(p_s^*)'}(\Omega)$, which basically will be achieved through an adequate growth condition (see assumption (H)). We emphasize that the nonlinearity $f(x, u, \nabla u)$ depends on the solution u and on its gradient ∇u , which generally makes the variational methods be ineffective. Such a term $f(x, u, \nabla u)$ is often called convection. It is expressed by means of a function $f : \Omega \times \mathbb{R} \times \mathbb{R}^N \rightarrow \mathbb{R}$ that is Carathéodory, i.e., $f(\cdot, t, \xi)$ is measurable for every $(t, \xi) \in \mathbb{R} \times \mathbb{R}^N$ and $f(x, \cdot, \cdot)$ is continuous for a.e. $x \in \Omega$.

The goal of our work is to build a systematical approach to problem (P) via the method of sub-supersolution. It is for the first time when the method of sub-supersolution is implemented for problem (P) involving the degenerated p -Laplacian and related convection. In this respect, the functional setting is adapted to the novel situation of degenerated operators relying in an essential way on the associated exponent p_s . For results on the method of sub-supersolution applied to problems exhibiting convection terms but not driven by degenerated differential operators we refer to [2–6].

By a (weak) solution to problem (P) we mean a function $u \in W_0^{1,p}(a, \Omega)$ such that $f(x, u, \nabla u) \in L^{(p_s^*)'}(\Omega)$ and

$$\int_{\Omega} a(x)|\nabla u(x)|^{p-2}\nabla u(x) \cdot \nabla v(x)dx = \int_{\Omega} f(x, u(x), \nabla u(x))v(x)dx, \quad \forall v \in W_0^{1,p}(a, \Omega). \quad (2)$$

A function $\underline{u} \in W^{1,p}(a, \Omega)$ is called a subsolution for problem (P) if $\underline{u} \leq 0$ on $\partial\Omega$ (in the sense of traces), $f(\cdot, \underline{u}(\cdot), \nabla \underline{u}(\cdot)) \in L^{(p_s^*)'}(\Omega)$ and

$$\int_{\Omega} a(x)|\nabla \underline{u}(x)|^{p-2}\nabla \underline{u}(x) \cdot \nabla v(x)dx \leq \int_{\Omega} f(x, \underline{u}(x), \nabla \underline{u}(x))v(x)dx \quad (3)$$

for all $v \in W_0^{1,p}(a, \Omega)$, $v \geq 0$ a.e. in Ω . Symmetrically, a function $\bar{u} \in W^{1,p}(a, \Omega)$ is called a supersolution for problem (P) if $\bar{u} \geq 0$ on $\partial\Omega$ (in the sense of traces), $f(\cdot, \bar{u}(\cdot), \nabla \bar{u}(\cdot)) \in L^{(p_s^*)'}(\Omega)$ and

$$\int_{\Omega} a(x)|\nabla \bar{u}(x)|^{p-2}\nabla \bar{u}(x) \cdot \nabla v(x)dx \geq \int_{\Omega} f(x, \bar{u}(x), \nabla \bar{u}(x))v(x)dx \quad (4)$$

for all $v \in W_0^{1,p}(a, \Omega)$, $v \geq 0$ a.e. in Ω . Corresponding to a subsolution \underline{u} and a supersolution \bar{u} with $\underline{u} \leq \bar{u}$ a.e. in Ω we can consider the ordered interval

$$[\underline{u}, \bar{u}] = \{w \in W^{1,p}(a, \Omega) : \underline{u} \leq w \leq \bar{u}\}.$$

The following hypothesis for $f(x, s, \xi)$ is adapted to an ordered sub-supersolution $\underline{u} \leq \bar{u}$.

Hypothesis 1. Given an ordered sub-supersolution $\underline{u} \leq \bar{u}$ for problem (P), the Carathéodory function $f : \Omega \times \mathbb{R} \times \mathbb{R}^N \rightarrow \mathbb{R}$ satisfies the growth condition

$$|f(x, t, \xi)| \leq \sigma(x) + b|\xi|^r \quad \text{for a.e. } x \in \Omega, \text{ for all } t \in [\underline{u}(x), \bar{u}(x)], \quad \xi \in \mathbb{R}^N,$$

with a function $\sigma \in L^{\frac{ps}{r}}(\Omega)$ and constants $b > 0$ and $r \in (0, \frac{ps}{(p_s^*)'})$.

According to Hypothesis 1 we have

$$f(x, u, \nabla u) \in L^{(p_s^*)'}(\Omega), \forall u \in [\underline{u}, \bar{u}],$$

thus the integrals in the definitions above exist since

$$f(x, u, \nabla u)v \in L^1(\Omega), \forall u \in [\underline{u}, \bar{u}], v \in W_0^{1,p}(a, \Omega).$$

Under Hypothesis 1, our main result establishes the existence of a weak solution to problem (P) with the additional location property $u \in [\underline{u}, \bar{u}]$. We stress that this location property represents a significant qualitative information for the solution giving actually a priori estimates for it. As an application we prove the existence of a nontrivial nonnegative solution for a class of problems of type (P). The applicability of the stated result is demonstrated by an example.

2. Preliminary Material

The notation $|\Omega|$ stands for the Lebesgue measure of the bounded domain Ω in \mathbb{R}^N . In this section we discuss a few facts about the degenerated p -Laplacian entering problem (P). More details can be found in [1].

We note that (1) implies

$$a^{-\frac{1}{p-1}} \in L^1(\Omega).$$

Indeed, it is seen that

$$\begin{aligned} \int_{\Omega} a(x)^{-\frac{1}{p-1}} dx &= \int_{\{a(x)<1\}} a(x)^{-\frac{1}{p-1}} dx + \int_{\{a(x)\geq 1\}} a(x)^{-\frac{1}{p-1}} dx \\ &\leq \int_{\{a(x)<1\}} a(x)^{-s} dx + |\Omega| < \infty \end{aligned}$$

since according to (1) one has $s \geq \frac{1}{p-1}$ and $a^{-s} \in L^1(\Omega)$.

The weighted Sobolev space $W^{1,p}(a, \Omega)$ consists of all the functions $u \in L^p(\Omega)$ for which $a^{\frac{1}{p}}|\nabla u| \in L^p(\Omega)$. It is endowed with the norm

$$\|u\|_{1,p,a} = \left(\int_{\Omega} |u|^p dx + \int_{\Omega} a(x)|\nabla u|^p dx \right)^{\frac{1}{p}}$$

becoming a uniformly convex Banach space (due to the preceding property of the weight $a(x)$, see ([1], [Theorem 1.3])), thus reflexive, that contains $C_0^\infty(\Omega)$. The space $W_0^{1,p}(a, \Omega)$ is the closure of $C_0^\infty(\Omega)$ with respect to the norm $\|\cdot\|_{1,p,a}$.

There is an extensive literature devoted to the weighted Sobolev spaces including embeddings and traces related to different boundary value problems (see, e.g., [1,7,8]). The results depend strongly on what type of weight is used, generally attempting reduction to nonweighted spaces. As described below, under assumption (1), we can embed the space $W^{1,p}(a, \Omega)$ into the ordinary Sobolev space $W^{1,p_s}(\Omega)$, hence automatically having the trace (note the boundary $\partial\Omega$ is Lipschitz). This fact is needed in the definition of the sub-supersolution.

From (1) it is known that $s \geq \frac{1}{p-1}$, so one has $p_s \geq 1$ and the continuous embedding

$$W^{1,p}(a, \Omega) \hookrightarrow W^{1,p_s}(\Omega), \tag{5}$$

which is relation (1.22) in [1]. More precisely, observing that $p > p_s$, through Holder's inequality and (1) we get

$$\int_{\Omega} |\nabla u|^{p_s} dx = \int_{\Omega} a^{-\frac{p_s}{p}} a^{\frac{p_s}{p}} |\nabla u|^{p_s} dx \leq \left(\int_{\Omega} a^{-s} dx \right)^{\frac{1}{s+1}} \left(\int_{\Omega} a |\nabla u|^p dx \right)^{\frac{p_s}{p}}$$

for all $u \in W^{1,p}(a, \Omega)$. As a consequence of the above inequality, we can endow $W_0^{1,p}(a, \Omega)$ with an equivalent norm

$$\|u\| = \left(\int_{\Omega} a(x) |\nabla u|^p dx \right)^{\frac{1}{p}}$$

for which it holds

$$\|u\|_{W_0^{1,p_s}(\Omega)} \leq \|a^{-s}\|_{L^1(\Omega)}^{\frac{1}{p_s}} \|u\|. \tag{6}$$

The Sobolev embedding theorem ensures the continuous embedding $W_0^{1,p_s}(\Omega) \hookrightarrow L^{p_s^*}(\Omega)$, with the critical exponent $p_s^* = \frac{N p_s}{N - p_s}$ (note that $1 \leq p_s < N$). Hence there exists a constant $T_0 > 0$ such that

$$\|u\|_{L^{p_s^*}(\Omega)} \leq T_0 \|u\|_{W_0^{1,p_s}(\Omega)}, \forall u \in W_0^{1,p_s}(\Omega). \tag{7}$$

The best embedding constant T_0 has been estimated by Talenti [9] as follows

$$T_0 \leq \pi^{-\frac{1}{2}} N^{-\frac{1}{p_s}} \left(\frac{p_s - 1}{N - p_s} \right)^{1 - \frac{1}{p_s}} \left(\frac{\Gamma(1 + \frac{N}{2}) \Gamma(N)}{\Gamma(\frac{N}{p_s}) \Gamma(1 + N - \frac{N}{p_s})} \right)^{\frac{1}{N}},$$

where Γ is the Euler function

$$\Gamma(t) = \int_0^{+\infty} z^{t-1} e^{-z} dz, \forall t > 0.$$

Moreover, by the Rellich–Kondrachov compact embedding theorem, if $1 \leq r < p_s^*$ then the embedding $W_0^{1,p_s}(\Omega) \hookrightarrow L^r(\Omega)$ is compact.

By (7) and Hölder’s inequality we infer that

$$\|u\|_{L^r(\Omega)} \leq T_0 |\Omega|^{\frac{p_s^* - r}{p_s^*}} \|u\|_{W_0^{1,p_s}(\Omega)} \tag{8}$$

for every $u \in W_0^{1,p_s}(\Omega)$ and $r \in [1, p_s^*]$. Combining (6) and (8) we arrive at

$$\|u\|_{L^r(\Omega)} \leq \kappa_r \|u\| \tag{9}$$

for all $u \in W_0^{1,p}(a, \Omega)$ and $r \in [1, p_s^*]$, with the constant

$$\kappa_r = T_0 |\Omega|^{\frac{p_s^* - r}{p_s^*}} \|a^{-s}\|_{L^1(\Omega)}^{\frac{1}{p_s}}.$$

The (negative) degenerated p -Laplacian with the weight $a \in L^1_{loc}(\Omega)$ satisfying condition (1) is the operator $A : W_0^{1,p}(a, \Omega) \rightarrow (W_0^{1,p}(a, \Omega))^*$ defined by

$$\langle A(u), v \rangle = \int_{\Omega} a(x) |\nabla u|^{p-2} \nabla u \cdot \nabla v dx, \forall u, v \in W_0^{1,p}(a, \Omega). \tag{10}$$

We readily check that the operator A in (10) is well defined noticing by means of Hölder’s inequality that for all $u, v \in W_0^{1,p}(a, \Omega)$ it holds

$$\begin{aligned} \left| \int_{\Omega} a(x) |\nabla u|^{p-2} \nabla u \cdot \nabla v dx \right| &\leq \int_{\Omega} a(x)^{\frac{p-1}{p}} |\nabla u|^{p-1} a(x)^{\frac{1}{p}} |\nabla v| dx \\ &\leq \left(\int_{\Omega} a(x) |\nabla u|^p dx \right)^{\frac{p-1}{p}} \left(\int_{\Omega} a(x) |\nabla v|^p dx \right)^{\frac{1}{p}} < \infty. \end{aligned} \tag{11}$$

Important properties of the operator A introduced in (10) are listed in the statement below.

Proposition 1. Assume that the measurable function $a : \Omega \rightarrow \mathbb{R}$ satisfies condition (1). Then the (negative) degenerated p -Laplacian $A : W_0^{1,p}(a, \Omega) \rightarrow (W_0^{1,p}(a, \Omega))^*$ defined by (10) has the following properties:

- (i) A is a bounded operator in the sense that it maps bounded sets to bounded sets;
- (ii) A is a coercive operator, i.e.,

$$\lim_{\|u\| \rightarrow \infty} \frac{\langle Au, u \rangle}{\|u\|} = +\infty;$$

- (iii) A is a strictly monotone operator, i.e.,

$$\langle Au - Av, u - v \rangle > 0, \quad u \neq v;$$

- (iv) A has the S_+ property meaning that any sequence $\{u_n\} \subset W_0^{1,p}(a, \Omega)$ that satisfies $u_n \rightharpoonup u$ in $W_0^{1,p}(a, \Omega)$ and

$$\limsup_{n \rightarrow \infty} \langle A(u_n), u_n - u \rangle \leq 0 \tag{12}$$

is strongly convergent.

Proof. (i) From (10) and (11) we infer that

$$|\langle Au, v \rangle| = \left| \int_{\Omega} a(x) |\nabla u|^{p-2} \nabla u \cdot \nabla v dx \right| \leq \|u\|^{p-1} \|v\|, \quad \forall u, v \in W_0^{1,p}(a, \Omega).$$

We obtain

$$\|Au\|_{(W_0^{1,p}(a, \Omega))^*} = \sup_{v \in W_0^{1,p}(a, \Omega), \|v\| \leq 1} |\langle Au, v \rangle| \leq \|u\|^{p-1}, \quad \forall u \in W_0^{1,p}(a, \Omega),$$

whence A is bounded.

- (ii) By (10) we have that

$$\langle Au, u \rangle = \int_{\Omega} a(x) |\nabla u|^p dx = \|u\|^p, \quad \forall u \in W_0^{1,p}(a, \Omega).$$

Taking into account that $p > 1$, it follows that the operator A is coercive.

- (iii) In view of the strict monotonicity of the mapping $\zeta \mapsto |\zeta|^{p-2} \zeta$ on \mathbb{R}^N , it turns out

$$\langle Au - Av, u - v \rangle = \int_{\Omega} a(x) (|\nabla u|^{p-2} \nabla u - |\nabla v|^{p-2} \nabla v) \cdot (\nabla u - \nabla v) dx > 0, \quad u \neq v,$$

so A is a strictly monotone operator.

- (iv) Let a sequence $\{u_n\} \subset W_0^{1,p}(a, \Omega)$ satisfy $u_n \rightharpoonup u$ in $W_0^{1,p}(a, \Omega)$ and (12). Using the monotonicity of the operator A and (12) we have

$$\lim_{n \rightarrow \infty} \langle A(u_n) - A(u), u_n - u \rangle = 0.$$

Through Hölder’s inequality we obtain

$$\begin{aligned}
 & \langle A(u_n) - A(u), u_n - u \rangle = \int_{\Omega} a(x) (|\nabla u_n|^{p-2} \nabla u_n - |\nabla u|^{p-2} \nabla u) \cdot (\nabla u_n - \nabla u) dx \\
 = & \int_{\Omega} a(x) |\nabla u_n|^p dx - \int_{\Omega} a(x) |\nabla u_n|^{p-2} \nabla u_n \cdot \nabla u dx - \int_{\Omega} a(x) |\nabla u|^{p-2} \nabla u \cdot \nabla u_n dx + \int_{\Omega} a(x) |\nabla u|^p dx \\
 \geq & \int_{\Omega} a(x) |\nabla u_n|^p dx - \left(\int_{\Omega} a(x) |\nabla u_n|^p dx \right)^{\frac{p-1}{p}} \left(\int_{\Omega} a(x) |\nabla u|^p dx \right)^{\frac{1}{p}} \\
 & - \left(\int_{\Omega} a(x) |\nabla u|^p dx \right)^{\frac{p-1}{p}} \left(\int_{\Omega} a(x) |\nabla u_n|^p dx \right)^{\frac{1}{p}} + \int_{\Omega} a(x) |\nabla u|^p dx \\
 = & (\|u_n\| - \|u\|)(\|u_n\|^{p-1} - \|u\|^{p-1}) \geq 0,
 \end{aligned}$$

from which we find that $\lim_{n \rightarrow +\infty} \|u_n\| = \|u\|$. Due to the uniform convexity of $W_0^{1,p}(a, \Omega)$ it follows that $u_n \rightarrow u$ in $W_0^{1,p}(a, \Omega)$, thus completing the proof. \square

We also need the first eigenvalue λ_1 of the operator $A : W_0^{1,p}(a, \Omega) \rightarrow (W_0^{1,p}(a, \Omega))^*$ in (10). Precisely, $\lambda_1 > 0$ is the least (positive) number for which the equation

$$\begin{cases} -\operatorname{div}(a(x)|\nabla u|^{p-2}\nabla u) = \lambda_1|u|^{p-2}u & \text{in } \Omega \\ u = 0 & \text{on } \partial\Omega \end{cases} \tag{13}$$

admits a nontrivial solution called eigenfunction corresponding to the first eigenvalue λ_1 . A solution to (13) is understood in the weak sense, i.e., $u \in W_0^{1,p}(a, \Omega)$ satisfying

$$\int_{\Omega} a(x)|\nabla u(x)|^{p-2}\nabla u(x) \cdot \nabla v(x) dx = \lambda_1 \int_{\Omega} |u(x)|^{p-2}u(x)v(x) dx, \quad \forall v \in W_0^{1,p}(a, \Omega).$$

It is known that there exists an eigenfunction $u_1 \in W_0^{1,p}(a, \Omega)$ corresponding to the first eigenvalue λ_1 such that $u_1(x) \geq 0$ for a.e. $x \in \Omega$, $u_1 \not\equiv 0$, and $u_1 \in L^\infty(\Omega)$. For the proofs of these properties we refer to ([1], Chapter 3).

3. Main Results

Our main abstract result provides the existence of a solution to problem (P) and its location within the ordered interval determined by a sub-supersolution.

Theorem 1. *Let the weight $a \in L^1_{\text{loc}}(\Omega)$ fulfill the requirement (1) and assume that the condition (H) for a subsolution \underline{u} and a supersolution \bar{u} with $\underline{u} \leq \bar{u}$ a.e. is satisfied. Then problem (P) possesses at least a solution $u \in W_0^{1,p}(a, \Omega)$ with the location property $\underline{u} \leq u \leq \bar{u}$ for a.e. $x \in \Omega$.*

Proof. By means of the given sub-supersolution $\underline{u} \leq \bar{u}$ for problem (P), we introduce some related mappings. The cut-off function $\pi : \Omega \times \mathbb{R} \rightarrow \mathbb{R}$ is defined by

$$\pi(x, t) = \begin{cases} -(\underline{u}(x) - t)^{\frac{r}{ps-r}} & \text{if } t < \underline{u}(x) \\ 0 & \text{if } \underline{u}(x) \leq t \leq \bar{u}(x) \\ (t - \bar{u}(x))^{\frac{r}{ps-r}} & \text{if } t > \bar{u}(x), \end{cases} \tag{14}$$

where s and r are the constants given in (1) and Hypothesis 1. Using (14) in conjunction with $\underline{u}, \bar{u} \in L^{ps}(\Omega)$ enables us to find that

$$|\pi(x, t)| \leq c|t|^{\frac{r}{ps-r}} + \varrho(x) \text{ for a.e. } x \in \Omega, \text{ all } t \in \mathbb{R}, \tag{15}$$

with a constant $c > 0$ and a function $\varrho \in L^{\frac{p_s^*(p_s-r)}{r}}(\Omega)$. Moreover, proceeding as in [4], we can establish that

$$\int_{\Omega} \pi(x, u(x))u(x) dx \geq b_1 \|u\|_{L^{\frac{p_s}{p_s-r}}(\Omega)}^{\frac{p_s}{p_s-r}} - b_2 \quad \text{for all } u \in W_0^{1,p}(a, \Omega), \tag{16}$$

with positive constants b_1 and b_2 .

In view of (15), the Nemytskij operator $u \mapsto \pi(\cdot, u(\cdot))$ generated by π maps continuously $L^{p_s^*}(\Omega)$ to $L^{\frac{p_s^*(p_s-r)}{r}}(\Omega)$. Therefore, the mapping $\Pi : W_0^{1,p}(a, \Omega) \rightarrow (W_0^{1,p}(a, \Omega))^*$ defined by

$$\langle \Pi(u), v \rangle = \int_{\Omega} \pi(x, u)v dx, \quad \forall u, v \in W_0^{1,p}(a, \Omega)$$

is completely continuous. This is true because the inclusion $L^{\frac{p_s^*(p_s-r)}{r}}(\Omega) \subset (W_0^{1,p}(a, \Omega))^*$ is compact being the adjoint of the compact inclusion $W_0^{1,p}(a, \Omega) \subset L^{\frac{p_s}{p_s-r}}(\Omega)$ (note that $\frac{p_s^*(p_s-r)}{p_s^*(p_s-r)-r} < p_s^*$ owing to the assumption $r \in (0, \frac{p_s}{(p_s^*)'})$ in (H)).

Hypothesis (H) and (5) imply that the Nemytskij operator $u \mapsto f(\cdot, u(\cdot), \nabla u(\cdot))$ maps continuously $[\underline{u}, \bar{u}] \subset W^{1,p}(a, \Omega)$ to $L^{\frac{p_s}{r}}(\Omega)$ with $r \in (0, \frac{p_s}{(p_s^*)'})$. Composing the preceding Nemytskij operator with the inclusion $L^{\frac{p_s}{r}}(\Omega) \subset (W_0^{1,p}(a, \Omega))^*$, which is compact because it is the adjoint operator of the compact inclusion $W_0^{1,p}(a, \Omega) \subset L^{\frac{p_s}{p_s-r}}(\Omega)$ (note that $\frac{p_s}{p_s-r} < p_s^*$ since $r \in (0, \frac{p_s}{(p_s^*)'})$ in (H)), we obtain a completely continuous mapping $N_f : [\underline{u}, \bar{u}] \rightarrow (W_0^{1,p}(a, \Omega))^*$ given by

$$\langle N_f(u), v \rangle = \int_{\Omega} f(x, u(x), \nabla u(x))v(x) dx$$

for all $u \in [\underline{u}, \bar{u}]$ and $v \in W_0^{1,p}(a, \Omega)$.

We also make use of the truncation operator $T : W_0^{1,p}(a, \Omega) \rightarrow W^{1,p}(a, \Omega)$ given by

$$(Tu)(x) = \begin{cases} \underline{u}(x) & \text{if } u(x) < \underline{u}(x) \\ u(x) & \text{if } \underline{u}(x) \leq u(x) \leq \bar{u}(x) \\ \bar{u}(x) & \text{if } u(x) > \bar{u}(x) \end{cases} \tag{17}$$

for all $u \in W_0^{1,p}(a, \Omega)$ and a.e. $x \in \Omega$. It is a continuous and bounded mapping (in the sense that it maps bounded sets to bounded sets). Notice that its range lies in $[\underline{u}, \bar{u}]$, so T can be composed with the operator N_f .

Now we consider for every $\lambda > 0$ the operator $A_{\lambda} : W_0^{1,p}(a, \Omega) \rightarrow (W_0^{1,p}(a, \Omega))^*$ defined by

$$A_{\lambda} = A + \lambda \Pi - N_f \circ T. \tag{18}$$

Explicitly, it reads as

$$\begin{aligned} \langle A_{\lambda}(u), v \rangle &= \int_{\Omega} a(x)|\nabla u|^{p-2} \nabla u \cdot \nabla v dx + \lambda \int_{\Omega} \pi(x, u)v dx \\ &- \int_{\Omega} f(x, Tu, \nabla(Tu))v dx \quad \text{for all } u, v \in W_0^{1,p}(a, \Omega). \end{aligned} \tag{19}$$

From Proposition 1(i) it is known that the operator $A : W_0^{1,p}(a, \Omega) \rightarrow (W_0^{1,p}(a, \Omega))^*$ is bounded, while the above comments demonstrate that the operators Π, N_f and T are all of them bounded. Therefore from (18) we infer that the operator $A_{\lambda} : W_0^{1,p}(a, \Omega) \rightarrow (W_0^{1,p}(a, \Omega))^*$ is bounded.

We claim that $A_\lambda : W_0^{1,p}(a, \Omega) \rightarrow (W_0^{1,p}(a, \Omega))^*$ is a pseudomonotone operator. In this respect, let a sequence $\{u_n\} \subset W_0^{1,p}(a, \Omega)$ satisfy $u_n \rightharpoonup u$ in $W_0^{1,p}(a, \Omega)$ and

$$\limsup_{n \rightarrow \infty} \langle A_\lambda(u_n), u_n - u \rangle \leq 0. \tag{20}$$

The sequence $\{\Pi(u_n)\}$ is bounded in $L^{\frac{ps^*(ps-r)}{r}}(\Omega)$, while $u_n \rightarrow u$ in $L^{\frac{ps^*(ps-r)}{ps^*(ps-r)-r}}(\Omega)$ by the compact embedding $W_0^{1,p}(a, \Omega) \subset L^{\frac{ps^*(ps-r)}{ps^*(ps-r)-r}}(\Omega)$, thus

$$\lim_{n \rightarrow \infty} \langle \Pi(u_n), u_n - u \rangle = 0.$$

The sequence $\{N_f \circ T(u_n)\}$ is bounded in $L^{\frac{ps}{r}}(\Omega)$, while $u_n \rightarrow u$ in $L^{\frac{ps}{ps-r}}(\Omega)$ by the compact embedding $W_0^{1,p}(a, \Omega) \subset L^{\frac{ps}{ps-r}}(\Omega)$, producing

$$\lim_{n \rightarrow \infty} \langle N_f \circ T(u_n), u_n - u \rangle = 0.$$

Consequently, complying with (18), we see that (20) reduces to (12). This, in conjunction with the weak convergence $u_n \rightharpoonup u$, enables us to apply Proposition 1(iv) ensuring that the strong convergence $u_n \rightarrow u$ in $W_0^{1,p}(a, \Omega)$ holds.

From the strong convergence $a(\cdot)^{\frac{1}{p}} \nabla u_n(\cdot) \rightarrow a(\cdot)^{\frac{1}{p}} \nabla u(\cdot)$ in $(L^p(\Omega))^N$ it follows the strong convergence $a(\cdot)^{\frac{p-1}{p}} |\nabla u_n(\cdot)|^{p-2} \nabla u_n(\cdot) \rightarrow a(\cdot)^{\frac{p-1}{p}} |\nabla u(\cdot)|^{p-2} \nabla u(\cdot)$ in $(L^{\frac{p}{p-1}}(\Omega))^N$. This amounts to saying that $Au_n \rightarrow Au$ in $(W_0^{1,p}(a, \Omega))^*$ since

$$\langle Au_n, v \rangle = \int_{\Omega} a(x) |\nabla u_n|^{p-2} \nabla u_n \cdot \nabla v dx \rightarrow \int_{\Omega} a(x) |\nabla u|^{p-2} \nabla u \cdot \nabla v dx = \langle Au, v \rangle, \forall v \in W_0^{1,p}(a, \Omega).$$

Again, from the strong convergence $a(\cdot)^{\frac{1}{p}} \nabla u_n(\cdot) \rightarrow a(\cdot)^{\frac{1}{p}} \nabla u(\cdot)$ in $(L^p(\Omega))^N$ we infer that

$$\langle Au_n, u_n \rangle = \int_{\Omega} a(x) |\nabla u_n|^p dx \rightarrow \int_{\Omega} a(x) |\nabla u|^p dx = \langle Au, u \rangle$$

as $n \rightarrow \infty$. Taking into account the continuity of the mappings Π and $N_f \circ T$, we have

$$\langle A_\lambda u_n, v \rangle \rightarrow \langle A_\lambda u, v \rangle, \forall v \in W_0^{1,p}(a, \Omega),$$

and

$$\langle A_\lambda u_n, u_n \rangle \rightarrow \langle A_\lambda u, u \rangle$$

as $n \rightarrow \infty$, for every $\lambda > 0$. We can conclude that $A_\lambda : W_0^{1,p}(a, \Omega) \rightarrow (W_0^{1,p}(a, \Omega))^*$ is a pseudomonotone operator (see, e.g., ([2], Definition 2.97)).

The next step in the proof is to show that the operator $A_\lambda : W_0^{1,p}(a, \Omega) \rightarrow (W_0^{1,p}(a, \Omega))^*$ is coercive provided $\lambda > 0$ is large enough. Taking advantage of the fact that $Tu \in [\underline{u}, \bar{u}]$ whenever $u \in W_0^{1,p}(a, \Omega)$, let us note by (16), (19) and Hypothesis 1 that

$$\begin{aligned} \langle A_\lambda(u), u \rangle &= \langle A(u), u \rangle + \lambda \int_{\Omega} \pi(x, u) u dx - \int_{\Omega} f(x, Tu, \nabla(Tu)) u dx \\ &\geq \|u\|^p + \lambda (b_1 \|u\|_{L^{\frac{ps}{ps-r}}(\Omega)}^{\frac{ps}{ps-r}} - b_2) - \|\sigma\|_{L^{\frac{ps}{r}}(\Omega)} \|u\|_{L^{\frac{ps}{ps-r}}(\Omega)} - b \int_{\Omega} |\nabla(Tu)|^r |u| dx \end{aligned} \tag{21}$$

for all $u \in W_0^{1,p}(a, \Omega)$. Now we estimate the last term in (21) based on the fact that by (5) we know that $\nabla u \in (L^{p_s}(\Omega))^N$, and so $\nabla(Tu) \in (L^{p_s}(\Omega))^N$. Using the definition of Tu in (17), Hölder’s inequality and the continuous embedding in (9) it turns out that

$$\begin{aligned} & \int_{\Omega} |\nabla(Tu)|^r |u| dx = \int_{\{\underline{u} \leq u \leq \bar{u}\}} |\nabla u|^r |u| dx + \int_{\{u < \underline{u}\}} |\nabla \underline{u}|^r |u| dx + \int_{\{u > \bar{u}\}} |\nabla \bar{u}|^r |u| dx \\ & \leq \int_{\Omega} |\nabla u|^r |u| dx + c_1 \|u\|, \quad \forall u \in W_0^{1,p}(a, \Omega), \end{aligned}$$

with a constant $c_1 > 0$. We can insert the preceding inequality in (21) to derive

$$\langle A_{\lambda}(u), u \rangle \geq \|u\|^p + \lambda (b_1 \|u\|_{L^{\frac{p_s}{p_s-r}}(\Omega)}^{\frac{p_s}{p_s-r}} - b_2) - c_2 \|u\| - b \int_{\Omega} |\nabla u|^r |u| dx, \quad (22)$$

with a constant $c_2 > 0$. The Hölder’s and Young’s inequalities in conjunction with embedding (5) imply

$$\int_{\Omega} |\nabla u|^r |u| dx \leq \|\nabla u\|_{L^{p_s}(\Omega)}^r \|u\|_{L^{\frac{p_s}{p_s-r}}(\Omega)} \leq c_3 \|u\|^{p_s} + c_4 \|u\|_{L^{\frac{p_s}{p_s-r}}(\Omega)}^{\frac{p_s}{p_s-r}},$$

with constants $c_3 > 0$ and $c_4 > 0$. Then (22) entails

$$\langle A_{\lambda}(u), u \rangle \geq \|u\|^p + \lambda (b_1 \|u\|_{L^{\frac{p_s}{p_s-r}}(\Omega)}^{\frac{p_s}{p_s-r}} - b_2) - c_2 \|u\| - b (c_3 \|u\|^{p_s} + c_4 \|u\|_{L^{\frac{p_s}{p_s-r}}(\Omega)}^{\frac{p_s}{p_s-r}}) \quad (23)$$

for all $u \in W_0^{1,p}(a, \Omega)$. Recalling from (16) that $b_1 > 0$, we can choose $\lambda > 0$ so large to have $\lambda b_1 > b c_4$. Hence due to $p > p_s \geq 1$ (see (1)), (23) yields the coercivity of A_{λ} , i.e.,

$$\lim_{\|u\| \rightarrow +\infty} \frac{\langle A_{\lambda}(u), u \rangle}{\|u\|} = +\infty.$$

We have shown that the nonlinear operator $A_{\lambda} : W_0^{1,p}(a, \Omega) \rightarrow (W_0^{1,p}(a, \Omega))^*$ is bounded, pseudomonotone and coercive provided $\lambda > 0$ is sufficiently large. Therefore, for such an A_{λ} we can apply the main theorem of pseudomonotone operators (see, e.g., ([2], Theorem 2.99)) ensuring that there exists a solution $u \in W_0^{1,p}(a, \Omega)$ to the equation

$$A_{\lambda}(u) = 0. \quad (24)$$

Fix an admissible $\lambda > 0$ as pointed out above. We are going to prove that $u \in W_0^{1,p}(a, \Omega)$ resolving (24) is a weak solution of the original problem (P), which means that (2) is satisfied. To this end, notice that (19) and (24) yield

$$\begin{aligned} & \int_{\Omega} a(x) |\nabla u(x)|^{p-2} \nabla u(x) \cdot \nabla v(x) dx + \lambda \int_{\Omega} \pi(x, u) v dx \\ & = \int_{\Omega} f(x, Tu, \nabla(Tu)) v dx \quad \text{for all } v \in W_0^{1,p}(a, \Omega). \end{aligned} \quad (25)$$

We proceed by comparing u with the subsolution \underline{u} and supersolution \bar{u} postulated in assumption (H). We claim that $u \leq \bar{u}$ a.e. in Ω . Towards this, it can be readily checked that $(u - \bar{u})^+ = \max\{u - \bar{u}, 0\} \in W_0^{1,p}(a, \Omega)$, where the condition $\bar{u} \geq 0$ on $\partial\Omega$ in the sense of traces is essentially used. Thus, we can insert $v = (u - \bar{u})^+$ in (25) and (4) which gives

$$\begin{aligned} & \int_{\Omega} a(x) |\nabla u(x)|^{p-2} \nabla u(x) \cdot \nabla (u - \bar{u})^+(x) dx + \lambda \int_{\Omega} \pi(x, u(x)) (u - \bar{u})^+(x) dx \\ & = \int_{\Omega} f(x, Tu(x), \nabla(Tu)(x)) (u - \bar{u})^+(x) dx \end{aligned} \quad (26)$$

and

$$\int_{\Omega} a(x)|\nabla\bar{u}(x)|^{p-2}\nabla\bar{u}(x) \cdot \nabla(u - \bar{u})^+(x)dx \geq \int_{\Omega} f(x, \bar{u}(x), \nabla\bar{u}(x))(u - \bar{u})^+(x)dx. \tag{27}$$

From (26) and (27), by subtraction we are led to

$$\begin{aligned} & \int_{\Omega} a(x)\left(|\nabla u(x)|^{p-2}\nabla u(x) - |\nabla\bar{u}(x)|^{p-2}\nabla\bar{u}(x)\right) \cdot \nabla(u - \bar{u})^+(x)dx + \lambda \int_{\Omega} \pi(x, u(x))(u - \bar{u})^+(x)dx \\ & \leq \int_{\Omega} (f(x, Tu(x), \nabla(Tu)(x)) - f(x, \bar{u}(x), \nabla\bar{u}(x)))(u - \bar{u})^+(x)dx. \end{aligned}$$

By (14), (17), and the preceding inequality we get

$$\begin{aligned} & \int_{\{u>\bar{u}\}} a(x)\left(|\nabla u(x)|^{p-2}\nabla u(x) - |\nabla\bar{u}(x)|^{p-2}\nabla\bar{u}(x)\right) \cdot \nabla(u - \bar{u})dx + \lambda \int_{\{u>\bar{u}\}} (u(x) - \bar{u}(x))^{\frac{ps}{ps-r}} dx \\ & \leq \int_{\{u>\bar{u}\}} (f(x, Tu, \nabla(Tu)) - f(x, \bar{u}, \nabla\bar{u}))(u - \bar{u})dx = 0. \end{aligned}$$

Since the function $a(x)$ is positive almost everywhere in Ω and the mapping $\xi \mapsto |\xi|^{p-2}\xi$ on \mathbb{R}^N is monotone, we arrive at

$$\int_{\{u>\bar{u}\}} (u(x) - \bar{u}(x))^{\frac{ps}{ps-r}} dx \leq 0.$$

Therefore, the Lebesgue measure of the set $\{u > \bar{u}\}$ is zero, i.e., $u \leq \bar{u}$ a.e. in Ω .

Similarly, we can prove that $\underline{u} \leq u$ a.e. in Ω . Specifically, relying on the condition $\underline{u} \leq 0$ on $\partial\Omega$ (in the sense of traces), it holds $(\underline{u} - u)^+ = \max\{\underline{u} - u, 0\} \in W_0^{1,p}(a, \Omega)$, which allows us to test (25) and (3) with $v = (\underline{u} - u)^+ \in W_0^{1,p}(a, \Omega)$. This results in

$$\begin{aligned} & \int_{\Omega} a(x)|\nabla u(x)|^{p-2}\nabla u(x) \cdot \nabla(\underline{u} - u)^+(x)dx + \lambda \int_{\Omega} \pi(x, u(x))(\underline{u} - u)^+(x)dx \\ & = \int_{\Omega} f(x, Tu(x), \nabla(Tu)(x))(\underline{u} - u)^+(x)dx \end{aligned} \tag{28}$$

and

$$\int_{\Omega} a(x)|\nabla\underline{u}(x)|^{p-2}\nabla\underline{u}(x) \cdot \nabla(\underline{u} - u)^+(x)dx \leq \int_{\Omega} f(x, \underline{u}(x), \nabla\underline{u}(x))(\underline{u} - u)^+(x)dx. \tag{29}$$

Arguing as before, we deduce from (28), (29), (14), and (17) the following estimate

$$\begin{aligned} & \int_{\{\underline{u}>u\}} a(x)\left(|\nabla\underline{u}(x)|^{p-2}\nabla\underline{u}(x) - |\nabla u(x)|^{p-2}\nabla u(x)\right) \cdot \nabla(\underline{u} - u)dx + \lambda \int_{\{\underline{u}>u\}} (\underline{u}(x) - u(x))^{\frac{ps}{ps-r}} dx \\ & \leq \int_{\Omega} (f(x, \underline{u}, \nabla\underline{u}) - f(x, Tu, \nabla(Tu)))(\underline{u} - u)^+ dx \\ & = \int_{\{\underline{u}>u\}} (f(x, \underline{u}, \nabla\underline{u}) - f(x, Tu, \nabla(Tu)))(\underline{u} - u)^+ dx = 0. \end{aligned}$$

At this point, the positivity of the function $a(x)$ on Ω and the monotonicity of the mapping $\xi \mapsto |\xi|^{p-2}\xi$ on \mathbb{R}^N confirm that

$$\int_{\{\underline{u}>u\}} (\underline{u}(x) - u(x))^{\frac{ps}{ps-r}} dx \leq 0,$$

from which we can readily derive that $\underline{u} \leq u$ a.e in Ω .

Based on the enclosure property $\underline{u} \leq u \leq \bar{u}$ a.e. in Ω , it follows through (17) that $T(u) = u$ and through (14) that $\Pi(u) = 0$. As a result, (25) takes the form of (2), thus the proof is complete. \square

Now we present an application of Theorem 1 describing how the existence of a nontrivial nonnegative solution can be established by effectively determining a sub-supersolution. In the sequel, by λ_1 we denote the first eigenvalue of problem (13) (see Section 2).

Theorem 2. Let the weight $a \in L^1_{loc}(\Omega)$ fulfill the requirement (1). Assume that the Carathéodory function $f : \Omega \times \mathbb{R} \times \mathbb{R}^N \rightarrow \mathbb{R}$ satisfies the conditions:

(j) there is a constant $\mu > 0$ such that

$$\lambda_1 t^{p-1} \leq f(x, t, \xi) \text{ for a.e. } x \in \Omega, \text{ all } t \in [0, \mu], \xi \in \mathbb{R}^N;$$

(jj) there is a constant $C > 0$ such that

$$f(x, C, 0) \leq 0 \text{ for a.e. } x \in \Omega;$$

(jjj) there are a function $\sigma \in L^{\frac{p_s}{r}}(\Omega)$ and constants $b > 0$ and $r \in (0, \frac{p_s}{(p_s^*)'})$ such that

$$|f(x, t, \xi)| \leq \sigma(x) + b|\xi|^r \text{ for a.e. } x \in \Omega, \text{ all } t \in [0, C], \xi \in \mathbb{R}^N.$$

Then problem (P) has a nondegenerate, nonnegative and bounded weak solution $u \in W_0^{1,p}(a, \Omega)$ satisfying the estimate $u \leq C$.

Proof. Our goal is to apply Theorem 1 by constructing an appropriate sub-supersolution. In order to determine a subsolution, we use an eigenfunction $u_1 \in W_0^{1,p}(a, \Omega)$ corresponding to the first eigenvalue λ_1 of problem (13) with the properties $u_1(x) \geq 0$ for a.e. $x \in \Omega$, $u_1 \not\equiv 0$, and $u_1 \in L^\infty(\Omega)$ as mentioned in Section 2. Then we choose an $\varepsilon > 0$ sufficiently small to verify

$$\varepsilon u_1(x) \leq \mu \text{ for a.e. } x \in \Omega, \tag{30}$$

where μ is the positive constant postulated in assumption (j). Then assumption (j) implies

$$\lambda_1(\varepsilon u_1)^{p-1} \leq f(x, \varepsilon u_1, \nabla(\varepsilon u_1)) \text{ for a.e. } x \in \Omega. \tag{31}$$

For a possibly smaller $\varepsilon > 0$ we can suppose

$$\varepsilon u_1(x) \leq C \text{ for a.e. } x \in \Omega, \tag{32}$$

with $C > 0$ in assumption (jj).

Let us fix an $\varepsilon > 0$ for which (30) and (32) are fulfilled. We claim that $\underline{u} = \varepsilon u_1$ is a subsolution to problem (P). Indeed, by (13) with u_1 in place of u and (31) we note that

$$\begin{aligned} \int_{\Omega} a(x)|\nabla \underline{u}(x)|^{p-2} \nabla \underline{u}(x) \cdot \nabla v(x) dx &= \varepsilon^{p-1} \lambda_1 \int_{\Omega} u_1(x)^{p-1} v(x) dx \\ &\leq \int_{\Omega} f(x, \varepsilon u_1(x), \nabla(\varepsilon u_1)(x)) v(x) dx = \int_{\Omega} f(x, \underline{u}(x), \nabla \underline{u}(x)) v(x) dx \end{aligned}$$

for all $v \in W_0^{1,p}(a, \Omega)$, $v \geq 0$ a.e. in Ω , thereby proving the claim.

Next we claim that the constant function $\bar{u} = C$, with $C > 0$ in assumption (jj), is a supersolution to problem (P). Accordingly, from assumption (jj) we find that

$$\int_{\Omega} a(x)|\nabla \bar{u}(x)|^{p-2} \nabla \bar{u}(x) \cdot \nabla v(x) dx = 0 \geq \int_{\Omega} f(x, C, 0) v(x) dx = \int_{\Omega} f(x, \bar{u}(x), \nabla \bar{u}(x)) v(x) dx$$

for all $v \in W_0^{1,p}(a, \Omega)$, $v \geq 0$ a.e. in Ω , which proves the claim.

It is clear from (32) that $\underline{u}(x) \leq \bar{u}(x)$ for a.e. in Ω . Assumption (jjj) ensures that the growth condition required in Hypothesis 1 of Theorem 1 holds true. Therefore, all the hypotheses of Theorem 1 are verified, which permits the conclusion that there exists a solution $u \in W_0^{1,p}(a, \Omega)$ of problem (P) within the ordered interval $[\underline{u}, \bar{u}]$. Since the function $\underline{u} = \varepsilon u_1$ is nontrivial and nonnegative, and $u \geq \underline{u}$, we have that u is nontrivial and

nonnegative, whereas $u \in [\underline{u}, \bar{u}]$ renders the boundedness of u and the a priori estimate $u \leq C$. The proof is complete. \square

We end the paper with a simple example for which Theorem 2 applies.

Example 1. Fix a positive weight $a \in L^1_{\text{loc}}(\Omega)$ with the property (1). Let the function $f : \Omega \times \mathbb{R} \times \mathbb{R}^N \rightarrow \mathbb{R}$ be defined by

$$f(x, t, \xi) = \begin{cases} 0 & \text{if } t < 0 \\ t^{p-1}(\rho(x) + |\xi|^r) & \text{if } 0 \leq t \leq 1 \\ (2-t)(\rho(x) + |\xi|^r) & \text{if } t > 1, \end{cases}$$

with some $r \in [1, \frac{p_s}{(p_s^*)})$ and $\rho \in L^\infty(\Omega)$ satisfying $\rho(x) \geq \lambda_1$ for a.e. $x \in \Omega$. It follows that f is a Carathéodory function for which conditions (j) – (jjj) in Theorem 2 are verified. Precisely, condition (j) holds with $\mu = 1$ because $\rho(x) \geq \lambda_1$, condition (jj) holds with $C = 2$, and condition (jjj) is fulfilled with the given r . Hence Theorem 2 applies to problem (P) whose equation has the right-hand side expressed with the function $f(x, t, \xi)$ given above.

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