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CODIMENSION GROWTH OF SPECIAL SIMPLE JORDAN ALGEBRAS

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ABSTRACT. Let R be a special simple Jordan algebra over a field of characteristic zero. We exhibit a noncommutative Jordan polynomial f multialternating on disjoint sets of variables which is not a polynomial identity of R. We then study the growth of the polynomial identities of the Jordan algebra R through an analysis of its sequence of Jordan codimensions. By exploiting the basic properties of the polynomial f, we are able to compute the exponential rate of growth of the sequence of Jordan codimensions of R and prove that it equals the dimension of the Jordan algebra over its center. We also show that for any finite dimensional special Jordan algebra, such an exponential rate of growth cannot be strictly between 1 and 2.

1. INTRODUCTION

Let F be a field of characteristic zero and A a not necessarily associative algebra over F. The study of the polynomial identities satisfied by A has been carried out in an effective way through the representation theory of the symmetric group. The combination of algebraic and analytical methods in this theory leads to significant results (see for instance [3], [4], [11], [19]).

The identities of an algebra A form a T-ideal Id(A) of the free nonassociative algebra $F\{X\}$, and one associates to Id(A) an integral sequence $c_n(A)$, n = 1, 2, ...,called the sequence of codimensions of A. Recall that if P_n is the space of multilinear polynomials in the variables x_1, \ldots, x_n , then $c_n(A) = \frac{P_n}{P_n \cap Id(A)}$. Such a sequence measures in some way the polynomial relations vanishing in an algebra A and in general has overexponential growth. In order to study such a sequence, several methods have been developed over the years ([11], [19]) and the most significant results have been obtained when $c_n(A)$ is exponentially bounded.

In this setting a celebrated theorem of Regev ([21]) states that any associative algebra satisfying a nontrivial polynomial identity (PI-algebra) has the sequence of the codimensions exponentially bounded. Moreover the class of nonassociative algebras sharing such a property is quite wide and includes finite dimensional algebras ([11]), infinite dimensional simple Lie algebras of Cartan type ([17]), affine Kac-Moody algebras ([22]), etc. In case $c_n(A)$ is exponentially bounded, one

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can construct the bounded sequence $\sqrt[n]{c_n(A)}$, n = 1, 2, ..., and ask if $exp(A) = \lim_{n \to \infty} \sqrt[n]{c_n(A)}$ exists; exp(A) is called the PI-exponent of the algebra A.

In [10] it was proved that for any associative PI-algebra A, exp(A) exists and is an integer. In the case of finite dimensional Lie algebras, in [23] it was shown that the PI-exponent also exists and is an integer. The same conclusion was achieved in [12] for the Jordan algebra $M_k(F)$ of $k \times k$ matrices and in [9] for some special simple Jordan algebras of small dimension. These results about the integrality of the PI-exponent are quite surprising since in [7] the authors constructed, for any real number $\alpha > 1$, a nonassociative algebra whose exponential rate of growth of the codimensions equals α .

The main purpose of this paper is to prove the existence of the PI-exponent for any finite dimensional special simple Jordan algebra. Recall that if F is algebraically closed, then any such algebra is isomorphic to one of the following: 1) $M_k(F)$ with the Jordan product $a \circ b = ab + ba$, 2) the Jordan algebra $(M_k(F), t)^+$ of $k \times k$ symmetric matrices under the transpose involution, 3) the Jordan algebra $(M_k(F), s)^+$ of $k \times k$ symmetric matrices under the symplectic involution, 4) the Jordan algebra defined by a nondegenerate symmetric bilinear form on a k-dimensional vector space. The main result proved here is the following.

Theorem. Let A be a finite dimensional special simple Jordan algebra over a field of characteristic zero. Then exp(A) exists and equals the dimension of A over its center.

Of independent interest is also a construction for any such algebra, of a multialternating Jordan polynomial in $k \cdot \dim A$ variables for any $k \ge 1$, which is not an identity of A. We refer the reader to [14] for the basic properties of Jordan algebras.

The last section of the paper is devoted to finite dimensional special Jordan algebras and slow exponential growth of the codimensions.

In [5] it was proved that if A is a finite dimensional algebra, dim A = d, then either $c_n(A)$ is polynomially bounded or $c_n(A) > \frac{1}{n^2} 2^{\frac{n}{3d^2}}$ for n large enough. Moreover by [7], given any real numbers $1 < \alpha < \beta < 2$ there exists a finite dimensional algebra B such that $\alpha < exp(B) < \beta$.

Despite these results, the exponential rate of growth of the codimensions cannot be less than 2 for a wide class of algebras. In fact, if A is either an associative algebra ([16]) or a Lie algebra ([18]), then the asymptotic inequality $c_n(A) < 2^n$ implies $c_n(A) \leq f(n)$ for some polynomial f. The same phenomenon occurs in the case of two and three dimensional nonassociative algebras ([6], [8]) and finite dimensional Lie superalgebras ([24]). In the last section we show that finite dimensional special Jordan algebras also cannot have exponential codimension growth strictly between 1 and 2.

Recall that given an associative algebra A, the Lie commutator [a, b] = ab - badefines a structure of a Lie algebra on A. Similarly the circle operation $a \circ b = ab + ba$ defines a structure of a Jordan algebra. Throughout we shall use the left-normed notation on Lie and Jordan monomials; i.e., $[x_1, \ldots, x_n]$ denotes $[[x_1, x_2], \ldots, x_n]$ and similarly for Jordan products $x_1 \circ \cdots \circ x_n = ((x_1 \circ x_2) \cdots) \circ x_n$.

Let $X = \{x_1, x_2, \ldots\}$ be a countable set. We denote by $F\langle X \rangle$ the free associative algebra on X over F and by $F^J\langle X \rangle$ and $F^L\langle X \rangle$ the free special Jordan algebra and the free Lie algebra on X, respectively. Throughout we shall tacitly assume that

 $F^{J}\langle X \rangle$ and $F^{L}\langle X \rangle$ are canonically embedded in $F\langle X \rangle$. Also, we shall use other symbols such as y, z, x_{i}^{j} for extra new indeterminates in $F\langle X \rangle$.

2. Multialternating Lie polynomials and symmetric matrices

Let A be any associative algebra and $V \subseteq A$ a subspace. Recall that a polynomial $f(x_1, \ldots, x_t) \in F\langle X \rangle$ is an identity of V if $f(v_1, \ldots, v_t) = 0$ for any $v_1, \ldots, v_t \in V$. Also, a polynomial $f \in F^L\langle X \rangle$ is called a Lie polynomial and $f \in F^J\langle X \rangle$ is a Jordan polynomial. There is a connection between Lie and Jordan polynomials given in the following.

Lemma 1. Any multilinear Lie polynomial of odd degree is a Jordan polynomial.

Proof. Since any Lie polynomial is a sum of left-normed monomials, the proof easily follows from the equality

(1)
$$[a,b,c] = a \circ (c \circ b) - (a \circ c) \circ b.$$

Lemma 2. Let $f = f(x_1, \ldots, x_m, y_1, \ldots, y_k)$ be a multilinear Lie polynomial alternating on x_1, \ldots, x_m . Then, for $v, z \in X$, the polynomial

$$g = \sum_{i=1}^{m} f(x_1, \dots, x_{i-1}, [x_i, v, z], x_{i+1}, \dots, x_m, y_1, \dots, y_k)$$

is also alternating on x_1, \ldots, x_m .

Proof. Clearly it is enough to check that f is alternating on each pair $x_{\alpha}, x_{\beta}, 1 \leq \alpha < \beta \leq m$. For short let $\alpha = 1$ and $\beta = 2$. Since the polynomial

$$\sum_{i=3}^m f(x_1,\ldots,[x_i,v,z],\ldots,x_m,y_1,\ldots,y_k)$$

is alternating on x_1 and x_2 , it is enough to check that

 $g' = f([x_1, v, z], x_2, \dots, x_m, y_1, \dots, y_k) + f(x_1, [x_2, v, z], x_3, \dots, x_m, y_1, \dots, y_k)$

is alternating on x_1 and x_2 . But

$$g'(x_1, x_2, \ldots) + g'(x_2, x_1, \ldots) = f([x_1, v, z], x_2, \ldots) + f(x_1, [x_2, v, z], \ldots) + f([x_2, v, z], x_1, \ldots) + f(x_2, [x_1, v, z], \ldots) = f([x_1, v, z], x_2, \ldots) - f([x_2, v, z], x_1, \ldots) + f([x_2, v, z], x_1, \ldots) - f([x_1, v, z], x_2, \ldots) \equiv 0,$$

since $f(x, y, \ldots) = -f(y, x, \ldots)$.

Throughout we let $R = M_q(F)$ denote the algebra of $q \times q$ matrices over a field F of characteristic zero and we let * denote either the transpose involution denoted * = t or the symplectic involution denoted * = s on R. Since we are interested in simple Jordan algebras, we shall also assume that $q \geq 3$. Define

$$R^{(+)} = \{ a \in R \mid a^* = a \}, \quad R^{(-)} = \{ a \in R \mid a^* = -a \}.$$

Then $R^{(+)}$ is a Jordan algebra, $R^{(-)}$ is a Lie algebra and $R = R^{(+)} \oplus R^{(-)}$ is a vector space decomposition. Let $L = sl_q(F) \subseteq R$ be the Lie algebra of $q \times q$

traceless matrices. Then $L^* = L$ and we have

$$L = L^{(+)} \oplus L^{(-)},$$

where $L^{(+)} = sl_q(F) \cap R^{(+)}$ and $L^{(-)} = R^{(-)}$.

Recall that, given $a \in R$, the adjoint map $\operatorname{ad} a : R \to R$ is the left Lie multiplication $\operatorname{ad} a : b \to [a, b]$. It is readily seen that if $a \in L^{(+)}$ is symmetric, then $\operatorname{ad} a(L^{(+)}) \subseteq L^{(-)}$ and $\operatorname{ad} a(L^{(-)}) \subseteq L^{(+)}$. Hence, for any $a, b \in L^{(+)}$, the product $(\operatorname{ad} a)(\operatorname{ad} b)$ preserves $L^{(+)}$ and $L^{(-)}$. We shall denote by tr($\operatorname{ad} a \operatorname{ad} b$) the trace of the linear transformation $\operatorname{ad} a \operatorname{ad} b$ on $L^{(+)}$.

In what follows, in order to simplify the notation, we shall often write $f = f(x_1, \ldots, x_m, y_1, \ldots, y_n) = f(x_1, \ldots, x_m, Y)$, where $Y = \{y_1, \ldots, y_n\}$.

Lemma 3. Let $Y = Y_0 \cup Y_1 \cup \cdots \cup Y_r \subseteq X$ be a disjoint union with $r \ge 0$ and Y_0 eventually empty. Let $f = f(x_1, \ldots, x_m, Y)$ be a multilinear Lie polynomial alternating on each Y_i , $1 \le i \le r$, and on x_1, \ldots, x_m , where $m = \dim L^{(+)}$. Then, for any $k \ge 1$ and for any $v_1, z_1, \ldots, v_k, z_k \in X$, there exists a multilinear Lie polynomial

$$g = g(x_1, \ldots, x_m, v_1, z_1, \ldots, v_k, z_k, Y)$$

such that, for any evaluation $\varphi : X \to L^{(+)}$, $\varphi(x_i) = \bar{x}_i$, $1 \le i \le m$, $\varphi(v_j) = \bar{v}_j$, $\varphi(z_j) = \bar{z}_j$, $1 \le j \le k$, $\varphi(y) = \bar{y}$, for $y \in Y$, we have

$$\varphi(g) = g(\bar{x}_1, \dots, \bar{x}_m, \bar{v}_1, \bar{z}_1, \dots, \bar{v}_k, \bar{z}_k, Y)$$

= tr(ad \bar{v}_1 ad \bar{z}_1) \cdots tr(ad \bar{v}_k ad \bar{z}_k) $f(\bar{x}_1, \dots, \bar{x}_m, \bar{Y})$

Moreover g is alternating on each set Y_i , $1 \leq i \leq r$, and on x_1, \ldots, x_m .

Proof. The proof is by induction of k. Suppose first that k = 1. Then we define

$$g = g(x_1, \dots, x_m, v, z, Y) = \sum_{i=1}^m f(x_1, \dots, [x_i, v, z], \dots, x_m, Y).$$

Clearly g is alternating on each set Y_i , $1 \leq i \leq r$ and, by Lemma 2, is also alternating on x_1, \ldots, x_m . Consider the evaluation $\varphi : X \to L^{(+)}$ such that $\varphi(x_i) = \bar{x}_i$, $1 \leq i \leq m$, $\varphi(v) = \bar{v}$, $\varphi(z) = \bar{z}$, $\varphi(y) = \bar{y}$, for $y \in Y$. If the elements $\bar{x}_1, \ldots, \bar{x}_m$ are linearly dependent over F, then, since f and g are alternating on x_1, \ldots, x_m , it follows that $\varphi(f) = \varphi(g) = 0$ and there is nothing to prove.

Suppose then that $\bar{x}_1, \ldots, \bar{x}_m$ are linearly independent over F. Since dim $L^{(+)} = m$, they form a basis of $L^{(+)}$. Hence, for all $i = 1, \ldots, m$, we can write

$$[\bar{x}_i, \bar{v}, \bar{z}] = \alpha_{ii} \bar{x}_i + \sum_{j \neq i} \alpha_{ij} \bar{x}_j,$$

for some scalars $\alpha_{ij} \in F$. Since f is alternating on x_1, \ldots, x_m , we have that

$$f(\bar{x}_1,\ldots,[\bar{x}_i,\bar{v},\bar{z}],\ldots,\bar{x}_m,\bar{Y})=\alpha_{ii}f(\bar{x}_1,\ldots,\bar{x}_i,\ldots,\bar{x}_m,\bar{Y}).$$

It follows that

$$g(\bar{x}_1,\ldots,\bar{x}_m,\bar{v},\bar{z},\bar{Y}) = (\alpha_{11}+\cdots+\alpha_{mm})f(\bar{x}_1,\ldots,\bar{x}_m,\bar{Y}),$$

and, since $\alpha_{11} + \cdots + \alpha_{mm} = \operatorname{tr}(\operatorname{ad} \bar{v} \operatorname{ad} \bar{z})$, the lemma is proved in case k = 1.

Now let k > 1 and suppose that we have constructed a multilinear Lie polynomial $g = g(x_1, \ldots, x_m, v_1, z_1, \ldots, v_{k-1}, z_{k-1}, Y)$ satisfying the conclusion of the lemma. We then write $g = g(x_1, \ldots, x_m, Y')$, where $Y' = Y'_0 \cup Y_1 \cup \cdots \cup Y_r$ and

 $Y'_0 = Y_0 \cup \{v_1, z_1, \dots, v_{k-1}, z_{k-1}\}$. If we now apply to g the same arguments as in the case k = 1, we obtain a polynomial satisfying the conclusion of the lemma. \Box

The following remark holds.

Remark 1. If $q \ge 3$, then $L^{(+)}$ is an irreducible $L^{(-)}$ -module under the adjoint action.

Proof. Suppose first that $L^{(-)}$ is a simple algebra. If M is a proper $L^{(-)}$ -submodule of $L^{(+)}$, then [M, M] is an ideal of $L^{(-)}$. By the simplicity of $L^{(-)}$ either $[M, M] = L^{(-)}$ or [M, M] = 0.

Suppose first that $[M, M] = L^{(-)}$. Since $[M, M] \oplus M$ is an $L^{(-)}$ -module and $[L^{(+)}, [M, M]] \subseteq [[L^{(+)}, M], M] \subseteq [L^{(-)}, M] \subseteq M, [L^{(+)}, M] \subseteq L^{(-)} = [M, M]$, we conclude that $[M, M] \oplus M$ is a proper ideal of $L = sl_q(F)$, a contradiction.

In case [M, M] = 0, we consider the decomposition $L^{(+)} = M \oplus N$, where M and N are $L^{(-)}$ -submodules. By the same arguments as above we have that [N, N] = 0. If we denote $L_0 = L^{(-)}$, $L_1 = M$ and $L_2 = N$, then the decomposition $L = L_0 \oplus L_1 \oplus L_2$ is a \mathbb{Z}_3 -grading of $L = sl_q(F)$. Now, it is well known that, up to isomorphism of graded algebras, any \mathbb{Z}_3 -grading of $L = sl_q(F)$ is induced by a grading of $R = M_q(F)$; i.e., there exists a \mathbb{Z}_3 -grading of $R, R = R_0 \oplus R_1 \oplus R_2$ such that $L_1 = R_1, L_2 = R_2$ and $L_0 = L \cap R_0$ ([2]). On the other hand any \mathbb{Z}_3 -grading of $M_q(F)$ is elementary ([1]) and R_0 is a semisimple not simple associative algebra. It follows that $R_0 \cap sl_q(F) = L_0 = L^{(-)}$ cannot be simple and this is a contradiction. Thus $L^{(+)}$ is an irreducible $L^{(-)}$ -module and we are done.

Suppose now that $L^{(-)}$ is not simple. Then by [13], * = t is the transpose involution and q = 4. In this case a direct computation shows that $L^{(+)}$ is an irreducible $L^{(-)}$ -module.

Definition 1. $\beta : L^{(+)} \times L^{(+)} \to F$ is the bilinear form defined by $\beta(a, b) = \operatorname{tr}(\operatorname{ad} a \operatorname{ad} b)$, for $a, b \in L^{(+)}$.

Next we need to exploit some of the properties of the bilinear form β .

Lemma 4. The bilinear form β is nondegenerate on $L^{(+)} = sl_q(F)^{(+)}$.

Proof. Denote by $I = \{a \in L^{(+)} \mid \beta(a, L^{(+)}) = 0\}$ the (left) kernel of β . Notice that, since ad [a, b] = [ad a, ad b], the form β satisfies the equality

(2)
$$\beta([a,c],b) = \beta(a,[c,b]),$$

for all $a, b \in L^{(+)}$ and $c \in L^{(-)}$. If we consider the adjoint action of $L^{(-)}$ on L, then $L^{(+)}$ is an $L^{(-)}$ -submodule. Now, the equality (2) implies that $[I, L^{(-)}] \subseteq I$, i.e., that I is an $L^{(-)}$ -submodule of $L^{(+)}$. By Remark 1 we have that either I = 0or $I = L^{(+)}$ and, in order to complete the proof of the lemma, it is enough to check that $I \neq L^{(+)}$, i.e., that β is nonzero.

Suppose first that * is the symplectic involution on $M_q(F)$. Then q = 2p is even and * is given by

$$\left(\begin{array}{cc}A & B\\C & D\end{array}\right)^* = \left(\begin{array}{cc}D^t & -B^t\\-C^t & A^t\end{array}\right)$$

where A, B, C, D are $p \times p$ matrices and t denotes the transpose involution. The matrix $a = e_{11} + e_{p+1,p+1}$ is symmetric, and we let $\varphi = (\operatorname{ad} a)^2$. Since $\varphi^2 = \varphi$, then φ is a diagonalizable linear transformation of $L = sl_q(F)$ with eigenvalues 0 and 1. Hence the restriction of φ to $L^{(+)}$ is also diagonalizable with possibly the same

eigenvalues. Since $\varphi(L^{(+)}) \neq 0$, we conclude that $\operatorname{tr} \varphi \neq 0$ and, so, $\beta(a, a) \neq 0$. This completes the proof in case * is symplectic.

In case * is the transpose involution, we choose $a = e_{11} + e_{22}$. Then, since $q \ge 3$, $\varphi = (\operatorname{ad} a)^2$ is a nonzero diagonalizable linear transformation of L with eigenvalues 0 and 1. As above, since the restriction of φ to $L^{(+)}$ is nonzero, we conclude that $\beta(a, a) = \operatorname{tr} \varphi \neq 0.$

As an immediate consequence of the above lemma we have that, given any linearly independent elements $a_1, \ldots, a_m \in L^{(+)}$ with $m = \dim L^{(+)}$, then

(3)
$$\det\left(\beta_{ij}\right) \neq 0,$$

where $\beta_{ij} = \beta(a_i, a_j), 1 \leq i, j \leq m$. We shall use the above property in order to construct alternating polynomials nonvanishing in $L^{(+)}$ and $R^{(+)}$.

Lemma 5. Let $f = f(x_1, \ldots, x_m, y_1, \ldots, y_r)$ be a multilinear Lie polynomial alternating on x_1, \ldots, x_m , where $m = \dim L^{(+)}$. Then, for any $k \ge 1$, there exists a multilinear Lie polynomial

$$g_k(x_1,\ldots,x_m,v_1^{(1)},z_1^{(1)},\ldots,v_m^{(1)},z_m^{(1)},\ldots,v_1^{(k)},z_1^{(k)},\ldots,v_m^{(k)},z_m^{(k)},y_1,\ldots,y_r)$$

satisfying the following conditions:

- 1) g_k is alternating on each of the sets $\{x_1, \ldots, x_m\}$, $\{v_1^{(i)}, \ldots, v_m^{(i)}\}$, and
- 1) g_k is unconverse in (i), $1 \le i \le k$; 2) for any evaluation $\varphi : X \to L^{(+)}$, such that $\varphi(x_i) = \bar{x}_i$, $\varphi(y_i) = \bar{y}_i$, $\varphi(v_i^{(j)}) = \bar{v}_i^{(j)}$, $\varphi(z_i^{(j)}) = \bar{z}_i^{(j)}$, we have

(4)
$$\varphi(g_k) = (\det \bar{\beta}_1) \cdots (\det \bar{\beta}_k) f(\bar{x}_1, \dots, \bar{x}_m, \bar{y}_1, \dots, \bar{y}_r),$$

where

$$\bar{\beta}_{s} = \begin{pmatrix} \beta(\bar{v}_{1}^{(s)}, \bar{z}_{1}^{(s)}) & \cdots & \beta(\bar{v}_{1}^{(s)}, \bar{z}_{m}^{(s)}) \\ \vdots & \vdots \\ \beta(\bar{v}_{m}^{(s)}, \bar{z}_{1}^{(s)}) & \cdots & \beta(\bar{v}_{m}^{(s)}, \bar{z}_{m}^{(s)}) \end{pmatrix},$$

$$s=1,\ldots,k$$

Proof. Suppose first that k = 1 and write $Y = \{y_1, \ldots, y_r\}$. By Lemma 3 there exists a multilinear Lie polynomial

$$g = g(x_1, \dots, x_m, v_1^{(1)}, z_1^{(1)}, \dots, v_m^{(1)}, z_m^{(1)}, Y)$$

such that

$$g(\bar{x}_1, \dots, \bar{x}_m, \bar{v}_1^{(1)}, \bar{z}_1^{(1)}, \dots, \bar{v}_m^{(1)}, \bar{z}_m^{(1)}, \bar{Y})$$

= tr(ad $\bar{v}_1^{(1)}$ ad $\bar{z}_1^{(1)}$) \cdots tr(ad $\bar{v}_m^{(1)}$ ad $\bar{z}_m^{(1)}$) $f(\bar{x}_1, \dots, \bar{x}_m, \bar{Y})$.

Now, for any $\sigma, \tau \in S_m$, we define the polynomial

$$g_{\sigma,\tau} = g_{\sigma,\tau}(x_1, \dots, x_m, v_1^{(1)}, z_1^{(1)}, \dots, v_m^{(1)}, z_m^{(1)}, Y)$$

= $g(x_1, \dots, x_m, v_{\sigma(1)}^{(1)}, z_{\tau(1)}^{(1)}, \dots, v_{\sigma(m)}^{(1)}, z_{\tau(m)}^{(1)}, Y)$

and we set

$$g_1(x_1,\ldots,x_m,v_1^{(1)},z_1^{(1)},\ldots,v_m^{(1)},z_m^{(1)},Y) = \frac{1}{m!} \sum_{\sigma,\tau \in S_m} (\operatorname{sgn} \sigma)(\operatorname{sgn} \tau) g_{\sigma,\tau}.$$

Clearly the polynomial g_1 is alternating on each of the sets $\{x_1, \ldots, x_m\}$, $\{v_1^{(1)}, \ldots, v_m^{(1)}\}$ and $\{z_1^{(1)}, \ldots, z_m^{(1)}\}$. Next we show that $\varphi(g_1) = \det \overline{\beta}_1 \varphi(f)$, for any evaluation φ .

Now, by Lemma 3, it is readily seen that

$$\varphi(g_1) = \gamma \varphi(f)$$

for any evaluation $\varphi: X \to L^{(+)}$, where

$$\gamma = \frac{1}{m!} \sum_{\sigma, \tau \in S_m} (\operatorname{sgn} \sigma) (\operatorname{sgn} \tau) \beta(\bar{v}_{\sigma(1)}^{(1)}, \bar{z}_{\tau(1)}^{(1)}) \cdots \beta(\bar{v}_{\sigma(m)}^{(1)}, \bar{z}_{\tau(m)}^{(1)}).$$

We fix $\sigma \in S_m$ and we compute the sum

$$\gamma_{\sigma} = \sum_{\tau \in S_m} (\operatorname{sgn} \tau) \beta(\bar{v}_{\sigma(1)}^{(1)}, \bar{z}_{\tau(1)}^{(1)}) \cdots \beta(\bar{v}_{\sigma(m)}^{(1)}, \bar{z}_{\tau(m)}^{(1)}).$$

In order to simplify the notation, write $\bar{v}_{\sigma(i)}^{(1)} = a_i$, $\bar{z}_i^{(1)} = b_i$, $i = 1, \dots, m$. Then

$$\gamma_{\sigma} = \sum_{\tau \in S_m} (\operatorname{sgn} \tau) \beta(a_1, b_{\tau(1)}) \cdots \beta(a_m, b_{\tau(m)}) = \det \begin{pmatrix} \beta(a_1, b_1) & \cdots & \beta(a_1, b_m) \\ \vdots & & \vdots \\ \beta(a_m, b_1) & \cdots & \beta(a_m, b_m) \end{pmatrix}$$
$$= (\operatorname{sgn} \sigma) \det \begin{pmatrix} \beta(a_{\sigma^{-1}(1)}, b_1) & \cdots & \beta(a_{\sigma^{-1}(1)}, b_m) \\ \vdots & & \vdots \\ \beta(a_{\sigma^{-1}(m)}, b_1) & \cdots & \beta(a_{\sigma^{-1}(m)}, b_m) \end{pmatrix} = (\operatorname{sgn} \sigma) \det \bar{\beta}_1.$$

Hence

$$\gamma = \frac{1}{m!} \sum_{\sigma \in S_m} (\operatorname{sgn} \sigma) \gamma_\sigma = \operatorname{det} \bar{\beta}_1,$$

and the proof is completed in case k = 1.

If
$$k > 1$$
, by the inductive hypothesis there exists a multilinear Lie polynomial

$$g_{k-1}(x_1, \dots, x_m, v_1^{(1)}, z_1^{(1)}, \dots, v_m^{(1)}, z_m^{(1)}, \dots, v_1^{(k-1)}, z_1^{(k-1)}, \dots, v_m^{(k-1)}, z_m^{(k-1)}, Y)$$

satisfying the conclusion of the lemma. We then write

$$g_{k-1} = g_{k-1}(x_1, \dots, x_m, Y'),$$

where $Y' = Y \cup \{v_1^{(1)}, z_1^{(1)}, \ldots, v_m^{(1)}, z_m^{(1)}, \ldots, v_1^{(k-1)}, z_1^{(k-1)}, \ldots, v_m^{(k-1)}, z_m^{(k-1)}\}$ and we apply to g_{k-1} , Lemma 3 and the previous arguments. In this way we can construct the polynomial g_k and, for any evaluation φ , we have

$$\varphi(g_k) = \det \bar{\beta}_k \varphi(g_{k-1}) = \det \bar{\beta}_1 \cdots \det \bar{\beta}_k \varphi(f).$$

This completes the proof of the lemma.

3. Multialternating Jordan Polynomials

Recall that $R = M_q(F)$, $q \ge 3$, $L = sl_q(F)$, $L^{(+)} = sl_q(F) \cap R^{(+)}$ and $L^{(-)} = R^{(-)}$. By making use of the results of the previous section, we can now construct multialternating Lie polynomials nonvanishing in $L^{(+)}$.

Lemma 6. For any $k \ge 0$ there exists a multilinear Lie polynomial

$$g = g(x_1^{(1)}, \dots, x_m^{(1)}, \dots, x_1^{(2k+1)}, \dots, x_m^{(2k+1)}, y_1, \dots, y_N)$$

satisfying the following conditions:

- 1) g is alternating on each set $\{x_1^{(i)}, ..., x_m^{(i)}\}, 1 \le i \le 2k + 1;$
- 2) g is not an identity of $L^{(+)}$;
- 3) the integer N does not depend on k.

Proof. We start with the case k = 0 by constructing a multilinear Lie polynomial $f = f(x_1, \ldots, x_m, y_1, \ldots, y_N)$ alternating on x_1, \ldots, x_m and nonvanishing on $L^{(+)}$. By a result of Barmydov (20, Theorem 12.1) applied to the adjoint represent

By a result of Razmyslov ([20, Theorem 12.1]) applied to the adjoint representation of the Lie algebra $L = sl_q(F)$, there exist an integer $r \ge 1$ and a multilinear polynomial $h(z_1, \ldots, z_{dr}, y)$, where $d = \dim L = q^2 - 1$, with the following properties: 1) h is alternating on each set $\{z_{(i-1)d+1}, \ldots, z_{id}\}, 1 \le i \le r; 2\}$ for any evaluation $z_i \to \overline{z}_i \in L, y \to \overline{y} \in L$ we have that $h(\overline{z}_1, \ldots, \overline{z}_{dr}, \overline{y}) = \lambda \overline{y}$, for some $\lambda \in F; 3$ h is not an identity of L.

Let $\varphi: z_i \to \overline{z}_i \in L, \ y \to \overline{y} \in L$ be an evaluation such that $\varphi(h) \neq 0$. Then, for any $i = 1, \ldots, r$, the elements $\overline{z}_{(i-1)d+1}, \ldots, \overline{z}_{id}$ must be linearly independent over F. Since $d = \dim L$, this says that precisely $m = \dim L^{(+)}$ among them lie in $L^{(+)}$. After renaming the variables, we may write

$$h = h(x_1, \ldots, x_m, z_1, \ldots, z_{dr-m}, y),$$

h is alternating on x_1, \ldots, x_m and $\varphi(h) \neq 0$, for some evaluation $\varphi : x_1 \rightarrow \bar{x}_1, \ldots, x_m \rightarrow \bar{x}_m$ in $L^{(+)}$ and of the remaining variables in $L^{(+)} \cup L^{(-)}$.

Now, notice that $[L^{(+)}, L^{(+)}] \oplus L^{(+)}$ is a nonzero ideal of the simple Lie algebra $L = sl_q(F)$. Hence $[L^{(+)}, L^{(+)}] = L^{(-)}$. This implies that if φ is a nonzero evaluation of h such that, say, $\varphi : z_1 \to \overline{z}_1 \in L^{(-)}$, then the polynomial

$$h' = h(x_1, \dots, x_m, [y_1, y_2], z_2, \dots, z_{dr-m}, y)$$

has a nonzero evaluation in $L^{(+)} \cup L^{(-)}$ such that $\bar{x}_1, \ldots, \bar{x}_m, \bar{y}_1, \bar{y}_2 \in L^{(+)}$. Next we apply the same procedure to all the variables z_i which are evaluated in $L^{(-)}$. Then, after renaming the variables, we obtain a polynomial $f = f(x_1, \ldots, x_m, y_1, \ldots, y_N)$ alternating on x_1, \ldots, x_m and nonvanishing in $L^{(+)}$. This completes the case k = 0.

If $k \geq 1$, we apply Lemma 5 to f and we obtain a polynomial g_k which is alternating on 2k + 1 sets of variables each of order m. By (4), for any evaluation φ in $L^{(+)}$,

$$\varphi(g_k) = (\det \bar{\beta}_1) \cdots (\det \bar{\beta}_k) \varphi(f).$$

Since by Lemma 4 β is nondegenerate, by (3) det $\bar{\beta}_i \neq 0$, for some evaluation $\bar{\beta}_i$. Hence, since f is not an identity of $L^{(+)}$ it also follows that the polynomial g_k is not an identity of $L^{(+)}$. This completes the proof of the lemma.

Suppose that there exists an element $a \in L$ such that ab = ba or ab = -ba for all $b \in L^{(+)}$. In this case, a commutes with all the elements of $[L^{(+)}, L^{(+)}] = L^{(-)}$; hence it generates a 1-dimensional module for the Lie algebra $L^{(-)}$, under the adjoint action of L. Recall that $L = sl_q(F)$, and it is well known that since $q \geq 3$, L is a faithful $L^{(-)}$ -module. It follows that a = 0. We have proved the following.

Remark 2. If $a \in L$ is such that ab = ba or ab = -ba for all $b \in L^{(+)}$, then a = 0.

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Now we are ready to prove the existence of Jordan multialternating polynomials.

Theorem 1. Let F be a field of characteristic zero and let $R = M_q(F)$ be the algebra of $q \times q$ matrices with transpose or symplectic involution $*, q \geq 3$. Let $R^{(+)} = \{a \in R \mid a^* = a\}$ be its Jordan subalgebra of symmetric elements. If $m = \dim R^{(+)}$, then, for all $k \geq 1$, there exists a multilinear Jordan polynomial

$$h = h(x_1^{(1)}, \dots, x_m^{(1)}, \dots, x_1^{(2k+1)}, \dots, x_m^{(2k+1)}, y_1, \dots, y_N)$$

satisfying the following conditions:

- 1) h is alternating on each set $\{x_1^{(i)}, \ldots, x_m^{(i)}\}, 1 \le i \le 2k + 1;$
- 2) h is not an identity of $R^{(+)}$;
- 3) N does not depend on k.

Proof. Recall that $L = sl_q(F)$, $L^{(+)} = L \cap R^{(+)}$, $L^{(-)} = L \cap R^{(-)} = R^{(-)}$ and $L = L^{(+)} \oplus L^{(-)}$, a direct sum of vector spaces.

Since dim $L^{(+)} = \dim R^{(+)} - 1 = m - 1$, by Lemma 6 there exists a Lie polynomial

$$g = g(x_1^{(1)}, \dots, x_{m-1}^{(1)}, \dots, x_1^{(2k+1)}, \dots, x_{m-1}^{(2k+1)}, y_1, \dots, y_N)$$

nonvanishing on $L^{(+)}$. If deg g is odd, then by Lemma 1, g is a Jordan polynomial. In case deg g is even, we replace g with the polynomial

$$g' = [g(x_1^{(1)}, \dots, x_{m-1}^{(2k+1)}, y_1, \dots, y_N), y_{N+1}].$$

Let $\varphi : X \to L^{(+)}$ be an evaluation such that $\varphi(g) \neq 0$. Then by Remark 2, $[\varphi(g), \bar{y}_{N+1}] \neq 0$ for some $\bar{y}_{N+1} \in L^{(+)}$. This proves that g' does not vanish on $L^{(+)}$. Moreover g' is a Lie polynomial of odd degree. Hence, without loss of generality, we may assume that g itself has odd degree.

Now define

$$h = h(x_1^{(1)}, \dots, x_m^{(1)}, \dots, x_1^{(2k+1)}, \dots, x_m^{(2k+1)}, y_1, \dots, y_N)$$

= Alt₁ · · · Alt_{2k+1}(g \circ x_m^{(1)} \circ \dots \circ x_m^{(2k+1)}),

where Alt_i means alternation on the variables $x_1^{(i)}, \ldots, x_m^{(i)}$. For instance,

$$\operatorname{Alt}_{1}(g \circ x_{m}^{(1)}) = \sum_{\sigma \in S_{m}} (\operatorname{sgn} \sigma) g(x_{\sigma(1)}^{(1)}, \dots, x_{\sigma(m-1)}^{(1)}, \dots, x_{1}^{(2k+1)}, \dots, x_{m-1}^{(2k+1)}, y_{1}, \dots, y_{N}) \circ x_{\sigma(m)}^{(1)}$$

Then h satisfies the conclusion 1) of the theorem, and we need only to prove that h is not an identity of $R^{(+)}$.

Since g is not an identity of $L^{(+)}$, there exists an evaluation $\varphi : x_i^{(j)} \to \bar{x}_i^{(j)} \in L^{(+)}$, $y_j \to \bar{y}_j \in L^{(+)}$ with $\varphi(g) = \bar{g} \neq 0$. Now we extend φ to $x_m^{(1)}, \ldots, x_m^{(2k+1)}$, by setting $\varphi : x_m^{(i)} \to \bar{x}_m^{(i)} = E$, for all $i = 1, \ldots, 2k + 1$, where E is the identity $q \times q$ matrix.

Recalling that g is a Lie polynomial, we get that

$$g(\ldots,\bar{x}_{\sigma(1)}^{(j)},\ldots,\bar{x}_{\sigma(m-1)}^{(j)},\ldots)\circ\cdots\circ\bar{x}_{\sigma(m)}^{(j)}\circ\cdots=0,$$

as soon as $\sigma(m) \neq m$. Therefore, since

$$\sum_{\sigma \in S_m, \sigma(m)=m} (\operatorname{sgn} \sigma) g(\dots, \bar{x}_{\sigma(1)}^{(j)}, \dots, x_{\sigma(m-1)}^{(j)}, \dots) = (m-1)! \bar{g}_{\sigma(m-1)}$$

we obtain

$$\varphi(h) = ((m-1)!)^{2k+1} \overline{g} \circ E \circ \dots \circ E = 2^{2k+1} ((m-1)!)^{2k+1} \overline{g} \neq 0$$

and the proof is complete.

4. Central polynomials for simple Jordan Algebras OF Bilinear forms

In this section we let $R = F \oplus V$ be a Jordan algebra defined by a symmetric bilinear form β on a vector space V. Recall that the product is defined by $uv = \beta(u, v) \cdot 1$, where 1 is the unit element of F, and it acts on V as the identity linear transformation. In case β is nondegenerate and dim $V \ge 2$, then R is simple.

Recall that a central polynomial for an algebra A with 1 is a polynomial f whose values are scalar multiples of 1 in A and f is not a polynomial identity of A.

Proposition 1. If dim V = n, then

(5)
$$f = f(x_1, \dots, x_{n+1}, y_1, \dots, y_{n+1})$$
$$= \sum_{\sigma \in S_{n+1}, \tau \in S_{n+1}} (\operatorname{sgn} \sigma \tau) (x_{\sigma(1)} \circ y_{\tau(1)}) \circ \dots \circ (x_{\sigma(n+1)} \circ y_{\tau(n+1)})$$

is a central polynomial of R.

Proof. We start by proving that f takes scalar values in R, i.e., values of the type $\lambda = \lambda 1 \in F$.

Let $\{e_1, \ldots, e_n\}$ be an orthogonal basis of V, that is, $\beta(e_i, e_j) = 0$ if and only if $i \neq j$. If we set $e_{n+1} = 1 \in F$, then $\{e_1, \ldots, e_{n+1}\}$ is a basis of R. Since f is multilinear it is enough to check that

(6)
$$f(e_{i_1}, \dots, e_{i_{n+1}}, e_{j_1}, \dots, e_{j_{n+1}})$$

is central in R, for all $1 \leq i_1, j_1, \ldots, i_{n+1}, j_{n+1} \leq n+1$. Now, if $\{i_1, \ldots, i_{n+1}\} \neq \{1, \ldots, n+1\}$, then the elements $e_{i_1}, \ldots, e_{i_{n+1}}$ are linearly dependent and the value of f in (6) is zero, since f is alternating on x_1, \ldots, x_{n+1} . Hence $\{i_1, \ldots, i_{n+1}\} = \{1, \ldots, n+1\}$. Similarly $\{j_1, \ldots, j_{n+1}\} = \{1, \ldots, n+1\}$ and the value of f in (6) is a linear combination of monomials of the type

(7)
$$a = (e_{k_1} \circ e_{l_1}) \circ \dots \circ (e_{k_{n+1}} \circ e_{l_{n+1}}),$$

where $\{k_1, \ldots, k_{n+1}\} = \{l_1, \ldots, l_{n+1}\} = \{1, \ldots, n+1\}$. Suppose that i and j are such that $k_i = l_j = n + 1$. Then, in case i = j, all factors $e_{k_\alpha} \circ e_{l_\beta}$ in (7) are scalars and $a \in F$. If $i \neq j$, then $e_{k_i} \circ e_{l_i} = e_{l_i}$, $e_{k_j} \circ e_{l_j} = e_{k_j}$ and, since any other product of the type $e_{k_\alpha} \circ e_{l_\beta}$ with $k_\alpha, l_\beta \leq n$ gives a scalar, we get that $a = \lambda(e_{k_j} \circ e_{l_i}) = \lambda' \in F$. We have proved that all values of f are scalar multiples of 1 in R.

Next we prove that f is not an identity of R. We consider the evaluation φ of f such that $\varphi(x_1) = \varphi(y_1) = e_1, \ldots, \varphi(x_{n+1}) = \varphi(y_{n+1}) = e_{n+1}$. Then

$$\varphi(f) = \sum_{\sigma \in S_{n+1}, \tau \in S_{n+1}} (\operatorname{sgn} \sigma \tau) (e_{\sigma(1)} \circ e_{\tau(1)}) \circ \dots \circ (e_{\sigma(n+1)} \circ e_{\tau(n+1)}) = \sum_{\tau \in S_{n+1}} w_{\tau}$$

where

$$w_{\tau} = \sum_{\sigma \in S_{n+1}} (\operatorname{sgn} \sigma \tau) (e_{\sigma(1)} \circ e_{\tau(1)}) \circ \dots \circ (e_{\sigma(n+1)} \circ e_{\tau(n+1)})$$

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Now we fix $\tau \in S_{n+1}$ and we compute w_{τ} . Since $S_{n+1} = S_{n+1}\tau$, we can write

$$w_{\tau} = \sum_{\rho \in S_{n+1}} (\operatorname{sgn} \rho \tau \tau) (e_{\rho \tau(1)} \circ e_{\tau(1)}) \circ \cdots \circ (e_{\rho \tau(n+1)} \circ e_{\tau(n+1)})$$

(8)
$$= \sum_{\rho \in S_{n+1}} (\operatorname{sgn} \rho) (e_{\rho(i_1)} \circ e_{i_1}) \circ \dots \circ (e_{\rho(i_{n+1})} \circ e_{i_{(n+1)}}),$$

where we have set $\tau(1) = i_1, ..., \tau(n+1) = i_{n+1}$.

If in (8), ρ is such that $\rho(n+1) = n+1$, then the product $(e_{\rho(i_1)} \circ e_{i_1}) \circ \cdots \circ (e_{\rho(i_{n+1})} \circ e_{i_{n+1}}) = v_{\rho}$ is nonzero only if $\rho = (1)$. In this case $\operatorname{sgn} \rho = 1$ and $v_{\rho} = \lambda \in F$, where $\lambda = \lambda_1 \cdots \lambda_n$ with $\lambda_i = e_i \circ e_i \neq 0, 1 \leq i \leq n$. Now let ρ be such that $\rho(n+1) = t \neq n+1$. Then the factor $e_{\rho(t)} \circ e_t$ is nonzero only if $e_{\rho(t)} = e_{n+1} = 1$, i.e., $\rho(t) = n+1$. In this case v_{ρ} is nonzero only if $\rho(j) = j$, for all $j \neq t, n+1$. Hence $\rho = (t, n+1), v_{\rho} = \lambda \in F$ and $\operatorname{sgn} \rho = -1$.

It follows that $w_{\tau} = (1 - n)\lambda \in F$. Therefore

$$\varphi(f) = \sum_{\tau \in S_{n+1}} w_{\tau} = (n+1)!(1-n) \cdot \lambda \neq 0,$$

and f is not an identity of R.

5. Codimension growth

In this section we shall compute the exponential rate of growth of the codimensions of any finite dimensional special simple Jordan algebra. We start by computing an upper bound of the codimensions of any finite dimensional algebra.

Let $F\{X\}$ be the free nonassociative algebra on a countable set X and, for $n \ge 1$ let P_n denote the space of multilinear polynomials of $F\{X\}$ in the variables x_1, \ldots, x_n . If A is a not necessarily associative algebra, we still denote by Id(A) the T-ideal of $F\{X\}$ of polynomial identities of A and $c_n(A) = \dim \frac{P_n}{P_n \cap Id(A)}$.

Proposition 2. If A is a finite dimensional algebra, dim A = d, then $c_n(A) \leq d^{n+1}$.

Proof. Let a_1, \ldots, a_d be a basis of A over F. For a fixed n, let

$$m_1(x_1,\ldots,x_n),\ldots,m_N(x_1,\ldots,x_n)$$

be a basis of P_n over F. Then a multilinear polynomial

$$f(x_1,\ldots,x_n)=\sum \alpha_j m_j(x_1,\ldots,x_n)$$

is an identity of A if and only if it vanishes under any evaluation $x_1 \to a_{i_1}, \ldots, x_n \to a_{i_n}$ i.e., the following linear relation is satisfied:

(9)
$$f(a_{i_1}, \dots, a_{i_n}) = \sum \alpha_j m_j(a_{i_1}, \dots, a_{i_n}) = 0.$$

The total number of such evaluations is d^n since any x_i can take d distinct values. We regard the coefficients α_j as indeterminates. By rewriting the right-hand side of (9) as a linear combination of the basis elements of A, any relation (9) can be viewed as d linear equations on the α_j 's since dim A = d. Hence, (9) can be regarded as a system of d^{n+1} linear equations in N indeterminates α_j , $1 \leq j \leq N$. The space of solutions has dimension N - r, where r is the rank of the system, $r \leq d^{n+1}$. Any solution of (9), i.e., any N-tuple of coefficients α_j , $1 \leq j \leq N$, gives a multilinear identity of A. Moreover, linearly independent solutions give linearly independent

identities. Therefore $\dim(P_n \cap Id(A)) = N - r$ and $c_n(A) = \dim P_n/(P_n \cap Id(A)) = r \le d^{n+1}$.

Now we restrict our attention to Jordan algebras. Let P_n^J be the space of multilinear Jordan polynomials in x_1, \ldots, x_n . Recall that P_n^J is spanned by the Jordan products $x_{\sigma(1)} \circ x_{\sigma(2)} \circ \cdots \circ x_{\sigma(n)}$, where $\sigma \in S_n$ with all possible arrangements of brackets. Given a Jordan algebra B denote by $Id^J(B)$ the T-ideal of $F^J\langle X \rangle$ of polynomial identities of B.

It is well known that the symmetric group S_n acts on P_n^J : if $\sigma \in S_n$ and $f(x_1, \ldots, x_n) \in P_n^J$, then $\sigma f(x_1, \ldots, x_n) = f(x_{\sigma(1)}, \ldots, x_{\sigma(n)})$. We refer the reader to [15] for a description of the representation theory of S_n . As in the associative case, if B is a Jordan algebra, $P_n^J \cap Id^J(B)$ is an S_n -module and $c_n^J(B) = \dim \frac{P_n^J}{P_n^J \cap Id^J(A)}$ is called the *n*th Jordan codimension of B. In case B is a Jordan algebra such that its codimensions $c_n^J(B)$, $n = 1, 2, \ldots$, are exponentially bounded (e.g., if B is finite dimensional), one defines the Jordan exponent of B as $exp^J(B) = \lim_{n \to \infty} \sqrt[n]{c_n^J(B)}$, in case such a limit exists.

In the next theorem we prove that for most special simple Jordan algebras B, the Jordan exponent exists and $exp^{J}(B) = \dim B$.

Theorem 2. Let F be a field of characteristic zero, $R = M_q(F)$, $q \ge 3$, with an involution * and $R^{(+)}$ its Jordan subalgebra of symmetric elements. Then, for all $n \ge 1$, there exist constants C > 0, t such that

$$Cn^t m^n \leq c_n^J(R^{(+)}) \leq m^{n+1}$$

where $m = \dim R^{(+)}$. Hence the Jordan exponent of $R^{(+)}$ exists and $\exp^J(R^{(+)}) = \dim R^{(+)}$.

Proof. It is well known that the codimensions of an algebra do not change upon extension of the base field. Hence without loss of generality we may assume that F is algebraically closed and * is either the transpose or the symplectic involution (see for instance the proof of [11, Theorem 3.6.8]).

By Theorem 1, for all $k \geq 1$, there exists a multilinear Jordan polynomial

$$h = h(x_1^{(1)}, \dots, x_m^{(1)}, \dots, x_1^{(2k+1)}, \dots, x_m^{(2k+1)}, y_1, \dots, y_N)$$

such that h is alternating on each set of indeterminates $\{x_1^{(i)}, \ldots, x_m^{(i)}\}, 1 \leq i \leq 2k + 1$, and h is not a polynomial identity of $R^{(+)}$. For simplicity we rename the variables and we write

$$h = h(x_1, \dots, x_{(2k+1)m}, Y),$$

where $Y = \{y_1, ..., y_N\}.$

For a fixed k, let n = (2k + 1)m. By abuse of notation, we let P_{n+N}^J be the space of multilinear Jordan polynomials in $x_1, \ldots, x_n, y_1, \ldots, y_N$. Then $h \in P_{n+N}^J$ and we regard P_{n+N}^J as an S_n -module by letting S_n act on x_1, \ldots, x_n . We then consider FS_nh , the S_n -submodule of P_{n+N}^J generated by h, and we decompose it into irreducible submodules.

Let $\lambda \vdash n$ be a partition of n. Given a Young tableau T_{λ} of shape $\lambda \vdash n$, let $R_{T_{\lambda}}$ and $C_{T_{\lambda}}$ denote the subgroups of S_n stabilizing the rows and the columns of T_{λ} , respectively. It is well known that if we let

$$\bar{R}_{T_{\lambda}} = \sum_{\sigma \in R_{T_{\lambda}}} \sigma \text{ and } \bar{C}_{T_{\lambda}} = \sum_{\tau \in C_{T_{\lambda}}} (\operatorname{sgn} \tau) \tau,$$

the element $e_{T_{\lambda}} = \bar{R}_{T_{\lambda}}\bar{C}_{T_{\lambda}}$ is an essential idempotent of the group algebra FS_n , generating an irreducible S_n -module associated to λ .

Since $h \notin Id^J(R^{(+)})$, there exists a Young tableau $T_{\lambda}, \lambda \vdash n$, such that $e_{T_{\lambda}}h \neq 0$ in $R^{(+)}$. Write $\lambda = (\lambda_1, \ldots, \lambda_r)$.

If $\lambda_1 \geq 2k + 2$, then $e_{T_{\lambda}}h$ is symmetric on at least 2k + 2 variables among x_1, \ldots, x_n . But for any $\sigma \in \bar{R}_{T_{\lambda}}$ these variables in $\sigma \bar{C}_{T_{\lambda}}$ are divided into 2k + 1 disjoint alternating subsets. It follows that $\sigma \bar{C}_{T_{\lambda}}h$ is alternating and symmetric on at least two variables and, so, $e_{T_{\lambda}}h = 0$ in the zero polynomial, a contradiction. Thus $\lambda_1 \leq 2k + 1$.

Suppose now that $r \geq m+1$. Since the first column of T_{λ} is of height at least m+1, the polynomial $\bar{C}_{T_{\lambda}}h$ is alternating on at least m+1 variables among x_1, \ldots, x_n . From dim $R^{(+)} = m$ it follows that for any $\sigma, \sigma \bar{C}_{T_{\lambda}}h \equiv 0$ on $R^{(+)}$ and, so, also $e_{T_{\lambda}}h = \bar{R}_{T_{\lambda}}\bar{C}_{T_{\lambda}}h \equiv 0$ on $R^{(+)}$, a contradiction.

We have proved that $FS_n e_{T_{\lambda}} h \not\subseteq Id^J(R^{(+)})$, for some Young tableau T_{λ} of shape $\lambda = ((2k+1)^m)$, a rectangle of width 2k+1 and height m.

Now let $n \ge m + N$ be an arbitrary integer and write n = (2k+1)m + N + r, for some $k \ge 1$ and $0 \le r \le 2m$. Let $h = h(x_1, \ldots, x_{(2k+1)m}, Y)$ be the polynomial constructed above and set h' = h, if r = 0, or

$$h'(x_1, \dots, x_{(2k+1)m+r}, Y) = h(x_1, \dots, x_{(2k+1)m}, Y) \circ x_{(2k+1)m+1} \circ \dots \circ x_{(2k+1)m+r},$$

if r > 0. Clearly $h' \in P_n^J$. Moreover, if $\lambda = ((2k+1)^m)$ and T_{λ} is the Young tableau given above such that $e_{T_{\lambda}}h \notin Id^J(R^{(+)})$, it is clear that $e_{T_{\lambda}}h' \notin Id^J(R^{(+)})$ also holds.

Write $FS_n = \bigoplus_{\mu \vdash n} I_{\mu}$, where I_{μ} is the minimal two-sided ideal of FS_n corresponding to the partition μ . By the branching rule of $S_{(2k+1)m}$ (see [15, Theorem 2.4.3]) we have that

$$FS_n e_{T_{\lambda}} h' \subseteq \bigoplus_{\substack{\mu \supseteq \lambda \\ \mu \vdash n}} I_{\mu} h',$$

and, since $e_{T_{\lambda}}h' \notin Id^J(R^{(+)})$, there exists a partition $\mu \vdash n$ and a tableau T_{μ} such that $FS_n e_{T_{\mu}}h' \notin Id^J(R^{(+)})$. This says that $c_n^J(R^{(+)}) \geq d_{\mu} = \dim FS_n e_{T_{\mu}}$. But again by the branching rule, $d_{\mu} \geq d_{\lambda} = d_{((2k+1)^m)}$. Since $n - (2k+1)m \leq r$ and asymptotically $d_{((2k+1)^m)} \simeq C_0((2k+1)m)^s m^{(2k+1)m}$, for some constants C_0, s (see [11, Lemma 6.2.5]), we obtain that

$$c_n^J(R^{(+)}) \ge Cn^t m^n,$$

for some constants C > 0, t.

Putting together Proposition 2 and the above inequality, we get $Cn^tm^n \leq c_n^J(R^{(+)}) \leq m^{n+1}$, for some constants C, t. In particular $\lim_{n\to\infty} \sqrt[n]{c_n^J(R^{(+)})} = m$, and we are done.

The same result also holds for Jordan algebras of bilinear forms.

Theorem 3. Let R be a finite dimensional simple Jordan algebra of a bilinear form over a field of characteristic zero. Then, for all $n \ge 1$, there exist constants C > 0, t such that

$$Cn^t m^n \leq c_n^J(R) \leq m^{n+1},$$

where $m = \dim R$. Hence the Jordan exponent of R exists and $exp^{J}(R) = \dim R$.

Proof. By Proposition 1 there exisits a multilinear polynomial $f(x_1, \ldots, x_m, y_1, \ldots, y_m)$ alternating on x_1, \ldots, x_m and on y_1, \ldots, y_m , where $m = \dim R$, which takes scalar values on R and is not an identity of R. Hence, for all $k \ge 1$ there exists a multilinear Jordan polynomial

$$h = h(x_1^{(1)}, \dots, x_m^{(1)}, \dots, x_1^{(2k)}, \dots, x_m^{(2k)})$$

such that h is alternating on each set of indeterminates $\{x_1^{(i)}, \ldots, x_m^{(i)}\}, 1 \le i \le 2k$, and h is not a polynomial identity of R. The same arguments as in the previous theorem give us a lower bound for the codimensions:

$$c_n^J(R) \ge Cn^t m^n$$

for some constants C > 0, t.

By Proposition 2 we get $c_n^J(B) \leq m^{n+1}$. Hence $\lim_{n \to \infty} \sqrt[n]{c_n^J(R^{(+)})} = m$ and the proof is complete.

We can now state the following result.

Theorem 4. Let R be a finite dimensional special simple Jordan algebra over a field of characteristic zero. Then $exp^{J}(R)$ exists and equals the dimension of R over its center.

Proof. Since the codimensions do not change upon extension of the base field, we may regard R as an algebra over its center F. Now, if \overline{F} is the algebraic closure of F, then $\overline{R} = R \otimes_F \overline{F}$ is a special simple Jordan algebra over \overline{F} and dim_F $R = \dim_F \overline{R}$. Putting together [14, Corollary 2, p. 204], Theorem 2 and Theorem 3, we get the desired conclusion.

Corollary 1. Let R be a finite dimensional special semisimple Jordan algebra over a field of characteristic zero. Then $exp^{J}(R)$ exists and is an integer.

Proof. Write $R = R_1 \oplus \cdots \oplus R_m$, a direct sum of special simple Jordan algebras. Since for all $1 \leq i \leq m$, $c_n(R_i) \leq c_n(R) \leq c_n(R_1) + \cdots + c_n(R_m)$, we get that $exp^J(R) = \max_i(exp^J(R_i))$.

6. Lower bounds for the codimension growth

In this section we want to determine the least exponential rate of growth of a finite dimensional Jordan algebra. In general, for nonassociative algebras, in [5, Theorem 2] it was proved that for a finite dimensional algebra A, dim A = d, $c_n(A)$ is either polynomially bounded or $c_n(A) > \frac{1}{n^2} 2^{\frac{n}{3d^2}}$ for n large enough. Moreover, for any $1 < \alpha < \beta < 2$, in [7] the authors constructed a finite dimensional algebra A sin the case of associative or Lie algebras, finite dimensional special Jordan algebras cannot have exponential rate of growth of the codimensions strictly between 1 and 2.

Theorem 5. Let R be a finite dimensional special Jordan algebra. Then either the sequence of codimensions $c_n^J(R)$ is polynomially bounded or $c_n^J(R) \ge Cn^q 2^n$ for some constants C > 0, q.

Proof. As we remarked in the previous section, we may assume that F is algebraically closed and let us denote by I the nilpotent radical of R. If I = R, then R

is nilpotent and $c_n^J(R) = 0$ asymptotically. Hence we may assume that $I \neq R$. By [25, p. 97 Corollary] A/I is also a special Jordan algebra and let

$$R/I = B_1 \oplus \cdots \oplus B_m$$

be the decomposition of A/I into the sum of simple algebras. If there exists $j \ge 1$ such that dim $B_j = d > 1$, then by Theorem 3 we have that $c_n^J(A) \ge c_n^J(A/I) \ge c_n^J(B_j) = Cn^t d^n$ and we are done.

Hence we may assume that $B_1 \cong \ldots \cong B_m \cong F$ (as Jordan algebras). Since I is nilpotent, by [14, Lemma 3, p. 149] any set of orthogonal idempotents can be lifted modulo I. Hence, since B_1, \ldots, B_m are unitary algebras, there exist m nonzero orthogonal idempotents e_1, \ldots, e_m in R.

Recall that

(10)
$$c_n^J(R) = \dim \frac{P_n^J}{P_n^J \cap Id(R)}$$

(see Section 5) and consider the structure of an S_n -module on $M = \frac{P_n^J}{P_n^J \cap Id(R)}$. By complete reducibility M decomposes into a finite sum of irreducible submodules and by [5, Theorem 1] the number of such submodules is a polynomially bounded function of n. Therefore in order to complete the proof we need only to estimate the dimension of an irreducible submodule of M.

First suppose that any multilinear Jordan monomial $m = m(x_1, \ldots, x_n)$ vanishes in R provided that two variables are evaluated in e_i and e_j , for some $i \neq j$. That is,

(11)
$$m(\underbrace{e_1,\ldots,e_1}_{p_1},\ldots,\underbrace{e_m,\ldots,e_m}_{p_m},a_1,\ldots,a_k)$$

is equal to 0 in R as soon as at least two among p_1, \ldots, p_m are nonzero, $a_1, \ldots, a_k \in I, k \geq 0$, and $p_1 + \cdots + p_m + k = n$. We shall prove that in this case, $c_n^J(R)$ is polynomially bounded.

Now we consider the embedding of A into its special universal envelope U. Then $I \subseteq rad(U)$ where rad(U) is the Jacobson radical of U.

Let $\lambda = (\lambda_1, \ldots, \lambda_r) \vdash n$ be such that $\lambda_2 + \cdots + \lambda_r \geq N$ where $rad(U)^N = 0$. For any multilinear polynomial $h = h(x_1, \ldots, x_n)$, the polynomial $\overline{C}_{T_\lambda}h$ contains λ_2 sets of alternating variables, each of order at least 2. When evaluating the variables in R, we must substitute either at least two distinct e_i 's or at least two equal e_i 's in an alternating set or at least N elements from I. In all cases the value of the polynomial is zero. It follows that

$$FS_n e_{T_\lambda} h \not\equiv 0$$

only if $\lambda_2 + \cdots + \lambda_r < N$. From the hook formula that gives the dimension of an irreducible FS_n -module (see [15]), it easily follows that dim $FS_n e_{T_{\lambda}}$ is bounded by a polynomial of degree N and the proof is complete in this case.

Now suppose that there exists a monomial $m(x_1, \ldots, x_n)$ with a nonzero evaluation (11), where at least two among p_1, \ldots, p_m are nonzero and $a_1, \ldots, a_k \in I$. In order to simplify the notation suppose $p_1 \neq 0, p_2 \neq 0$ and rename the variable so that $m = m(x_1, x_2, y_1, \ldots, y_t)$ and $m(e_1, e_2, \overline{y}_1, \ldots, \overline{y}_t) \neq 0$, for some $\overline{y}_1, \ldots, \overline{y}_t \in R$. Starting from m we shall now construct a polynomial in n pairs of alternating variables, for all n = 1, 2, ... In fact define

$$f = f(x_1, \dots, x_{2n+2}, y_1, \dots, y_t)$$

= $\sum_{\sigma_1, \dots, \sigma_n \in S_2} (\operatorname{sgn} \sigma_1) \cdots (\operatorname{sgn} \sigma_n)$
 $\times m(x_{\sigma_1(1)} \cdots x_{\sigma_n(n)} x_{2n+1}, x_{\sigma_1(n+1)} \cdots x_{\sigma_n(2n)} x_{2n+2}, y_1, \dots, y_t),$

where $\sigma_i \in S_2$ acts on the indices i, n + i. By evaluating

we get a sum of 2^n evaluated monomials corresponding to the distinct *n*-tuples of permutations $(\sigma_{i_1}, \ldots, \sigma_{i_n})$. If at least one σ_{i_j} is different from 1, then the value of the corresponding summand is zero since $e_1e_2 = 0$. Hence the only nonzero summand is $m(e_1^{n+1}, e_2^{n+1}, \bar{y}_1, \ldots, \bar{y}_t) = m(e_1, e_2, \bar{y}_1, \ldots, \bar{y}_t) \neq 0$ and f is not an identity of R. On the other hand, if we let S_{2n} act on P_{2n+t+2}^J by the permutation action only on the variables x_1, \ldots, x_{2n} , the complete linearization of f generates in P_{2n+t+2}^J an S_{2n} -module whose irreducible components correspond to the partition $\lambda = (n, n)$. Now, by the hook formula, for any $\mu \vdash 2n + t + 2$ such that $\mu \geq \lambda$ in the left lexicographic order, we have that $d_{\mu} \geq d_{\lambda}$. Hence, since asymptotically $d_{\lambda} \simeq C_0(2n)^{s}2^{2n}$ (see, for example [11, Lemma 6.2.5]), and t + 2 is constant, one can easily find constants C > 0 and q such that $c_n^J(R) \geq Cn^q 2^n$ for all n.

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