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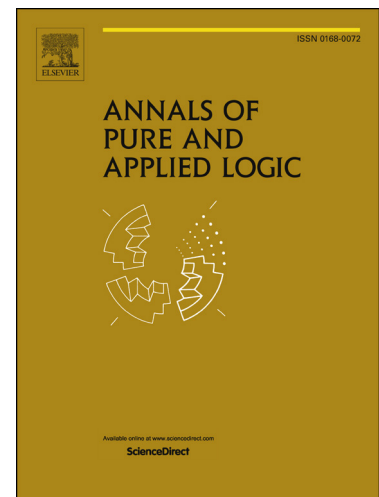
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Highlights

- Combining logic and coherence-based probability theory.
- Coherence-based probability semantics for Aristotelian syllogisms.
- New notions of validity of probabilistic syllogisms and probabilistic existential import assumptions.
- Probability propagation rules for categorical syllogisms of Figure I, II, and III.
- Applications and bridges to nonmonotonic reasoning.
- Analysis of the Aristotelian methods of proof by conversion and *reductio ad impossibile*.
- Generalized syllogisms involving intermediate quantifiers by suitable instantiations of probability propagation rules.

Probability propagation rules for Aristotelian syllogisms

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Abstract

We present a coherence-based probability semantics and probability propagation rules for (categorical) Aristotelian syllogisms. For framing the Aristotelian syllogisms as probabilistic inferences, we interpret basic syllogistic sentence types A, E, I, O by suitable precise and imprecise conditional probability assessments. Then, we define validity of probabilistic inferences and probabilistic notions of the existential import which is required, for the validity of the syllogisms. Based on a generalization of de Finetti's fundamental theorem to conditional probability, we investigate the coherent probability propagation rules of argument forms of the syllogistic Figures I, II, and III, respectively. These results allow to show, for all three figures, that each traditionally valid syllogism is also valid in our coherence-based probability semantics. Moreover, we interpret the basic syllogistic sentence types by suitable defaults and negated defaults. Thereby, we build a bridge from our probability semantics of Aristotelian syllogisms to nonmonotonic reasoning. Then we show that *reductio* by conversion does not work while *reductio ad impossibile* can be applied in our approach. Finally, we show how the proposed probability propagation rules can be used to analyze syllogisms involving generalized quantifiers (like *Most*).

Keywords: Conditional events, coherence, imprecise probability semantics, probabilistic syllogistics, nonmonotonic reasoning, generalized quantifiers.

2020 MSC: 03A05, 03B42, 03B48, 03C80, 60-08, 60A05

1. Motivation and outline.

There is a long tradition in logic to investigate categorical syllogisms that goes back to Aristotle's *Analytica Priora*. However, not many authors proposed *probability* semantics for categorical syllogisms (see, e.g., [2, 3, 14, 19, 20, 29, 31, 52, 44, 61, 88]) to overcome formal restrictions imposed by logic, like its *monotonicity* (i.e., the inability to retract conclusions in the light of new evidence) or its qualitative nature (i.e., the inability to express *degrees of belief*). In particular, *universally* and *existentially quantified* statements are hardly ever used in commonsense contexts: even if people mention words like "all" or "every", they usually don't mean *all* in the modern sense of the universal quantifier \forall . Indeed, universal quantified statements are usually not falsified by one exception in everyday life. Likewise, people mostly don't mean by "some" *at least one* in the sense of the existential quantifier \exists . Our aim is to provide a richer and more flexible framework for managing quantified statements in common sense reasoning. Specifically, our probabilistic approach is scalable in the sense that the proposed semantics allows for managing not only

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traditional logical quantifiers but also the much bigger superset of *generalized* or *intermediate quantifiers* (see, e.g., [5, 66, 67, 90]). Such a framework will also be useful as a rationality framework for the psychology of reasoning, which has a long tradition in investigating syllogisms (see, e.g., [87, 57, 71]). Finally, a further aim within our probabilistic approach is to build a bridge from ancient syllogisms to relatively recent approaches in nonmonotonic reasoning.

Among various approaches to probability, we use the subjective interpretation. Specifically, we use the theory of subjective probability based on the coherence principle of Bruno de Finetti (see, e.g., [25, 28]). This coherence principle has been investigated by many authors and it has been generalized to the conditional probability and to imprecise probability (see, e.g., [6, 10, 11, 16, 17, 22, 37, 41, 47, 44, 55, 60, 69, 78, 89]). The coherence principle plays a key role in probabilistic reasoning. Coherence is a flexible approach as it allows to assign conditional probability *directly* on an arbitrary family of conditional events—without requiring algebraic structures—and to propagate coherent probabilities to further conditional events. Moreover, coherence is more general than approaches which require positive probability for the conditioning events. In such approaches the conditional probability $p(E|H)$ is defined by the ratio $\frac{p(E \wedge H)}{p(H)}$, which requires positive probability of the conditioning event, $p(H) > 0$ (or by making *ad hoc* assumptions, like setting $p(E|H) = 1$, when $p(H) = 0$). However, in the coherence-based approach, conditional probability $p(E|H)$ is a *primitive* notion and it is properly defined and managed even if the conditioning event has probability zero, i.e., $p(H) = 0$. If E and H are logically independent, then, by coherence, $p(E|H)$ can take any value in the unit interval $[0, 1]$. Moreover, for any coherent p , the equation $p(E|H)p(H) = p(E \wedge H)$ follows as a *theorem (compound probability theorem)*. In particular, when $p(H) > 0$, of course coherence requires that $p(E|H) = \frac{p(E \wedge H)}{p(H)}$; however, when $p(H) = 0$, coherence requires that $p(E|H) \in [0, 1]$.

In the subjective approach to probability of de Finetti no algebraic structure of events is required. For each (conditional) event of interest, the uncertainty is directly evaluated in terms of a degree of belief, by means of coherent probability. This evaluation concerns only the (conditional) events of interest, without the necessity of evaluating degrees of belief of all events (possibly unrealistic many and irrelevant ones) of a presupposed suitable algebra. This approach is therefore more flexible, epistemically economic, and more realistic compared to the approaches which presuppose to give probability values to each element of the whole algebraic structure. Hence, as degrees of belief are primitive, conditional probabilities are also primitive. Moreover, any event E coincides with the conditional event $E|\Omega$ and hence the (unconditional) probability $p(E)$ coincides with the conditional probability $p(E|\Omega)$. Therefore, conditional probability is primitive in our approach and does not necessarily require a basis on unconditional probabilities.

For other axiomatic approaches to conditional probability which allow for such zero probabilities but which presuppose—differently from coherence—an algebraic structure see e.g., [24, 30, 75, 79, 80]. For a discussion of different axiomatic approaches and interpretations of conditional probability see [32]. We recall that a coherent assessment \mathcal{P} on an arbitrary family \mathcal{F} of conditional events—possibly without any algebraic structures—can always be extended as a full axiomatic (finitely additive) conditional probability p on $\mathcal{A} \times \mathcal{A}^0$, where \mathcal{A} is a Boolean algebra and $\mathcal{A}^0 = \mathcal{A} \setminus \{\perp\}$, such that, for all $E|H \in \mathcal{F}$, it holds that $E \in \mathcal{A}$, $H \in \mathcal{A}^0$, and $p(E|H) = \mathcal{P}(E|H)$ ([78]; see also [22, 55, 81]). Moreover, given a real-valued function p on $\mathcal{A} \times \mathcal{B}$, where \mathcal{A} is a Boolean algebra and \mathcal{B} is an arbitrary nonempty subset of \mathcal{A}^0 (meaning that no restrictions are made for the class of conditioning events \mathcal{B}), which satisfies the following properties of an axiomatic (finitely additive) conditional probability:

- (i) $p(\cdot|H)$ is a finitely additive probability on \mathcal{A} , for each $H \in \mathcal{B}$;
- (ii) $p(H|H) = 1$, for each $H \in \mathcal{B}$;
- (iii) $p(AB|H) = p(A|BH)p(B|H)$, for every A, B, H , with $A, B \in \mathcal{A}$ and $BH, H \in \mathcal{B}$,

Figure I (term order: $M-P, S-M, \text{therefore } S-P$)		
AAA	Barbara	<i>Every M is P, Every S is M, therefore Every S is P</i>
AAI*	Barbari	<i>Every M is P, Every S is M, therefore Some S is P</i>
AII	Darii	<i>Every M is P, Some S is M, therefore Some S is P</i>
EAE	Celarent	<i>No M is P, Every S is M, therefore No S is P</i>
EAO*	Celaront	<i>No M is P, Every S is M, therefore Some S is not P</i>
EIO	Ferio	<i>No M is P, Some S is M, therefore Some S is not P</i>
Figure II (term order: $P-M, S-M, \text{therefore } S-P$)		
AEE	Camestres	<i>Every P is M, No S is M, therefore No S is P</i>
AEO*	Camestrop	<i>Every P is M, No S is M, therefore Some S is not P</i>
AOO	Baroco	<i>Every P is M, Some S is not M, therefore Some S is not P</i>
EAE	Cesare	<i>No P is M, Every S is M, therefore No S is P</i>
EAO*	Cesaro	<i>No P is M, Every S is M, therefore Some S is not P</i>
EIO	Festino	<i>No P is M, Some S is M, therefore Some S is not P</i>
Figure III (term order: $M-P, M-S, \text{therefore } S-P$)		
AAI*	Darapti	<i>Every M is P, Every M is S, therefore Some S is P</i>
AII	Datisi	<i>Every M is P, Some M is S, therefore Some S is P</i>
IAI	Disamis	<i>Some M is P, Every M is S, therefore Some S is P</i>
EAO*	Felapton	<i>No M is P, Every M is S, therefore Some S is not P</i>
EIO	Ferison	<i>No M is P, Some M is S, therefore Some S is not P</i>
OAo	Bocardo	<i>Some M is not P, Every M is S, therefore Some S is not P</i>

Table 1: Traditional and logically valid Aristotelian syllogisms. * denotes syllogisms with implicit existential import assumptions.

then it could be that the function p is not coherent ([22, 40, 51]). However, Rigo ([81]) has shown that Császár's condition ([24], see also [42]) is necessary and sufficient for coherence of p on $\mathcal{A} \times \mathcal{B}$. Furthermore, a function $p : \mathcal{A} \times \mathcal{B}$ satisfying (i), (ii) and (iii), is coherent, when \mathcal{B} has a particular structure, for instance, if \mathcal{B} is additive ([22, 55]), or if \mathcal{B} is quasi-additive ([36, 82]).

In the present context dealing with zero probability antecedents will be important for analyzing the validity of the probabilistic syllogisms and for investigating probabilistic existential import assumptions. We also interpret the premise set of each syllogism as a suitable (precise/imprecise) conditional probability assessment on the respective sequence of conditional events (without presupposing particular algebraic structures). Specifically, we are interested in the probability propagation from the premise set to the conclusion. Coherence provides therefore tools to systematically investigate these aspects.

Traditional categorical syllogisms are valid argument forms consisting of two premises and a conclusion, which are composed of basic syllogistic sentence types (see, e.g., [70]): *Every a is b* (A), *No a is b* (E), *Some a is b* (I), and *Some a is not b* (O), where “a” and “b” denote two of the three categorical terms M (“middle term”), P (“predicate term”), or S (“subject term”). As an example of sentence type A consider *Every man is mortal*. The M term appears only in the premises and is combined with P in the first premise (“major premise”) and S in the second premise (“minor premise”). In the conclusion only the S term and the P term appear, traditionally in the fixed order $S-P$. By all possible permutations of the predicate order, four syllogistic figures result under the given restrictions. Following Aristotle's *Analytica Priora*, we will focus on the first three figures. Specifically, on the traditionally valid Aristotelian syllogisms of Figure I, II, and III (see Table 1). Consider (*Modus*) *Barbara*, which is a valid syllogism of Figure I: *Every M is P, Every S is M, therefore Every S is P*.

Type	Sentence	Probabilistic interpretation	Equivalent interpretation
(A)	<i>Every S is P</i>	$p(P S) = 1$	$p(\bar{P} S) = 0$
(E)	<i>No S is P (Every S is not P)</i>	$p(P S) = 0$	$p(\bar{P} S) = 1$
(I)	<i>Some S is P</i>	$p(P S) > 0$	$p(\bar{P} S) < 1$
(O)	<i>Some S is not P</i>	$p(\bar{P} S) > 0$	$p(P S) < 1$

Table 2: Probabilistic interpretations of the basic syllogistic sentence types based on $P|S$ and $\bar{P}|S$.

Note that some traditionally valid syllogisms require existential import assumption for the validity. For example, *Barbari* (*Every M is P, Every S is M, therefore Some S is P*) is valid under the assumption that the S term is not “empty” (in the sense that there is some S). The names of the syllogisms traditionally encode logical properties. For the present purpose, we only recall that vowels refer to the syllogistic sentence type: for instance, *Barbara* involves three sentences of type A, i.e., AAA (for details see, e.g., [70]).

In our approach we interpret the syllogistic terms as events. An event is conceived as a bi-valued logical entity which can be true or false. Moreover, we associate (ordered) pair of terms $S-P$ with the corresponding conditional event $P|S$, that is as a tri-valued logical object ([44]).

For giving a probabilistic interpretation of the premises and the conclusions of the syllogisms, we interpret basic syllogistic sentence types A, E, I, O by suitable imprecise conditional probability assessments. Specifically, we interpret the degree of belief in syllogistic sentence A by $p(P|S) = 1$, E by $p(P|S) = 0$, I by $p(P|S) > 0$, and we interpret O by $p(\bar{P}|S) > 0$ (Table 2; see also [19, 44]). Thus, A and E are interpreted as precise probability assessments and I and O by imprecise probability assessments. The basic logical relations among this interpretation of the syllogistic sentence types are analyzed in the probabilistic Square and in the probabilistic Hexagon of Opposition ([72, 73]).

Remark 1. We note that $p(P|S)$ does not constrain $p(S|P)$. Indeed, as we will show in Proposition 7, given two logically independent events S and P , the probability assessment (x, y) on $(P|S, S|P)$, where $x = p(P|S)$ and $y = p(S|P)$, is coherent for every $(x, y) \in [0, 1]^2$. Therefore, the interpretation of all the basic syllogistic sentence types in terms of conditional probabilities is not symmetric. For instance, $p(P|S) > 0$ does not constrain $p(S|P) > 0$, and hence *Some S is P* does not imply *Some P is S*. Moreover, the interpretation of (A), (E), (I), (O) in terms of the conditional probabilities is weaker than in terms of conjunction probabilities. For instance, the sentence type (I) interpreted by $p(S \wedge P) > 0$ implies $p(P|S) > 0$ but not vice versa. Indeed, as coherence requires that

$$p(S \wedge P) = p(P|S)p(S), \quad (1)$$

when $p(S \wedge P) > 0$, it must be that $p(P|S) > 0$. Concerning the converse, however, we recall that in the coherence approach, the assessment $p(P|S) = x$ and $p(S) = p(S \wedge P) = 0$ is coherent for every $x \in [0, 1]$, and in particular for $x > 0$ (in such a case equation (1) is satisfied by $0 = 0$, even if $p(P|S) > 0$). Hence, $p(P|S) > 0$ does not imply that $p(S \wedge P)$ is necessarily positive and therefore the conditional interpretation is weaker than the conjunction interpretation. Notice that, this asymmetry cannot be expressed in approaches which require positive probability for the conditioning events.¹

For framing the Aristotelian syllogisms as probabilistic inferences, we define validity of probabilistic inferences. We recall that in classical logic some Aristotelian syllogisms, like *Barbari*, require existential

¹This asymmetry is also not present in predicate logical interpretations of Aristotelian syllogisms (under appropriate existential import assumptions), since for example (I) can be equivalently expressed by “for at least one x : x is S and x is P ” and by “it is not the case that for all x : if x is S then x is not- P ”.

import assumptions for logical validity (marked by * in Table 1). In the present approach we require probabilistic versions of existential import assumptions for the validity of *all* traditionally valid syllogisms. For example, we do not only require an existential import assumption for syllogisms like Barbari but also for syllogisms like Barbara. Indeed, from the probabilistic premises of Barbari and Barbara, i.e., $p(P|M) = 1$ and $p(M|S) = 1$, we cannot validly infer the respective conclusion because only a non-informative conclusion can be obtained, i.e., every value of $p(P|S)$ in $[0, 1]$ is coherent. In order to validate the conclusions of Barbari and Barbara, that is $p(P|S) > 0$ and $p(P|S) = 1$, respectively, we add the probabilistic constraints $p(S|(S \vee M)) > 0$ as a probabilistic existential import assumption.

Based on a generalization of de Finetti's fundamental theorem to (precise and imprecise) conditional probability, we study the coherent probability propagation rules of argument forms of the syllogistic Figures I, II, and III. These results allow to show, for all three Figures, that each traditionally valid syllogism is also valid in our coherence-based probability semantics. Moreover, we build a bridge from our probability semantics of Aristotelian syllogisms to nonmonotonic reasoning by interpreting the basic syllogistic sentence types by suitable defaults (A: $S \sim P$, E: $S \sim \bar{P}$) and negated defaults (I: $S \not\sim \bar{P}$, O: $S \not\sim P$). We also show how the proposed semantics can be used to analyze syllogisms involving generalized quantifiers (like *most S are P*).

The paper is organized as follows. In Section 2 we recall preliminary notions and results on the coherence of conditional probability assessments and recall an algorithm for coherent probability propagation. In Section 3 we define *validity* and *strict validity* of probabilistic inferences and probabilistic notions of the existential import, which is required for the validity of the syllogisms. In sections 4, 5, and 6 we study the coherent probability propagation rules of argument forms of the syllogistic Figures I, II, and III, respectively. Then, we show for all three Figures that each traditionally valid syllogism is also valid in our coherence-based probability semantics. In Section 7 we build a bridge from our probability semantics of Aristotelian syllogisms to nonmonotonic reasoning by interpreting the basic syllogistic sentence types by suitable defaults and negated defaults. Then we discuss Aristotle's methods of proof: we show why *reductio* by *conversion* does not hold and to what extent *reductio ad impossibile* holds in our approach in Section 8. In Section 9 we show how the proposed probability propagation rules can be used to analyze syllogisms involving generalized quantifiers (like *Most*). Section 10 concludes the paper by a brief summary of the main results and by an outlook to future work.

2. Preliminary notions and results on coherence.

In this section we recall selected key features of coherence (for more details see, e.g., [9, 13, 22, 23, 46, 47, 69, 85]). We denote events (which can be true or false) and their indicators (which can be 1 or 0) by the same symbols (e.g., the indicator of the event E is denoted by the same symbol E). Given two events E and H , with $H \neq \perp$, the *conditional event* $E|H$ is defined as a three-valued logical entity which is *true* if EH (i.e., $E \wedge H$) is true, *false* if $\bar{E}H$ is true, and *void* if H is false.

Coherence and betting scheme. In betting terms, assessing $p(E|H) = x$ means that, for every real number s , you are willing to pay an amount $s \cdot x$ and to receive s , or 0, or $s \cdot x$, according to whether EH is true, or $\bar{E}H$ is true, or \bar{H} is true (i.e., the bet is called off), respectively. In these cases the random gain is $G = sH(E - x)$. More generally speaking, consider a real-valued function $p : \mathcal{K} \rightarrow \mathbb{R}$, where \mathcal{K} is an arbitrary (possibly not finite) family of conditional events. Let $\mathcal{F} = (E_1|H_1, \dots, E_n|H_n)$ be a sequence of n conditional events, where $E_j|H_j \in \mathcal{K}$, $j = 1, \dots, n$, and let $\mathcal{P} = (p_1, \dots, p_n)$ be the vector of values $p_j = p(E_j|H_j)$, where $j = 1, \dots, n$. We denote by \mathcal{H}_n the disjunction $H_1 \vee \dots \vee H_n$. With the pair $(\mathcal{F}, \mathcal{P})$ we associate the random gain $G = \sum_{j=1}^n s_j H_j (E_j - p_j)$, where s_1, \dots, s_n are n arbitrary real numbers. G represents the net gain of n

transactions. Let $\mathcal{G}_{\mathcal{H}_n}$ denote the set of possible values of G restricted to \mathcal{H}_n , that is, the values of G when at least one conditioning event is true (bet is not called off).

Definition 1. Function p defined on \mathcal{K} is coherent if and only if, for every integer n , for every sequence \mathcal{F} of n conditional events in \mathcal{K} and for every s_1, \dots, s_n , it holds that: $\min \mathcal{G}_{\mathcal{H}_n} \leq 0 \leq \max \mathcal{G}_{\mathcal{H}_n}$.

Intuitively, Definition 1 means in betting terms that a probability assessment is coherent if and only if, in any finite combination of n bets, it cannot happen that the values in $\mathcal{G}_{\mathcal{H}_n}$ —that is the values of the random gain by ignoring the cases where the bet is called off—are all positive, or all negative (*no Dutch Book*).

Geometrical interpretation of coherence. Coherence can also be characterized geometrically. Let $\mathcal{F} = (E_1|H_1, \dots, E_n|H_n)$. As $\Omega = E_j H_j \vee \bar{E}_j H_j \vee \bar{H}_j$, $j = 1, \dots, n$, it holds that $\Omega = \bigwedge_{j=1}^n (E_j H_j \vee \bar{E}_j H_j \vee \bar{H}_j)$. By applying the distributive property it follows that Ω can also be written as the disjunction of 3^n logical conjunctions, some of which may be impossible. The remaining ones are the constituents, generated by \mathcal{F} and, of course, form a partition of Ω . We denote by C_1, \dots, C_m the constituents contained in \mathcal{H}_n and (if $\mathcal{H}_n \neq \Omega$) by C_0 the remaining constituent $\bar{\mathcal{H}}_n = \bar{H}_1 \cdots \bar{H}_n$, so that

$$\mathcal{H}_n = C_1 \vee \cdots \vee C_m, \quad \Omega = \bar{\mathcal{H}}_n \vee \mathcal{H}_n = C_0 \vee C_1 \vee \cdots \vee C_m, \quad m+1 \leq 3^n.$$

Let $\mathcal{P} = (p_1, \dots, p_n)$, where $p_j = P(E_j|H_j)$, $j = 1, \dots, n$. For each constituent C_h , $h = 1, \dots, m$, we associate a point $Q_h = (q_{h1}, \dots, q_{hn})$, where $q_{hj} = 1$, or 0, or p_j , according to whether $C_h \subseteq E_j H_j$, or $C_h \subseteq \bar{E}_j H_j$, or $C_h \subseteq \bar{H}_j$. The point $Q_0 = \mathcal{P}$ is associated with C_0 . We say that the points Q_0, Q_1, \dots, Q_m are associated with the pair $(\mathcal{F}, \mathcal{P})$. For an instance on how the constituents and the associated points are generated we consider the following

Example 1. Let $\mathcal{F} = (E_1|H_1, E_2|H_2) = (C|B, B|A)$, where A, B, C are three logically independent events, and $\mathcal{P} = (p_1, p_2)$ be a probability assessment on \mathcal{F} . It holds that:

$$\Omega = (BC \vee B\bar{C} \vee \bar{B}) \wedge (AB \vee A\bar{B} \vee \bar{A}) = C_0 \vee C_1 \vee \cdots \vee C_5,$$

where the constituents are $C_1 = ABC$, $C_2 = \bar{A}BC$, $C_3 = ABC\bar{C}$, $C_4 = \bar{A}B\bar{C}$, $C_5 = A\bar{B}$, and $C_0 = \bar{A}\bar{B}$. We observe that $\mathcal{H}_2 = C_1 \vee \cdots \vee C_5 = A \vee B$. Moreover, the points $Q_1 = (1, 1)$, $Q_2 = (1, p_2)$, $Q_3 = (0, 1)$, $Q_4 = (0, p_2)$, $Q_5 = (p_1, 0)$, and $Q_0 = \mathcal{P} = (p_1, p_2)$ are associated with $(\mathcal{F}, \mathcal{P})$.

Denoting by \mathfrak{S} the convex hull of Q_1, \dots, Q_m , by a suitable alternative theorem (Theorem 2.9 in [35]), the condition $\mathcal{P} \in \mathfrak{S}$ is equivalent to the condition $\min \mathcal{G}_{\mathcal{H}_n} \leq 0 \leq \max \mathcal{G}_{\mathcal{H}_n}$ given in Definition 1 (see, e.g., [41, 47]). Moreover, the condition $\mathcal{P} \in \mathfrak{S}$ amounts to the solvability of the following system (\mathfrak{S}) in the unknowns $\lambda_1, \dots, \lambda_m$

$$(\mathfrak{S}) : \quad \sum_{h=1}^m q_{hj} \lambda_h = p_j, \quad j \in J_n; \quad \sum_{h=1}^m \lambda_h = 1; \quad \lambda_h \geq 0, \quad h \in J_m, \quad (2)$$

where, $J_n = \{1, 2, \dots, n\}$, for every integer n . We say that system (\mathfrak{S}) is associated with the pair $(\mathcal{F}, \mathcal{P})$. Hence, the following result provides a characterization of the notion of coherence given in Definition 1 (Theorem 4.4 in [37]; see also [38, 45, 47]).

Theorem 1. The function p defined on an arbitrary family of conditional events \mathcal{K} is coherent if and only if, for every finite subsequence $\mathcal{F} = (E_1|H_1, \dots, E_n|H_n)$ of \mathcal{K} , denoting by \mathcal{P} the vector (p_1, \dots, p_n) , where $p_j = p(E_j|H_j)$, $j = 1, 2, \dots, n$, the system (\mathfrak{S}) associated with the pair $(\mathcal{F}, \mathcal{P})$ is solvable.

Coherence checking. We recall now some results on the coherence checking of a probability assessment on a finite family of conditional events. Given a probability assessment $\mathcal{P} = (p_1, \dots, p_n)$ on $\mathcal{F} = (E_1|H_1, \dots, E_n|H_n)$, let \mathcal{S} be the set of solutions of the form $\Lambda = (\lambda_1, \dots, \lambda_m)$ of the system (\mathfrak{S}) . Then, assuming $\mathcal{S} \neq \emptyset$, we define

$$\begin{aligned} \Phi_j(\Lambda) &= \Phi_j(\lambda_1, \dots, \lambda_m) = \sum_{r: C_r \subseteq H_j} \lambda_r, \quad j \in J_n; \Lambda \in \mathcal{S}; \\ M_j &= \max_{\Lambda \in \mathcal{S}} \Phi_j(\Lambda), \quad j \in J_n, \end{aligned} \quad (3)$$

and

$$I_0 = \{j \in J_n : M_j = 0\}. \quad (4)$$

Assuming \mathcal{P} coherent, each solution $\Lambda = (\lambda_1, \dots, \lambda_m)$ of system (\mathfrak{S}) is a coherent extension of the assessment \mathcal{P} on \mathcal{F} to the sequence $(C_1|H_n, C_2|H_n, \dots, C_m|H_n)$. Then, for each solution Λ of system (\mathfrak{S}) the quantity $\Phi_j(\Lambda)$ is a coherent extension of the conditional probability $p(H_j|H_n)$. Moreover, the quantity M_j is the upper probability $p''(H_j|H_n)$ over all the solutions Λ of system (\mathfrak{S}) . Of course, $j \in I_0$ if and only if $p''(H_j|H_n) = 0$. Notice that I_0 is a strict subset of J_n . If I_0 is nonempty, we set $\mathcal{F}_0 = (E_i|H_i \in \mathcal{F}, i \in I_0)$ and $\mathcal{P}_0 = (p(E_i|H_i), i \in I_0)$. We say that the pair $(\mathcal{F}_0, \mathcal{P}_0)$ is associated with I_0 . Then, we have (Theorem 3.3 in [39]):

Theorem 2. *The assessment \mathcal{P} on \mathcal{F} is coherent if and only if the following conditions are satisfied: (i) the system (\mathfrak{S}) associated with the pair $(\mathcal{F}, \mathcal{P})$ is solvable; (ii) if $I_0 \neq \emptyset$, then \mathcal{P}_0 is coherent.*

Let \mathcal{S}' be a nonempty subset of the set of solutions \mathcal{S} of system (\mathfrak{S}) . We denote by I'_0 the set I_0 defined as in (4), where \mathcal{S} is replaced by \mathcal{S}' , that is

$$I'_0 = \{j \in J_n : M'_j = 0\}, \text{ where } M'_j = \max_{\Lambda \in \mathcal{S}'} \Phi_j(\Lambda), \quad j \in J_n. \quad (5)$$

Moreover, we denote by $(\mathcal{F}'_0, \mathcal{P}'_0)$ the pair associated with I'_0 . Then, we obtain (see, e.g., Theorem 7 in [12])

Theorem 3. *The assessment \mathcal{P} on \mathcal{F} is coherent if and only if the following conditions are satisfied: (i) the system (\mathfrak{S}) associated with the pair $(\mathcal{F}, \mathcal{P})$ is solvable; (ii) if $I'_0 \neq \emptyset$, then \mathcal{P}'_0 is coherent.*

For an illustration of Theorem 3 we consider

Example 1 (continued). We observe that $\mathcal{P} = (p_1, p_2) = p_1 Q_2 + (1 - p_1) Q_4$ and $\mathcal{P} = p_1 p_2 Q_1 + (1 - p_1) p_2 Q_3 + (1 - p_2) Q_5$. Then, $\mathcal{P} = \frac{1}{2}(p_1 p_2 Q_1 + p_1 Q_2 + (1 - p_1) p_2 Q_3 + (1 - p_1) Q_4 + (1 - p_2) Q_5)$. By assuming that $(p_1, p_2) \in [0, 1]^2$, it follows that the system (\mathfrak{S}) associated with $(\mathcal{F}, \mathcal{P})$ is solvable with a solution given by $\Lambda = \frac{1}{2}(p_1 p_2, p_1, (1 - p_1) p_2, (1 - p_1), (1 - p_2))$. Moreover, $\Phi_1(\Lambda) = \lambda_1 + \lambda_2 + \lambda_3 + \lambda_4 = \frac{p_2}{2} + \frac{1}{2} > 0$ and $\Phi_2(\Lambda) = \lambda_1 + \lambda_3 + \lambda_5 = \frac{p_1 p_2}{2} + \frac{(1 - p_1) p_2}{2} + \frac{1 - p_2}{2} = \frac{1}{2} > 0$. Then, by setting $\mathcal{S}' = \{\Lambda\}$ it holds that $M'_1 > 0$, $M'_2 > 0$ and hence $I'_0 = \emptyset$. Thus, by Theorem 3 the assessment (p_1, p_2) is coherent for every $(p_1, p_2) \in [0, 1]^2$.

Algorithm for probability propagation. We recall the following extension theorem for conditional probability, which is a generalization of de Finetti's fundamental theorem of probability to conditional events (see, e.g., [9, 21, 55, 65, 78, 91]).

Theorem 4. *Let a coherent probability assessment $\mathcal{P} = (p_1, \dots, p_n)$ on a sequence $\mathcal{F} = (E_1|H_1, \dots, E_n|H_n)$ and a further conditional event $E_{n+1}|H_{n+1}$ be given. Then, there exists a suitable closed interval $[z', z''] \subseteq [0, 1]$ such that the extension (\mathcal{P}, z) of \mathcal{P} to $(\mathcal{F}, E_{n+1}|H_{n+1})$ is coherent if and only if $z \in [z', z'']$.*

Theorem 4 states that a coherent assessment of premises can always be coherently extended to a conclusion, specifically there always exists an interval $[z', z''] \subseteq [0, 1]$ of all coherent extensions on the conclusion. A non informative or illusory restriction is obtained when $[z', z''] = [0, 1]$. The extension is unique when $z' = z''$. For applying Theorem 4, we now recall an algorithm (see Algorithm 1 in [44], which is originally based on Algorithm 2 in [9]) which allows for computing the lower and upper bounds z' and z'' of the interval of all coherent extensions on $E_{n+1}|H_{n+1}$.

Algorithm 1. Let $\mathcal{F} = (E_1|H_1, \dots, E_n|H_n)$ be a sequence of conditional events and $\mathcal{P} = (p_1, \dots, p_n)$ be a coherent precise probability assessment on \mathcal{F} , where $p_j = p(E_j|H_j) \in [0, 1]$, $j = 1, \dots, n$. Moreover, let $E_{n+1}|H_{n+1}$ be a further conditional event and denote by J_{n+1} the set $\{1, \dots, n+1\}$. The steps below describe the computation of the lower bound z' (resp., the upper bound z'') for the coherent extensions $z = p(E_{n+1}|H_{n+1})$.

- **Step 0.** Expand the expression $\bigwedge_{j \in J_{n+1}} (E_j H_j \vee \bar{E}_j H_j \vee \bar{H}_j)$ and denote by C_1, \dots, C_m the constituents contained in $\mathcal{H}_{n+1} = \bigvee_{j \in J_{n+1}} H_j$ associated with $(\mathcal{F}, E_{n+1}|H_{n+1})$. Then, construct the following system in the unknowns $\lambda_1, \dots, \lambda_m, z$

$$\begin{cases} \sum_{r: C_r \subseteq E_{n+1} H_{n+1}} \lambda_r = z \sum_{r: C_r \subseteq H_{n+1}} \lambda_r ; \\ \sum_{r: C_r \subseteq E_j H_j} \lambda_r = p_j \sum_{r: C_r \subseteq H_j} \lambda_r, \quad j \in J_n ; \\ \sum_{r \in J_m} \lambda_r = 1; \quad \lambda_r \geq 0, \quad r \in J_m . \end{cases} \quad (6)$$

- **Step 1.** Check the solvability of system (6) under the condition $z = 0$ (resp., $z = 1$). If it is not solvable, go to Step 2; otherwise, go to Step 3.
- **Step 2.** Solve the following linear programming problem

$$\text{Compute :} \quad \gamma' = \min \sum_{r: C_r \subseteq E_{n+1} H_{n+1}} \lambda_r$$

$$\text{(respectively :} \quad \gamma'' = \max \sum_{r: C_r \subseteq E_{n+1} H_{n+1}} \lambda_r \text{)}$$

subject to:

$$\begin{cases} \sum_{r: C_r \subseteq E_j H_j} \lambda_r = p_j \sum_{r: C_r \subseteq H_j} \lambda_r, \quad j \in J_n ; \\ \sum_{r: C_r \subseteq H_{n+1}} \lambda_r = 1; \quad \lambda_r \geq 0, \quad r \in J_m . \end{cases}$$

The minimum γ' (respectively the maximum γ'') of the *objective function* coincides with z' (respectively with z'') and the procedure stops.

- **Step 3.** For each subscript $j \in J_{n+1}$, compute the maximum M_j of the function $\Phi_j = \sum_{r: C_r \subseteq H_j} \lambda_r$, subject to the constraints given by the system (6) with $z = 0$ (respectively $z = 1$). We have the following three cases:
 1. $M_{n+1} > 0$;
 2. $M_{n+1} = 0$, $M_j > 0$ for every $j \neq n+1$;
 3. $M_j = 0$ for $j \in I_0 = J \cup \{n+1\}$, with $J \neq \emptyset$.

In the first two cases $z' = 0$ (respectively $z'' = 1$) and the procedure stops.

In the third case, defining $I_0 = J \cup \{n+1\}$, set $J_{n+1} = I_0$ and $(\mathcal{F}, \mathcal{P}) = (\mathcal{F}_J, \mathcal{P}_J)$, where $\mathcal{F}_J = (E_i|H_i : i \in J)$ and $\mathcal{P}_J = (p_i : i \in J)$. Then, go to Step 0.

The procedure ends in a finite number of cycles by computing the value z' (respectively z'').

Remark 2. Assuming (\mathcal{P}, z) on $(\mathcal{F}, E_{n+1}|H_{n+1})$ coherent, each solution $\Lambda = (\lambda_1, \dots, \lambda_m)$ of System (6) is a coherent extension of the assessment (\mathcal{P}, z) to the sequence $(C_1|\mathcal{H}_{n+1}, \dots, C_m|\mathcal{H}_{n+1})$.

For a software implementation of an algorithm based on [18, 22], which is similar to Algorithm 1, see the *Check-Coherence software* ([4]).

Imprecise probability. Now, we recall the notion of an imprecise (probability) assessment in set-valued terms.

Definition 2. An imprecise, or set-valued, assessment \mathcal{I} on a finite sequence of n conditional events \mathcal{F} is a (possibly empty) set of precise assessments \mathcal{P} on \mathcal{F} .

Definition 2, introduced in [43], states that an *imprecise (probability) assessment* \mathcal{I} on a finite sequence \mathcal{F} of n conditional events is just a (possibly empty) subset of $[0, 1]^n$. If an imprecise assessment \mathcal{I} on \mathcal{F} , with $\mathcal{I} = \mathcal{I}_1 \times \dots \times \mathcal{I}_n$, where $\mathcal{I}_i \subseteq [0, 1]$, $i = 1, \dots, n$, then \mathcal{I} on \mathcal{F} can be formulated in terms of constraints on the probability of the single events in \mathcal{F} , i.e.,

$$(p(E_1|H_1) \in \mathcal{I}_1, \dots, p(E_n|H_n) \in \mathcal{I}_n). \quad (7)$$

We recall the notions of g-coherence and total-coherence for imprecise (in the sense of set-valued) probability assessments ([43, 44]).

Definition 3. Let a sequence of n conditional events \mathcal{F} be given. An imprecise assessment $\mathcal{I} \subseteq [0, 1]^n$ on \mathcal{F} is g-coherent if and only if there exists a coherent precise assessment \mathcal{P} on \mathcal{F} such that $\mathcal{P} \in \mathcal{I}$.

Definition 4. An imprecise assessment \mathcal{I} on \mathcal{F} is totally coherent (t-coherent) if and only if the following two conditions are satisfied: (i) \mathcal{I} is non-empty; (ii) if $\mathcal{P} \in \mathcal{I}$, then \mathcal{P} is a coherent precise assessment on \mathcal{F} .

We denote by Π the set of all coherent precise assessments on \mathcal{F} . We recall that if there are no logical relations among the events $E_1, H_1, \dots, E_n, H_n$ involved in \mathcal{F} , that is $E_1, H_1, \dots, E_n, H_n$ are logically independent, then the set Π associated with \mathcal{F} is the whole unit hypercube $[0, 1]^n$. If there are logical relations, then the set Π could be a strict subset of $[0, 1]^n$. As it is well known $\Pi \neq \emptyset$; therefore, $\emptyset \neq \Pi \subseteq [0, 1]^n$.

Remark 3. We observe that:

$$\begin{aligned} \mathcal{I} \text{ is g-coherent} &\iff \Pi \cap \mathcal{I} \neq \emptyset \\ \mathcal{I} \text{ is t-coherent} &\iff \emptyset \neq \Pi \cap \mathcal{I} = \mathcal{I}. \end{aligned}$$

Then: \mathcal{I} is t-coherent \Rightarrow \mathcal{I} is g-coherent.

Definition 5. Let \mathcal{I} be a g-coherent assessment on $\mathcal{F} = (E_1|H_1, \dots, E_n|H_n)$; moreover, let $E_{n+1}|H_{n+1}$ be a further conditional event and let \mathcal{J} be an extension of \mathcal{I} to $(\mathcal{F}, E_{n+1}|H_{n+1})$. We say that \mathcal{J} is a g-coherent extension of \mathcal{I} if and only if \mathcal{J} is g-coherent.

Given a g-coherent assessment \mathcal{I} on a sequence of n conditional events \mathcal{F} , for each coherent precise assessment \mathcal{P} on \mathcal{F} , with $\mathcal{P} \in \mathcal{I}$, we denote by $[\alpha_{\mathcal{P}}, \beta_{\mathcal{P}}]$ the interval of coherent extensions of \mathcal{P} to $E_{n+1}|H_{n+1}$; that is, the assessment (\mathcal{P}, z) on $(\mathcal{F}, E_{n+1}|H_{n+1})$ is coherent if and only if $z \in [z'_{\mathcal{P}}, z''_{\mathcal{P}}]$. Then, defining the set

$$\Sigma = \bigcup_{\mathcal{P} \in \Pi \cap \mathcal{I}} [z'_{\mathcal{P}}, z''_{\mathcal{P}}], \quad (8)$$

for every $z \in \Sigma$, the assessment $\mathcal{I} \times \{z\}$ is a g-coherent extension of \mathcal{I} to $(\mathcal{F}, E_{n+1}|H_{n+1})$; moreover, for every $z \in [0, 1] \setminus \Sigma$, the extension $\mathcal{I} \times \{z\}$ of \mathcal{I} to $(\mathcal{F}, E_{n+1}|H_{n+1})$ is not g-coherent. We say that Σ is the set of (all) coherent extensions of the imprecise assessment \mathcal{I} on \mathcal{F} to the conditional event $E_{n+1}|H_{n+1}$. Of course, as \mathcal{I} is g-coherent, $\Sigma \neq \emptyset$.

Coherence and penalty criterion. We recall that de Finetti ([26, 27, 28]) introduced the notion of coherence (for the case of unconditional events) by means of a penalty criterion based on the Brier quadratic scoring rule ([15]), which is beyond the betting scheme (for a discussion on these two different justifications of probabilistic accounts of belief see, e.g., [56]). De Finetti also gave a geometrical interpretation of coherence and showed that the notion of coherence based on the betting scheme is equivalent to the notion of coherence based on the penalty criterion ([28]). The relationship between the notions of coherence and of *non-dominance*, with respect to proper scoring rules, for the case of unconditional events has been investigated by exploiting the Bregman divergence in [76]. For related work in terms of accuracy and credence functions see, e.g., [68]. Coherence based on the penalty criterion has been extended to the case of conditional events in [37] (see also [41, 50]) as follows. Let the assessment $\mathcal{P} = (p_1, \dots, p_n)$ on $\mathcal{F} = \{E_1|H_1, \dots, E_n|H_n\}$ be associated with a random loss $\mathcal{L} = \sum_{i=1}^n H_i(E_i - p_i)^2$ (Brier score adapted to conditional events). Then, the value L_h of the random loss \mathcal{L} when the constituent C_h is true is given by

$$L_h = \sum_{i=1}^n (q_{hi} - p_i)^2,$$

where $Q_h = (q_{h1}, \dots, q_{hn})$ is the corresponding point associated with C_h . Of course, $L_0 = \sum_{i=1}^n (p_i - p_i)^2 = 0$ is associated with the constituent $C_0 = \bar{H}_1 \cdots \bar{H}_n$, which means that the loss is zero when all the conditional events are void. Then, the following definition of coherence can be given:

Definition 6. A function p defined on an arbitrary family of conditional events \mathcal{K} is said to be coherent if and only if, for every integer n , for every subfamily $\mathcal{F} = \{E_1|H_1, \dots, E_n|H_n\} \subseteq \mathcal{K}$, denoting by $\mathcal{P} = (p_1, \dots, p_n)$ the restriction of p to \mathcal{F} , by $\mathcal{L} = \sum_{i=1}^n H_i(E_i - p_i)^2$ the associated random loss, there does not exist $\mathcal{P}^* = (p_1^*, \dots, p_n^*)$ such that: $\mathcal{L}^* \leq \mathcal{L}$ and $\mathcal{L}^* \neq \mathcal{L}$, that is $L_h^* \leq L_h$, for every h , with $L_h^* < L_h$ for at least an index h .

In [37] it has been shown that coherence based on the betting scheme (Definition 1) and coherence based on the penalty criterion (Definition 6) are equivalent (see also [41, 50]). In other words, a function p on \mathcal{K} is coherent according to Definition 1 if and only if p on \mathcal{K} is coherent according to Definition 6. We also recall that, based on Bregman divergences, coherence for conditional events can be characterized in terms of admissibility with respect to any given proper scoring rule. More precisely, in [45, Theorem 3] (see also [13]) it is shown that, given any bounded (strictly) proper scoring rule s , a probability assessment p on a family of conditional events \mathcal{K} is coherent if and only if it is *admissible* with respect to s .

3. Validity and existential import.

We define the validity of a probabilistic inference rule as follows:

Definition 7. Given a g -coherent assessment \mathcal{I} on a sequence of n conditional events \mathcal{F} and a non-empty imprecise assessment \mathcal{I}' on a conditional event $E_{n+1}|H_{n+1}$, we say that the (probabilistic) inference

$$\text{from } \mathcal{I} \text{ on } \mathcal{F} \text{ infer } \mathcal{I}' \text{ on } E_{n+1}|H_{n+1}$$

is valid (denoted by \models) if and only if $\Sigma \subseteq \mathcal{I}'$, where Σ is the set of coherent extensions of the imprecise assessment \mathcal{I} on \mathcal{F} . Moreover, we call a valid inference strictly valid (s -valid, denoted by \models_s) if and only if $\mathcal{I}' = \Sigma$.

Remark 4. Let from \mathcal{I} on \mathcal{F} infer \mathcal{I}' on $E_{n+1}|H_{n+1}$ be a valid inference, let \mathcal{I}_s be a g-coherent subset of \mathcal{I} , and let \mathcal{I}_w be a superset of \mathcal{I}' . Denoting by Σ_s the set of coherent extensions of the imprecise assessment \mathcal{I}_s , we observe that $\emptyset \neq \Sigma_s \subseteq \Sigma$. Then, by Definition 7, the following inference is valid

$$\text{from } \mathcal{I}_s \text{ on } \mathcal{F} \text{ infer } \mathcal{I}'_w \text{ on } E_{n+1}|H_{n+1}.$$

Thus, by starting from a valid inference we obtain valid inferences if the premises are strengthened or the conclusion is weakened.

In the next remark we explain how Adams' notion of p-validity ([1]) is interpreted in the framework of coherence and how it relates to our notion of s-validity.

Remark 5. We recall that a finite sequence of conditional events $\mathcal{F} = (E_1|H_1, E_2|H_2, \dots, E_n|H_n)$ is p-consistent if and only if the assessment $(1, 1, \dots, 1)$ on \mathcal{F} is coherent. In addition, a p-consistent family \mathcal{F} p-entails a conditional event $E_{n+1}|H_{n+1}$ if and only if the unique coherent extension on $E_{n+1}|H_{n+1}$ of the assessment $(1, 1, \dots, 1)$ on \mathcal{F} is $p(E_{n+1}|H_{n+1}) = 1$ (see, e.g., [46]). The inference from \mathcal{F} to $E_{n+1}|H_{n+1}$ is p-valid if and only if \mathcal{F} p-entails $E_{n+1}|H_{n+1}$. We observe that p-valid inferences are special cases of s-valid inferences, specifically when, in Definition 7, $\mathcal{I} = (1, 1, \dots, 1)$ and $\mathcal{I}' = \{1\}$.

Definition 8. The conditional event existential import assumption is defined by assuming that the conditional probability of the conditioning event of the minor premise of a syllogism given the disjunction of all conditioning events of the syllogism is positive.

For Datisi, the conditional event existential import assumption is $p(M|(S \vee M)) > 0$, which makes Datisi probabilistically informative:

$$\text{(Datisi)} \quad p(P|M) = 1, \quad p(S|M) > 0, \quad \text{and} \quad p(M|S \vee M) > 0 \implies p(P|S) > 0.$$

We will also consider the following

Definition 9. The unconditional event existential import assumption is defined by assuming that the probability of the conditioning event of the minor premise is positive.

For example, for Datisi, the unconditional event existential import assumption is $p(M) > 0$. In the next remark we observe that Definition 9 is stronger than Definition 8, and hence for Datisi it means that $p(M) > 0$ implies that $p(M|S \vee M) > 0$ (but not vice versa).

Remark 6. Let H_1, H_2 , and H_3 (where some of them may coincide) denote the conditioning event of the major premise, the minor premise, and of the conclusion, respectively. Then, the unconditional event existential import assumption is $p(H_2) > 0$ while the conditional event existential import assumption is $p(H_2|(H_1 \vee H_2 \vee H_3)) > 0$. We observe that in general $p(H_2) = p(H_2 \wedge (H_1 \vee H_2 \vee H_3)) = p(H_2|(H_1 \vee H_2 \vee H_3))p(H_1 \vee H_2 \vee H_3)$. Then,

$$p(H_2) > 0 \implies p(H_2|(H_1 \vee H_2 \vee H_3)) > 0. \tag{9}$$

However, the converse of (9) does not hold. Indeed, in the framework of coherence it could be that $p(H_2) = 0$ even if $p(H_2|(H_1 \vee H_2 \vee H_3)) > 0$, because $p(H_2|(H_1 \vee H_2 \vee H_3)) > 0$, $p(H_1 \vee H_2 \vee H_3) = 0$, and $p(H_2) = 0$ is coherent. Therefore, Definition 9 is stronger than Definition 8.

Remark 7. We are aware that it is not straightforward to find a natural language pendent to our conditional event existential import assumption, while the stronger unconditional event existential import assumption can be seen as a reading of the assumption that the subject term S must not be empty. However, we recall that in our approach we can have that $p(S|S \vee P) > 0$ even if $p(S) = 0$ (Remark 6). This situation cannot be represented in purely logical terms and hence there is no corresponding interpretation of the weaker existential import assumption. Moreover, we will see that, in order to prove the validity of the traditionally valid syllogisms, it is sufficient to use the conditional event existential import assumption. We also recall that it is traditionally at least tacitly assumed that the subject term must not be empty in Aristotelian syllogistics (for example, in his overview on Aristotle's logic, Smith claims that "Aristotle in effect supposes that all terms in syllogisms are non-empty" [86]). However, we note that there are also arguments that challenge this view, i.e., Aristotle in fact "places no requirement that the terms be non-empty" [77, p. 543]. We leave the question of whether our interpretation of the our existential import comes closer to Aristotle than stronger ones to historians of logic.

Remark 8. We define the conditional event existential import assumption by considering the conditioning events of all the conditional events involved in the premises and the conclusion. Single syllogistic sentences are interpreted by suitable probability assessments on a corresponding conditional events. For example, Every S is P by $p(P|S) = 1$. The corresponding conditional event existential import is $p(S|S) > 0$. For all $S \neq \perp$ our existential import is always satisfied because coherence requires that $p(S|S)$ must be 1, even if $p(S) = 0$. Indeed, it can easily be proved that the assessment (x, y) on $(S, S|S)$, with $S \neq \perp$, is coherent if and only if $x \in [0, 1]$ and $y = 1$. We also notice that in this case the equation $p(S) = p(S \wedge S) = p(S|S)p(S)$ is always satisfied. Sentences where the conditioning event S is a contradiction, i.e. $S = \perp$, are not considered because the corresponding conditional event is undefined in our approach.

4. Figure I.

In this section, we prove that the probabilistic inference of $C|A$ from the premise set $(C|B, B|A)$, which corresponds to the transitive structure of the general form of syllogisms of Figure I, is probabilistically non-informative. Specifically, we prove that the imprecise assessment $[0, 1]^3$ on $(C|B, B|A, C|A)$ is t-coherent. This t-coherence implies that: (i) the assessment $[0, 1]^2$ on $(C|B, B|A)$ is t-coherent, which means that any assessment $(x, y) \in [0, 1]^2$ on the premise set $(C|B, B|A)$ is coherent; (ii) the degree of belief in the conclusion $C|A$ is not constrained by the degrees of belief in the premises, since any value $z \in [0, 1]$ is a coherent extension of a given pair (x, y) on $(C|B, B|A)$. Then, in order to obtain probabilistic informativeness, we add the probabilistic constraint $p(B|(A \vee B)) > 0$ to the premise set. This constraint serves as the conditional event existential import assumption of syllogisms of Figure I according to Definition 8. We show that the imprecise assessment $[0, 1]^3$ on $(C|B, B|A, B|(A \vee B))$ is t-coherent. Then, we recall the precise and imprecise probability propagation rules for the inference from $(C|B, A|B, B|(A \vee B))$ to $C|A$. We apply these results in Section 4.2, where we study the valid syllogisms of Figure I. Contrary to first order monadic predicate logic, which requires existential import assumptions for Barbari and Celaront only (see Table 1), our probabilistic existential import assumption is required for all valid syllogisms of Figure I.

4.1. Coherence and probability propagation in Figure I.

We now prove the t-coherence of the imprecise assessment $[0, 1]^3$ on the sequence of conditional events involved in our probabilistic interpretation of syllogisms of Figure I.

Proposition 1. Let A, B, C be logically independent events. The imprecise assessment $[0, 1]^3$ on $\mathcal{F} = (C|B, B|A, C|A)$ is t-coherent.

Proof. Let $\mathcal{P} = (x, y, t) \in [0, 1]^3$ be any precise assessment on \mathcal{F} . The constituents C_h and the points Q_h associated with $(\mathcal{F}, \mathcal{P})$ are given in Table 3. By Theorem 2, coherence of \mathcal{P} on \mathcal{F} requires that the following

Table 3: Constituents C_h and points Q_h associated with the probability assessment $\mathcal{P} = (x, y, z)$ on $(C|B, B|A, C|A)$ involved in Figure I.

	C_h	Q_h	
C_1	ABC	$(1, 1, 1)$	Q_1
C_2	$ABC\bar{C}$	$(0, 1, 0)$	Q_2
C_3	$A\bar{B}C$	$(x, 0, 1)$	Q_3
C_4	$A\bar{B}\bar{C}$	$(x, 0, 0)$	Q_4
C_5	$\bar{A}BC$	$(1, y, z)$	Q_5
C_6	$\bar{A}B\bar{C}$	$(0, y, z)$	Q_6
C_0	$\bar{A}\bar{B}$	(x, y, z)	$Q_0 = \mathcal{P}$

system

$$(\mathfrak{S}) \quad \mathcal{P} = \sum_{h=1}^6 \lambda_h Q_h, \quad \sum_{h=1}^6 \lambda_h = 1, \quad \lambda_h \geq 0, \quad h = 1, \dots, 6.$$

is solvable. In geometrical terms, this means that the condition $\mathcal{P} \in \mathfrak{S}$ is satisfied, where \mathfrak{S} is the convex hull of Q_1, \dots, Q_6 . We observe that $\mathcal{P} = xQ_5 + (1-x)Q_6$, indeed it holds that $(x, y, z) = x(1, y, z) + (1-x)(0, y, z)$. Thus, system (\mathfrak{S}) is solvable and a solution is $\Lambda = (\lambda_1, \dots, \lambda_6) = (0, 0, 0, 0, x, 1-x)$. From (3) we obtain that $\Phi_1(\Lambda) = \sum_{h:C_h \subseteq B} \lambda_h = \lambda_1 + \lambda_2 + \lambda_5 + \lambda_6 = x + 1 - x = 1$, $\Phi_2(\Lambda) = \Phi_3(\Lambda) = \sum_{h:C_h \subseteq A} \lambda_h = \lambda_1 + \lambda_2 + \lambda_3 + \lambda_4 = 0$. Let $\mathcal{S}' = \{(0, 0, 0, 0, x, 1-x)\}$ denote a subset of the set \mathcal{S} of all solutions of (\mathfrak{S}) . Then, $M'_1 = \max\{\Phi_1 : \Lambda \in \mathcal{S}'\} > 0$ and hence $I'_0 = \{2, 3\}$ (as defined in (5)). By Theorem 3, as (\mathfrak{S}) is solvable and $I'_0 = \{2, 3\}$, it is sufficient to check the coherence of the sub-assessment $\mathcal{P}'_0 = (y, z)$ on $\mathcal{F}'_0 = (B|A, C|A)$ in order to check the coherence of (x, y, z) . The constituents C_h associated with the new pair $((B|A, C|A), (y, z))$ contained in $\mathcal{H}_2 = A$ are $C_1 = ABC, C_2 = ABC\bar{C}, C_3 = A\bar{B}C, C_4 = A\bar{B}\bar{C}$ and the corresponding points Q_h are $Q_1 = (1, 1), Q_2 = (1, 0), Q_3 = (0, 1), Q_4 = (0, 0)$. The convex hull \mathfrak{S} of the points Q_1, Q_2, Q_3, Q_4 is the unit square $[0, 1]^2$. Then $(y, z) \in [0, 1]^2$ trivially belongs to \mathfrak{S} and hence the system

$$(\mathfrak{S}) : (y, z) = \lambda_1 Q_1 + \lambda_2 Q_2 + \lambda_3 Q_3 + \lambda_4 Q_4, \quad \lambda_1 + \lambda_2 + \lambda_3 + \lambda_4 = 1, \quad \lambda_h \geq 0,$$

is solvable. Moreover, as $\Phi_1(\Lambda) = \Phi_2(\Lambda) = \sum_{h:C_h \subseteq A} \lambda_h = \lambda_1 + \lambda_2 + \lambda_3 + \lambda_4 = 1$, for every solution Λ of (\mathfrak{S}) , it follows that (the new) I_0 (as defined in (4)) is empty and, by Theorem 2, (y, z) is coherent. Then, $\mathcal{P} = (x, y, z)$ is coherent. Therefore, as any precise probability assessment $\mathcal{P} = (x, y, t) \in [0, 1]^3$ on \mathcal{F} is coherent, it follows that the imprecise assessment $\mathcal{I} = [0, 1]^3$ on \mathcal{F} is t-coherent. \square

We now prove the t-coherence of the imprecise assessment $[0, 1]^3$ on the sequence of conditional events $(C|B, B|A, A|(A \vee B))$. This sequence is involved in our probabilistic interpretation of the premise set of Figure I and includes the conditional event used in our existential import assumption.

Proposition 2. *Let A, B, C be logically independent events. The imprecise assessment $[0, 1]^3$ on $\mathcal{F} = (C|B, B|A, A|(A \vee B))$ is t-coherent.*

Proof. Let $\mathcal{P} = (x, y, t) \in [0, 1]^3$ be a probability assessment on \mathcal{F} . The constituents C_h and the points Q_h associated with $(\mathcal{F}, \mathcal{P})$ are given in Table 4. By Theorem 2, coherence of $\mathcal{P} = (x, y, z)$ on \mathcal{F} requires that the following system is solvable

$$(\mathfrak{S}) \quad \mathcal{P} = \sum_{h=1}^6 \lambda_h Q_h, \quad \sum_{h=1}^6 \lambda_h = 1, \quad \lambda_h \geq 0, \quad h = 1, \dots, 6,$$

Table 4: Constituents C_h and points Q_h associated with the probability assessment $\mathcal{P} = (x, y, t)$ on $(C|B, B|A, A|(A \vee B))$ involved in the premise set of Figure I.

	C_h	Q_h	
C_1	ABC	$(1, 1, 1)$	Q_1
C_2	$ABC\bar{C}$	$(0, 1, 1)$	Q_2
C_3	$A\bar{B}C$	$(x, 0, 1)$	Q_3
C_4	$A\bar{B}\bar{C}$	$(x, 0, 1)$	Q_4
C_5	$\bar{A}BC$	$(1, y, 0)$	Q_5
C_6	$\bar{A}\bar{B}\bar{C}$	$(0, y, 0)$	Q_6
C_0	$\bar{A}\bar{B}$	(x, y, t)	$Q_0 = \mathcal{P}$

that is

$$\left\{ \begin{array}{l} \lambda_1 + x\lambda_3 + x\lambda_4 + \lambda_5 = x, \\ \lambda_1 + \lambda_2 + y\lambda_5 + y\lambda_6 = y, \\ \lambda_1 + \lambda_2 + \lambda_3 + \lambda_4 = t, \\ \lambda_1 + \lambda_2 + \lambda_3 + \lambda_4 + \lambda_5 + \lambda_6 = 1, \\ \lambda_h \geq 0, \quad h = 1, \dots, 6. \end{array} \right. \iff \left\{ \begin{array}{l} \lambda_1 + \lambda_5 = x(\lambda_1 + \lambda_2 + \lambda_5 + \lambda_6), \\ \lambda_1 + \lambda_2 = y(\lambda_1 + \lambda_2 + \lambda_3 + \lambda_4), \\ \lambda_1 + \lambda_2 + \lambda_3 + \lambda_4 = t, \\ \lambda_1 + \lambda_2 + \lambda_3 + \lambda_4 + \lambda_5 + \lambda_6 = 1, \\ \lambda_h \geq 0, \quad h = 1, \dots, 6, \end{array} \right. \quad (10)$$

or equivalently

$$\left\{ \begin{array}{l} \lambda_1 + \lambda_5 = xyt + x(1-t), \\ \lambda_1 + \lambda_2 = yt, \\ \lambda_3 + \lambda_4 = 1 - yt, \\ \lambda_5 + \lambda_6 = 1 - t, \\ \lambda_h \geq 0, \quad h = 1, \dots, 6. \end{array} \right. \iff \left\{ \begin{array}{l} \lambda_5 = xyt + x(1-t) - \lambda_1, \\ \lambda_2 = yt - \lambda_1, \\ \lambda_3 = t(1-y) - \lambda_4, \\ \lambda_6 = (1-t)(1-x) - xyt + \lambda_1, \\ \lambda_h \geq 0, \quad h = 1, \dots, 6. \end{array} \right. \quad (11)$$

As $(x, y, t) \in [0, 1]^3$ it holds that $\max\{0, xyt - (1-t)(1-x)\} \leq \min\{xyt + x(1-t), yt\}$. Then, the System (\mathfrak{S}) is solvable and the set of all solutions \mathcal{S} is the set of vectors $\Lambda = (\lambda_1, \dots, \lambda_6)$ such that

$$\left\{ \begin{array}{l} \max\{0, xyt - (1-t)(1-x)\} \leq \lambda_1 \leq \min\{xyt + x(1-t), yt\}, \\ \lambda_2 = yt - \lambda_1, \\ \lambda_3 = t(1-y) - \lambda_4, \\ 0 \leq \lambda_4 \leq t(1-y), \\ \lambda_5 = xyt + x(1-t) - \lambda_1, \\ \lambda_6 = (1-t)(1-x) - xyt + \lambda_1. \end{array} \right.$$

For each conditional event A , B , and $A \vee B$ in \mathcal{F} we associate the function $\Phi_1(\Lambda) = \sum_{h: C_h \subseteq A} \lambda_h = \lambda_1 + \lambda_2 + \lambda_3 + \lambda_4$, $\Phi_2(\Lambda) = \sum_{h: C_h \subseteq B} \lambda_h = \lambda_1 + \lambda_2 + \lambda_5 + \lambda_6$, and $\Phi_3(\Lambda) = \lambda_1 + \dots + \lambda_6$, respectively, as defined in (3). We observe that $\Phi_3(\Lambda) = 1 > 0$ for each solution $\Lambda \in \mathcal{S}$ and hence $M_3 = \max\{\Phi_3 : \Lambda \in \mathcal{S}\} > 0$. Then, concerning the strict subset I_0 of $\{1, 2, 3\}$ (defined in (4)), we obtain $I_0 \subseteq \{1, 2\}$. Notice that I_0 cannot be equal to $\{1, 2\}$, because $\Phi_3(\Lambda) > 0$ implies that at least $\Phi_1(\Lambda)$ or $\Phi_2(\Lambda)$ is positive, for each $\Lambda \in \mathcal{S}$. Then, $M_1 = \max\{\Phi_1 : \Lambda \in \mathcal{S}\}$ and $M_2 = \max\{\Phi_2 : \Lambda \in \mathcal{S}\}$ cannot be equal to zero and hence $I_0 \subset \{1, 2\}$. Therefore, we distinguish the following three cases: (i) $I_0 = \emptyset$; (ii) $I_0 = \{1\}$; (iii) $I_0 = \{2\}$.

Case (i). As (\mathfrak{S}) is solvable, we obtain that the assessment $\mathcal{P} = (x, y, t)$ is coherent by Theorem 2.

Case (ii). The assessment $\mathcal{P}_0 = x \in [0, 1]$ on $\mathcal{F}_0 = \{C|B\}$ is coherent because B and C are logically independent. Then, as (\mathfrak{S}) is solvable and \mathcal{P}_0 on \mathcal{F}_0 is coherent, we obtain by Theorem 2 that the assessment $\mathcal{P} = (x, y, t)$ is coherent.

Case (iii) is analogous to Case (ii), where C and B are replaced by B and A , respectively.

Therefore, the assessment $\mathcal{P} = (x, y, t) \in [0, 1]^3$ is coherent for every $(x, y, t) \in [0, 1]^3$, that is the imprecise assessment $[0, 1]^3$ on \mathcal{F} is t-coherent. \square

We recall the following probability propagation rule for the inference form: from $(C|B, B|A, A|(A \vee B))$ to $C|A$ (Theorem 3 in [44]).

Theorem 5. *Let A, B, C be three logically independent events and $(x, y, t) \in [0, 1]^3$ be any (coherent) assessment on the sequence $(C|B, B|A, A|A \vee B)$. Then, the extension $z = p(C|A)$ from (x, y, t) is coherent if and only if $z \in [z', z'']$, where*

$$[z', z''] = \begin{cases} [0, 1], & t = 0; \\ \left[\max \left\{ 0, xy - \frac{(1-t)(1-x)}{t} \right\}, \min \left\{ 1, (1-x)(1-y) + \frac{x}{t} \right\} \right], & t > 0. \end{cases}$$

Theorem 5 has been generalized to the case of interval-valued probability assessments, which results into the following imprecise probability propagation rule (Theorem 4 in [44]):

Theorem 6. *Let A, B, C be three logically independent events and $\mathcal{I} = ([x_1, x_2] \times [y_1, y_2] \times [t_1, t_2]) \subseteq [0, 1]^3$ be a (t-coherent) interval-valued probability assessment on $(C|B, B|A, A|A \vee B)$. Then, the set Σ of the coherent extension of \mathcal{I} is the interval $[z^*, z^{**}]$, where $[z^*, z^{**}] =$*

$$\begin{cases} [0, 1], & t = 0; \\ \left[\max \left\{ 0, x_1 y_1 - \frac{(1-t_1)(1-x_1)}{t_1} \right\}, \min \left\{ 1, (1-x_2)(1-y_1) + \frac{x_2}{t_1} \right\} \right], & t > 0. \end{cases}$$

4.2. Traditionally valid syllogisms of Figure I.

In this section we consider the probabilistic interpretation of the valid syllogisms of Figure I (see Table 1). Specifically, we firstly adapt the results on Barbara, Barbari, and Darii given in [44] applying the notions of (s-)validity. Secondly, we prove s-validity of Celarent and Ferio and validity of Celaront. We use the probabilistic interpretation of the basic syllogistic sentence types given in Table 2. By instantiating in Proposition 1 the subject S , the middle M , and the predicate P term for the events A, B, C , respectively, we observe that the imprecise assessment $[0, 1]^3$ on $(P|M, M|S, P|S)$ is t-coherent. This implies that all syllogisms of Figure I are probabilistically non-informative. For instance, modus Barbara (“Every M is P , Every S is M , therefore Every S is P ”) without existential import assumption corresponds to the probabilistically non-informative inference: from the premises $p(P|M) = 1$ and $p(M|S) = 1$ infer that every $p(P|S) \in [0, 1]$ is coherent. Indeed, by Proposition 1, a probability assessment $(1, 1, z)$ on $(P|M, M|S, P|S)$ is coherent for every $z \in [0, 1]$. In order to construct probabilistically informative versions of valid syllogisms of Figure I, we add the conditional event existential import assumption to the probabilistic interpretation of the respective premise set: $p(S|(S \vee M)) > 0$ (see Definition 8). We now demonstrate the validity (and when possible the s-validity) of traditionally valid syllogisms by suitable instantiations in Theorem 5 within our semantics. Of course, some syllogisms will turn be equivalent when some terms are negated (and the corresponding probabilities are adjusted accordingly). However, we provide for each syllogism within each figure a direct way of showing its validity by simply instantiating the respective probability propagation rule.

Barbara. By instantiating S, M, P in Theorem 5 for A, B, C with $x = y = 1$ and any value $t > 0$ it follows that $z' = \max \left\{ 0, xy - \frac{(1-t)(1-x)}{t} \right\} = 1$ and $z'' = \min \left\{ 1, (1-x)(1-y) + \frac{x}{t} \right\} = 1$. Then, the

set Σ (see Equation (8)) of coherent extensions on $P|S$ of the imprecise assessment $\{1\} \times \{1\} \times (0, 1]$ on $(P|M, M|S, S|(S \vee M))$ is $\Sigma = \{1\}$. Thus, by Definition 7,

$$\{1\} \times \{1\} \times (0, 1] \text{ on } (P|M, M|S, S|(S \vee M)) \models_s \{1\} \text{ on } P|S. \quad (12)$$

In terms of probabilistic constraints, (12) can be expressed by

$$(p(P|M) = 1, p(M|S) = 1, p(S|(S \vee M)) > 0) \models_s p(P|S) = 1, \quad (13)$$

which is a s-valid (and probabilistically informative) version of Barbara (under the conditional event existential import assumption).

Remark 9. By instantiating Remark 6 to syllogisms of Figure I we obtain that $p(S) = p(S \wedge (S \vee M)) = p(S|(S \vee M))p(S \vee M)$. Hence, if $p(S) > 0$ then $p(S|(S \vee M)) > 0$. Then, as $p(S) > 0$ implies $p(S|(S \vee M)) > 0$, from (13) it follows that

$$(p(P|M) = 1, p(M|S) = 1, p(S) > 0) \models_s p(P|S) = 1, \quad (14)$$

which is an s-valid version of Barbara under the (stronger) unconditional existential import assumption.

Barbari. From (13), by weakening the conclusion (see Remark 4), it follows that

$$(p(P|M) = 1, p(M|S) = 1, p(S|(S \vee M)) > 0) \models p(P|S) > 0, \quad (15)$$

which is a valid (but not s-valid) version of Barbari (“Every M is P , Every S is M , therefore Some S is P ”).

Darii. By instantiating S, M, P in Theorem 5 for A, B, C with $x = 1$, any $y > 0$, and any $t > 0$, it follows that $z' = \max\left\{0, xy - \frac{(1-t)(1-x)}{t}\right\} = y > 0$ and $z'' = \min\{1, (1-x)(1-y) + \frac{x}{t}\} = 1$. Then, the set Σ of coherent extensions on $P|S$ of the imprecise assessment $\{1\} \times (0, 1] \times (0, 1]$ on $(P|M, M|S, S|(S \vee M))$ is $\Sigma = \bigcup_{\{(x,y,t) \in \{1\} \times (0,1] \times (0,1]\}} [y, 1] = (0, 1]$. Thus, by Definition 7,

$$\{1\} \times (0, 1] \times (0, 1] \text{ on } (P|M, M|S, S|(S \vee M)) \models_s (0, 1] \text{ on } P|S. \quad (16)$$

In terms of probabilistic constraints, (16) can be expressed by

$$(p(P|M) = 1, p(M|S) > 0, p(S|(S \vee M)) > 0) \models_s p(P|S) > 0, \quad (17)$$

which is a s-valid version of Darii (Every M is P , Some S is M , therefore Some S is P). Notice that Barbari (15) also follows from Darii (17) by strengthening the minor premise (see Remark 4).

Celarent. By instantiating S, M, P in Theorem 5 for A, B, C with $x = 0$, $y = 1$, and $t > 0$, it follows that $z' = \max\left\{0, xy - \frac{(1-t)(1-x)}{t}\right\} = 0$ and $z'' = \min\{1, (1-x)(1-y) + \frac{x}{t}\} = 0$. Then, the set Σ of coherent extensions on $P|S$ of the imprecise assessment $\{0\} \times (0, 1] \times (0, 1]$ on $(P|M, M|S, S|(S \vee M))$ is $\Sigma = \{0\}$. Thus, by Definition 7,

$$\{0\} \times \{1\} \times (0, 1] \text{ on } (P|M, M|S, S|(S \vee M)) \models_s \{0\} \text{ on } P|S. \quad (18)$$

In terms of probabilistic constraints, (18) can be expressed by

$$(p(P|M) = 0, p(M|S) = 1, p(S|(S \vee M)) > 0) \models_s p(P|S) = 0, \quad (19)$$

which is a s-valid version of Celarent (No M is P , Every S is M , therefore No S is P). Notice that Celarent is equivalent to Barbara, because (19) is equivalent to (13) when P is replaced by \bar{P} and the probabilities are adjusted accordingly.

Celarent. From (19), by weakening the conclusion, it follows that

$$(p(P|M) = 0, p(M|S) = 1, p(S|(S \vee M)) > 0) \models p(\bar{P}|S) > 0, \quad (20)$$

which is valid version of Celarent (*No M is P, Every S is M, therefore Some S is not P*). Notice that Celarent (20) is equivalent to Barbari (15), where P is replaced by \bar{P} .

Ferio. By instantiating S, M, P in Theorem 5 for A, B, C with $x = 0$, any $y > 0$, and any $t > 0$, it follows that $z' = \max \left\{ 0, xy - \frac{(1-t)(1-x)}{t} \right\} = 0$ and $z'' = \min \{ 1, (1-x)(1-y) + \frac{x}{t} \} = 1 - y < 1$. Then, the set Σ of coherent extensions on $P|S$ of the imprecise assessment $\{0\} \times (0, 1] \times (0, 1]$ on $(P|M, M|S, S|(S \vee M))$ is $\Sigma = \bigcup_{\{(x,y,t) \in \{0\} \times (0,1] \times (0,1]\}} [0, 1 - y] = [0, 1)$. Thus, by Definition 7,

$$\{0\} \times (0, 1] \times (0, 1] \text{ on } (P|M, M|S, S|(S \vee M)) \models_s [0, 1) \text{ on } P|S. \quad (21)$$

In terms of probabilistic constraints, (21) can be equivalently expressed by (see Table 2)

$$(p(P|M) = 0, p(M|S) > 0, p(S|(S \vee M)) > 0) \models_s p(\bar{P}|S) > 0, \quad (22)$$

which is a s -valid version of Ferio (*No M is P, Some S is M, therefore Some S is not P*). Notice that Ferio (22) is equivalent to Darii (17), where P is replaced by \bar{P} . Celarent (20) also follows from Ferio (22) by strengthening the minor premise (i.e., $p(M|S) > 0$ is replaced by the stronger constraint $p(M|S) = 1$).

5. Figure II.

In this section, we prove that the probabilistic inference of $\bar{C}|A$ from the premise set $(B|C, \bar{B}|A)$, which corresponds to the general form of syllogisms of Figure II, is probabilistically non-informative. Like in Section 4, we show that the imprecise assessment $[0, 1]^3$ on $(B|C, \bar{B}|A, \bar{C}|A)$ is t -coherent. Then, in order to obtain probabilistic informativeness, we add the probabilistic constraint $p(A|(A \vee C)) > 0$ to the premise set, which corresponds to the conditional event existential import assumption of syllogisms of Figure II according to Definition 8. After showing that the imprecise assessment $[0, 1]^3$ on $(B|C, \bar{B}|A, A|(A \vee C))$ is t -coherent, we prove the precise and imprecise probability propagation rules for the inference from $(B|C, \bar{B}|A, A|(A \vee C))$ to $\bar{C}|A$. We apply these results in Section 5.2, where we study the valid syllogisms of Figure II.

5.1. Coherence and probability propagation in Figure II.

We prove the t -coherence of the imprecise assessment $[0, 1]^3$ on the sequence of conditional events $(B|C, \bar{B}|A, \bar{C}|A)$.

Proposition 3. *Let A, B, C be logically independent events. The imprecise assessment $[0, 1]^3$ on $\mathcal{F} = (B|C, \bar{B}|A, \bar{C}|A)$ is t -coherent.*

Proof. Let $\mathcal{P} = (x, y, z) \in [0, 1]^3$ be any probability assessment on \mathcal{F} . The constituents C_h and the points Q_h associated with $(\mathcal{F}, \mathcal{P})$ are given in Table 5. The constituents C_h contained in $\mathcal{H}_3 = A \vee C$ are C_1, \dots, C_6 . We recall that coherence of $\mathcal{P} = (x, y, z)$ on \mathcal{F} requires that the condition $\mathcal{P} \in \mathfrak{S}$ is satisfied, where \mathfrak{S} is the convex hull of Q_1, \dots, Q_6 . This amounts to the solvability of the following system:

$$(\exists) \quad \mathcal{P} = \sum_{h=1}^6 \lambda_h Q_h, \quad \sum_{h=1}^6 \lambda_h = 1, \quad \lambda_h \geq 0, \quad h = 1, \dots, 6.$$

Table 5: Constituents C_h and points Q_h associated with the probability assessment $\mathcal{P} = (x, y, z)$ on $(B|C, \bar{B}|A, \bar{C}|A)$ involved in Figure II.

	C_h	Q_h	
C_1	ABC	$(1, 0, 0)$	Q_1
C_2	$ABC\bar{C}$	$(x, 0, 1)$	Q_2
C_3	$A\bar{B}C$	$(0, 1, 0)$	Q_3
C_4	$A\bar{B}C\bar{C}$	$(x, 1, 1)$	Q_4
C_5	$\bar{A}BC$	$(1, y, z)$	Q_5
C_6	$\bar{A}BC\bar{C}$	$(0, y, z)$	Q_6
C_0	$\bar{A}\bar{C}$	(x, y, z)	$Q_0 = \mathcal{P}$

We observe that $\mathcal{P} = (x, y, z) = x(1, y, z) + (1 - x)(0, y, z) = xQ_5 + (1 - x)Q_6$, that is system (\ominus) is solvable and a solution is $\Lambda = (0, 0, 0, 0, x, 1 - x)$. As $\Phi_2(\Lambda) = \Phi_3(\Lambda) = \lambda_1 + \lambda_2 + \lambda_3 + \lambda_4 = 0$, it holds that $I'_0 = \{2, 3\}$. Then, by Theorem 3, in order to check coherence of $(x, y, z) \in [0, 1]^3$ it is sufficient to check the coherence of the sub-assessment $(y, z) \in [0, 1]^2$ on $(\bar{B}|A, \bar{C}|A)$. The constituents C_h associated to the pair $((\bar{B}|A, \bar{C}|A), (y, z))$ contained in $\mathcal{H}_2 = A$ are $C_1 = ABC, C_2 = ABC\bar{C}, C_3 = A\bar{B}C, C_4 = A\bar{B}C\bar{C}$ and the corresponding points Q_h are $Q_1 = (0, 0), Q_2 = (0, 1), Q_3 = (1, 0), Q_4 = (1, 1)$. The convex hull \mathfrak{I} of the points Q_1, Q_2, Q_3, Q_4 is the unit square $[0, 1]^2$. Then $(y, z) \in [0, 1]^2$ trivially belongs to \mathfrak{I} and hence the system $(y, z) = \lambda_1 Q_1 + \lambda_2 Q_2 + \lambda_3 Q_3 + \lambda_4 Q_4$ has always a nonnegative solution $(\lambda_1, \lambda_2, \lambda_3, \lambda_4)$ with $\lambda_1 + \lambda_2 + \lambda_3 + \lambda_4 = 1$. Moreover, as $\Phi_1(\Lambda) = \Phi_2(\Lambda) = \lambda_1 + \lambda_2 + \lambda_3 + \lambda_4 = 1$, it follows that $I_0 = \emptyset$ and hence (y, z) is coherent. \square

Proposition 4. Let A, B, C be logically independent events. The assessment (x, y, t) on $(B|C, \bar{B}|A, A|(A \vee C))$ is coherent for every $(x, y, t) \in [0, 1]^3$.

Proof. Let $\mathcal{P} = (x, y, t) \in [0, 1]^3$ be a probability assessment on \mathcal{F} . The constituents C_h and the points Q_h associated with $(\mathcal{F}, \mathcal{P})$ are given in Table 6. By Theorem 2, coherence of $\mathcal{P} = (x, y, t)$ on \mathcal{F} requires that

 Table 6: Constituents C_h and points Q_h associated with the probability assessment $\mathcal{P} = (x, y, t)$ on $\mathcal{F} = (B|C, \bar{B}|A, A|(A \vee C))$ involved in the premise set of Figure II.

	C_h	Q_h	
C_1	ABC	$(1, 0, 1)$	Q_1
C_2	$ABC\bar{C}$	$(x, 0, 1)$	Q_2
C_3	$A\bar{B}C$	$(0, 1, 1)$	Q_3
C_4	$A\bar{B}C\bar{C}$	$(x, 1, 1)$	Q_4
C_5	$\bar{A}BC$	$(1, y, 0)$	Q_5
C_6	$\bar{A}BC\bar{C}$	$(0, y, 0)$	Q_6
C_0	$\bar{A}\bar{C}$	(x, y, t)	$Q_0 = \mathcal{P}$

the following system is solvable

$$(\ominus) \quad \mathcal{P} = \sum_{h=1}^6 \lambda_h Q_h, \quad \sum_{h=1}^6 \lambda_h = 1, \quad \lambda_h \geq 0, \quad h = 1, \dots, 6,$$

or equivalently

$$\left\{ \begin{array}{l} \lambda_1 + \lambda_5 = x(\lambda_1 + \lambda_3 + \lambda_5 + \lambda_6), \\ \lambda_3 + \lambda_4 = yt, \\ \lambda_1 + \lambda_2 + \lambda_3 + \lambda_4 = t, \\ \lambda_1 + \lambda_2 + \lambda_3 + \lambda_4 + \lambda_5 + \lambda_6 = 1, \\ \lambda_i \geq 0, i = 1, \dots, 6, \end{array} \right. \iff \left\{ \begin{array}{l} \lambda_1 + \lambda_5 = x(\lambda_1 + \lambda_3 + \lambda_5 + \lambda_6), \\ \lambda_3 + \lambda_4 = yt, \\ \lambda_1 + \lambda_2 = t(1 - y), \\ \lambda_5 + \lambda_6 = 1 - t, \\ \lambda_i \geq 0, i = 1, \dots, 6. \end{array} \right. \quad (23)$$

System (Ξ) is solvable and a subset \mathcal{S}' of the set of solutions consists of $\Lambda = (\lambda_1, \dots, \lambda_6)$ such that

$$\left\{ \begin{array}{l} \lambda_1 = \lambda_3 = 0, \lambda_2 = t(1 - y), \\ \lambda_4 = yt, \lambda_5 = x(1 - t), \\ \lambda_6 = (1 - x)(1 - t), \\ \lambda_i \geq 0, i = 1, \dots, 6. \end{array} \right. \quad (24)$$

Moreover, for each $\Lambda \in \mathcal{S}'$ it holds that $\Phi_1(\Lambda) = \sum_{h: C_h \subseteq C} = \lambda_1 + \lambda_3 + \lambda_5 + \lambda_6 = 1 - t$, $\Phi_2(\Lambda) = \sum_{h: C_h \subseteq A} = \lambda_1 + \lambda_2 + \lambda_3 + \lambda_4 = t$ and $\Phi_3(\Lambda) = \sum_{h: C_h \subseteq A \vee C} \lambda_h = 1 > 0$. If $0 < t < 1$, it holds that $I'_0 = \emptyset$, hence, by Theorem 3, (x, y, t) is coherent. If $t = 0$, it holds that $I'_0 = \{2\}$ and as the sub-assessment $y \in [0, 1]$ on $\bar{B}|A$ is coherent, it follows by Theorem 3 that (x, y, t) is coherent. Likewise, if $t = 1$, it holds that $I'_0 = \{1\}$ and as the sub-assessment $x \in [0, 1]$ on $B|C$ is coherent, it follows by Theorem 3 that (x, y, t) is coherent. Then, (x, y, t) is coherent for every $(x, y, t) \in [0, 1]^3$. \square

The next result allows for computing the lower and upper bounds, z' and z'' respectively, for the coherent extensions $z = p(\bar{C}|A)$ from the assessment (x, y, t) on $(B|C, \bar{B}|A, A|(A \vee C))$.

Theorem 7. *Let A, B, C be three logically independent events and $(x, y, t) \in [0, 1]^3$ be any assessment on the family $(B|C, \bar{B}|A, A|(A \vee C))$. Then, the extension $z = p(\bar{C}|A)$ is coherent if and only if $z \in [z', z'']$, where*

$$[z', z''] = \begin{cases} [0, 1], & \text{if } t \leq x + yt \leq 1, \\ \left[\frac{x + yt - 1}{t}, 1 \right], & \text{if } x + yt > 1, \\ \left[\frac{t - x - yt}{t(1 - x)}, 1 \right], & \text{if } x + yt < t. \end{cases}$$

Proof. Let $(x, y, t) \in [0, 1]^3$ be a generic assessment on $(B|C, \bar{B}|A, A|(A \vee C))$. We recall that (x, y, t) is coherent (Proposition 4). In order to prove the theorem we derive the coherent lower and upper probability bounds z' and z'' by applying Algorithm 1 in a symbolic way.

Computation of the lower probability bound z' on $\bar{C}|A$.

Input. $\mathcal{F} = (B|C, \bar{B}|A, A|(A \vee C))$, $E_{n+1}|H_{n+1} = \bar{C}|A$.

Step 0. The constituents associated with $(B|C, \bar{B}|A, A|(A \vee C), \bar{C}|A)$ and contained in $\mathcal{H}_{n+1} = A \vee C$ are $C_1 = ABC$, $C_2 = ABC\bar{C}$, $C_3 = A\bar{B}C$, $C_4 = A\bar{B}\bar{C}$, $C_5 = \bar{A}BC$, and $C_6 = \bar{A}\bar{B}C$. We construct the following starting system with unknowns $\lambda_1, \dots, \lambda_6, z$ (see Remark 2):

$$\left\{ \begin{array}{l} \lambda_2 + \lambda_4 = z(\lambda_1 + \lambda_2 + \lambda_3 + \lambda_4), \lambda_1 + \lambda_5 = x(\lambda_1 + \lambda_3 + \lambda_5 + \lambda_6), \\ \lambda_3 + \lambda_4 = y(\lambda_1 + \lambda_2 + \lambda_3 + \lambda_4), \\ \lambda_1 + \lambda_2 + \lambda_3 + \lambda_4 = t(\lambda_1 + \lambda_2 + \lambda_3 + \lambda_4 + \lambda_5 + \lambda_6), \\ \lambda_1 + \lambda_2 + \lambda_3 + \lambda_4 + \lambda_5 + \lambda_6 = 1, \lambda_i \geq 0, i = 1, \dots, 6. \end{array} \right. \quad (25)$$

Step 1. By setting $z = 0$ in System (25), we obtain

$$\begin{cases} \lambda_2 + \lambda_4 = 0, \lambda_1 + \lambda_5 = x, \\ \lambda_3 = y(\lambda_1 + \lambda_3), \lambda_1 + \lambda_3 = t, \\ \lambda_1 + \lambda_3 + \lambda_5 + \lambda_6 = 1, \\ \lambda_i \geq 0, i = 1, \dots, 6. \end{cases} \iff \begin{cases} \lambda_1 = t(1 - y), \lambda_2 = 0, \lambda_3 = yt, \\ \lambda_4 = 0, \lambda_5 = x - t(1 - y), \\ \lambda_6 = 1 - x - yt, \\ \lambda_i \geq 0, i = 1, \dots, 6. \end{cases} \quad (26)$$

The solvability of System (26) is a necessary condition for the coherence of the assessment $(x, y, t, 0)$ on $(B|C, \bar{B}|A, A|(A \vee C), \bar{C}|A)$. As $(x, y, t) \in [0, 1]^3$, it holds that: $\lambda_1 = t(1 - y) \geq 0$, $\lambda_3 = yt \geq 0$. Thus, System (26) is solvable if and only if $\lambda_5 \geq 0$ and $\lambda_6 \geq 0$, that is

$$t - yt \leq x \leq 1 - yt \iff t \leq x + yt \leq 1.$$

We distinguish two cases: (i) $x + yt > 1 \vee x + yt < t$; (ii) $t \leq x + yt \leq 1$. In Case (i), System (26) is not solvable (which implies that the coherent extension z of (x, y, t) must be positive). Then, we go to Step 2 of the algorithm where the (positive) lower bound z' is obtained by optimization. In Case (ii), System (26) is solvable and in order to check whether $z = 0$ is a coherent extension, we go to Step 3.

Case (i). We observe that in this case t cannot be 0. By Step 2 we have the following linear programming problem:

Compute $z' = \min(\lambda_2 + \lambda_4)$ subject to:

$$\begin{cases} \lambda_1 + \lambda_5 = x(\lambda_1 + \lambda_3 + \lambda_5 + \lambda_6), \lambda_3 + \lambda_4 = y(\lambda_1 + \lambda_2 + \lambda_3 + \lambda_4), \\ \lambda_1 + \lambda_2 + \lambda_3 + \lambda_4 = t(\lambda_1 + \lambda_2 + \lambda_3 + \lambda_4 + \lambda_5 + \lambda_6), \\ \lambda_1 + \lambda_2 + \lambda_3 + \lambda_4 = 1, \lambda_i \geq 0, i = 1, \dots, 6. \end{cases} \quad (27)$$

In this case, the constraints in (27) can be rewritten in the following way

$$\begin{cases} \lambda_1 + \lambda_5 = x(\lambda_1 + \lambda_3 + \lambda_5 + \lambda_6), \\ \lambda_3 + \lambda_4 = y, \lambda_5 + \lambda_6 = \frac{1-t}{t}, \\ \lambda_1 + \lambda_2 + \lambda_3 + \lambda_4 = 1, \\ \lambda_i \geq 0, i = 1, \dots, 6, \end{cases} \iff \begin{cases} 1 - y - \lambda_2 + \lambda_5 = x(1 - \lambda_2 - \lambda_4 + \frac{1-t}{t}), \\ \lambda_3 = y - \lambda_4, \lambda_6 = \frac{1-t}{t} - \lambda_5, \\ \lambda_1 = 1 - y - \lambda_2, \\ \lambda_i \geq 0, i = 1, \dots, 6, \end{cases}$$

or equivalently

$$\begin{cases} x\lambda_4 + (1 - y) + \lambda_5 = \lambda_2(1 - x) + \frac{x}{t}, \lambda_3 = y - \lambda_4, \\ \lambda_5 = \frac{1-t}{t} - \lambda_6, \lambda_1 = 1 - y - \lambda_2, \lambda_i \geq 0, i = 1, \dots, 6. \end{cases}$$

We distinguish two (alternative) cases: (i.1) $x + yt > 1$; (i.2) $x + yt < t$.

Case (i.1). The constraints in (27) can be rewritten in the following way

$$\begin{cases} x(\lambda_2 + \lambda_4) = \frac{x}{t} - (1 - y) - \frac{1-t}{t} + \lambda_2 + \lambda_6, \lambda_3 = y - \lambda_4, \\ \lambda_5 = \frac{1-t}{t} - \lambda_6, \lambda_1 = 1 - y - \lambda_2, \lambda_i \geq 0, i = 1, \dots, 6. \end{cases}$$

As $x > 1 - ty$, we observe that $x > 0$. Then, the minimum of $z = \lambda_2 + \lambda_4$, obtained when $\lambda_2 = \lambda_6 = 0$, is

$$z' = \frac{1}{x} \left(\frac{x}{t} - (1 - y) - \frac{1-t}{t} \right) = \frac{x - t + yt - 1 + t}{xt} = \frac{x + yt - 1}{xt}. \quad (28)$$

By choosing $\lambda_2 = \lambda_6 = 0$ the constraints in (27) are satisfied with

$$\begin{cases} \lambda_1 = 1 - y, \lambda_2 = 0, \lambda_3 = y - \frac{x+yt-1}{xt}, \lambda_4 = \frac{x+yt-1}{xt}, \\ \lambda_5 = \frac{1-t}{t}, \lambda_6 = 0, \lambda_i \geq 0, i = 1, \dots, 6. \end{cases}$$

In particular $\lambda_3 \geq 0$ is satisfied because the condition $\frac{x+yt-1}{xt} \leq y$, which in this case amounts to $yt(1-x) \leq 1-x$, is always satisfied. Then, the *procedure stops* yielding as *output* $z' = \frac{x+yt-1}{xt}$.

Case (i.2). The constraints in (27) can be rewritten in the following way

$$\begin{cases} (1-y) - \frac{x}{t} + \lambda_5 + \lambda_4 = \lambda_2(1-x) - x\lambda_4 + \lambda_4, & \lambda_3 = y - \lambda_4, \\ \lambda_6 = \frac{1-t}{t} - \lambda_5, & \lambda_1 = 1 - y - \lambda_2, \lambda_i \geq 0, \quad i = 1, \dots, 6, \end{cases}$$

or equivalently

$$\begin{cases} (\lambda_2 + \lambda_4)(1-x) = (1-y) - \frac{x}{t} + \lambda_4 + \lambda_5, & \lambda_3 = y - \lambda_4, \\ \lambda_6 = \frac{1-t}{t} - \lambda_5, & \lambda_1 = 1 - y - \lambda_2, \lambda_i \geq 0, \quad i = 1, \dots, 6. \end{cases}$$

As $t - yt - x > 0$, that is $x < t(1-y)$, it holds that $x < 1$. Then, the minimum of $z = \lambda_2 + \lambda_4$, obtained when $\lambda_4 = \lambda_5 = 0$, is

$$z' = \frac{1}{1-x} \left(1 - y - \frac{x}{t}\right) = \frac{t - yt - x}{(1-x)t} \geq 0.$$

We observe that by choosing $\lambda_4 = \lambda_5 = 0$ the constraints in (27) are satisfied, indeed they are

$$\begin{cases} \lambda_1 = 1 - y, & \lambda_2 = \frac{t-yt-x}{(1-x)t}, & \lambda_3 = y, & \lambda_4 = 0, \\ \lambda_5 = 0, & \lambda_6 = \frac{1-t}{t}, & \lambda_i \geq 0, & i = 1, \dots, 6. \end{cases}$$

Then, the *procedure stops* yielding as *output* $z' = \frac{t-yt-x}{(1-x)t}$.

Case (ii). We take Step 3 of the algorithm. We denote by Λ and \mathcal{S} the vector of unknowns $(\lambda_1, \dots, \lambda_6)$ and the set of solutions of System (26), respectively. We consider the following linear functions (associated with the conditioning events $H_1 = C, H_2 = H_4 = A, H_3 = A \vee C$) and their maxima in \mathcal{S} :

$$\begin{aligned} \Phi_1(\Lambda) &= \sum_{r: C_r \subseteq C} \lambda_r = \lambda_1 + \lambda_3 + \lambda_5 + \lambda_6, \\ \Phi_2(\Lambda) &= \Phi_4(\Lambda) = \sum_{r: C_r \subseteq A} \lambda_r = \lambda_1 + \lambda_2 + \lambda_3 + \lambda_4, \\ \Phi_3(\Lambda) &= \sum_{r: C_r \subseteq A \vee C} \lambda_r = \lambda_1 + \lambda_2 + \lambda_3 + \lambda_4 + \lambda_5 + \lambda_6, \\ M_i &= \max_{\Lambda \in \mathcal{S}} \Phi_i(\Lambda), \quad i = 1, 2, 3, 4. \end{aligned} \tag{29}$$

By (26) we obtain: $\Phi_1(\Lambda) = t(1-y) + yt + x - t(1-y) + 1 - x - yt = 1$, $\Phi_2(\Lambda) = \Phi_4(\Lambda) = t(1-y) + 0 + yt + 0 = t$, $\Phi_3(\Lambda) = t(1-y) + 0 + yt + 0 + x - t(1-y) + 1 - x - yt = 1$, $\forall \Lambda \in \mathcal{S}$. Then, $M_1 = 1$, $M_2 = M_4 = t$, and $M_3 = 1$. We consider two subcases: $t > 0$; $t = 0$. If $t > 0$, then $M_4 > 0$ and we are in the first case of Step 3. Thus, the *procedure stops* and yields $z' = 0$ as *output*.

If $t = 0$, then $M_1 > 0$, $M_3 > 0$ and $M_2 = M_4 = 0$. Hence, we are in third case of Step 3 with $J = \{2\}$, $I_0 = \{2, 4\}$ and the procedure restarts with Step 0, with \mathcal{F} replaced by $\mathcal{F}_J = (\bar{B}|A)$.

(2nd cycle) *Step 0.* The constituents associated with $(\bar{B}|A, \bar{C}|A)$, contained in A , are $C_1 = ABC, C_2 = ABC\bar{C}, C_3 = A\bar{B}C, C_4 = A\bar{B}\bar{C}$. The starting system is

$$\begin{cases} \lambda_3 + \lambda_4 = y(\lambda_1 + \lambda_2 + \lambda_3 + \lambda_4), & \lambda_2 + \lambda_4 = z(\lambda_1 + \lambda_2 + \lambda_3 + \lambda_4), \\ \lambda_1 + \lambda_2 + \lambda_3 + \lambda_4 = 1, & \lambda_i \geq 0, \quad i = 1, \dots, 4. \end{cases} \tag{30}$$

(2nd cycle) *Step 1.* By setting $z = 0$ in System (30), we obtain

$$\begin{cases} \lambda_1 = 1 - y, & \lambda_2 = \lambda_4 = 0, & \lambda_3 = y, & \lambda_i \geq 0, \quad i = 1, \dots, 4. \end{cases} \tag{31}$$

As $y \in [0, 1]$, System (31) is always solvable; thus, we go to Step 3.

(2nd cycle) *Step 3*. We denote by Λ and \mathcal{S} the vector of unknowns $(\lambda_1, \dots, \lambda_4)$ and the set of solutions of System (31), respectively. The conditioning events are $H_2 = A$ and $H_4 = A$; then the associated linear functions are: $\Phi_2(\Lambda) = \Phi_4(\Lambda) = \sum_{r: C_r \subseteq A} \lambda_r = \lambda_1 + \lambda_2 + \lambda_3 + \lambda_4$. From System (31), we obtain: $\Phi_2(\Lambda) = \Phi_4(\Lambda) = 1, \forall \Lambda \in \mathcal{S}$; so that $M_2 = M_4 = 1$. We are in the first case of Step 3 of the algorithm; then the *procedure stops* and yields $z' = 0$ as *output*.

To summarize, for any $(x, y, t) \in [0, 1]^3$ on $(B|C, \bar{B}|A, A|(A \vee C))$, we have computed the coherent lower bound z' on $\bar{C}|A$. In particular, if $t = 0$, then $z' = 0$. We also have $z' = 0$, when $t > 0$ and $t \leq x + yt \leq 1$, that is when $0 < t \leq x + yt \leq 1$. Then, we can write that $z' = 0$, when $t \leq x + yt \leq 1$. Otherwise, we have two cases: (i.1) $z' = \frac{x+yt-1}{xt}$, if $x + yt > 1$; (i.2) $z' = \frac{t-yt-x}{(1-x)t}$, if $x + yt < t$.

Computation of the upper probability bound z'' on $\bar{C}|A$.

Input and Step 0 are the same as in the proof of z' .

Step 1. By setting $z = 1$ in System (25), we obtain

$$\begin{cases} \lambda_1 + \lambda_3 = 0, \lambda_5 = x(\lambda_5 + \lambda_6), \\ \lambda_4 = y(\lambda_2 + \lambda_4), \lambda_2 + \lambda_4 = t, \\ \lambda_2 + \lambda_4 + \lambda_5 + \lambda_6 = 1, \\ \lambda_i \geq 0, i = 1, \dots, 6. \end{cases} \iff \begin{cases} \lambda_1 = \lambda_3 = 0, \lambda_2 = t(1-y), \\ \lambda_4 = yt, \lambda_5 = x(1-t), \\ \lambda_6 = (1-x)(1-t), \\ \lambda_i \geq 0, i = 1, \dots, 6. \end{cases} \quad (32)$$

As $(x, y, t) \in [0, 1]^3$, System (32) is solvable and we go to Step 3.

Step 3. We denote by Λ and \mathcal{S} the vector of unknowns $(\lambda_1, \dots, \lambda_6)$ and the set of solutions of System (32), respectively. We consider the functions given in (29). From System (32), we obtain: $\Phi_1(\Lambda) = 0 + 0 + x(1-t) + (1-x)(1-t) = 1-t$, $\Phi_2(\Lambda) = \Phi_4(\Lambda) = 0 + t(1-y) + 0 + yt = t$, $\Phi_3(\Lambda) = 0 + t(1-y) + 0 + yt + x(1-t) + (1-x)(1-t) = 1, \forall \Lambda \in \mathcal{S}$. Then, $M_1 = 1-t$, $M_2 = M_4 = t$, and $M_3 = 1$. If $t > 0$, then $M_4 > 0$ and we are in the first case of Step 3. Thus, the *procedure stops* and yields $z'' = 1$ as *output*. If $t = 0$, then $M_1 > 0$, $M_3 > 0$ and $M_2 = M_4 = 0$. Hence, we are in the third case of Step 3 with $J = \{2\}$, $I_0 = \{2, 4\}$ and the procedure restarts with Step 0, with \mathcal{F} replaced by $\mathcal{F}_J = (E_2|H_2) = (\bar{B}|A)$ and \mathcal{P} replaced by $\mathcal{P}_J = y$.

(2nd cycle) *Step 0*. This is the same as the (2nd cycle) Step 0 in the proof of z' .

(2nd cycle) *Step 1*. By setting $z = 1$ in System (25), we obtain

$$\{ \lambda_1 + \lambda_3 = 0, \lambda_4 = y, \lambda_2 = 1 - y, \lambda_i \geq 0, i = 1, \dots, 4. \quad (33)$$

As $y \in [0, 1]$, System (33) is always solvable; thus, we go to Step 3.

(2nd cycle) *Step 3*. Like in the (2nd cycle) Step 3 of the proof of z' , we obtain $M_4 = 1$. Thus, the procedure stops and yields $z'' = 1$ as *output*. To summarize, for any assessment $(x, y, t) \in [0, 1]^3$ on $(B|C, \bar{B}|A, A|(A \vee C))$, we have computed the coherent upper probability bound z'' on $\bar{C}|A$, which is always $z'' = 1$. \square

Remark 10. We observe that in Theorem 7 we do not presuppose, differently from the classical approach, positive probability for the conditioning events $(A$ and $C)$. For example, even if we assume $p(A|(A \vee C)) = t > 0$ we do not require positive probability for the conditioning event A , and $p(A)$ could be zero (indeed, since $p(A) = p(A \wedge (A \vee C)) = p(A|(A \vee C))p(A \vee C)$, $p(A) > 0$ implies $p(A|(A \vee C)) > 0$, but not vice versa).

The next result is based on Theorem 7 and presents the set of the coherent extensions of a given interval-valued probability assessment $\mathcal{I} = ([x_1, x_2] \times [y_1, y_2] \times [t_1, t_2]) \subseteq [0, 1]^3$ on the sequence on $(B|C, \bar{B}|A, A|(A \vee C))$ to the further conditional event $\bar{C}|A$.

Theorem 8. Let A, B, C be three logically independent events and $\mathcal{I} = ([x_1, x_2] \times [y_1, y_2] \times [t_1, t_2]) \subseteq [0, 1]^3$ be an imprecise assessment on $(B|C, \bar{B}|A, A|(A \vee C))$. Then, the set Σ of the coherent extensions of \mathcal{I} on $\bar{C}|A$ is the interval $[z^*, z^{**}]$, where

$$[z^*, z^{**}] = \begin{cases} [0, 1], & \text{if } (x_2 + y_2 t_1 \geq t_1) \wedge (x_1 + y_1 t_1 \leq 1), \\ \left[\frac{x_1 + y_1 t_1 - 1}{t_1 x_1}, 1 \right], & \text{if } x_1 + y_1 t_1 > 1, \\ \left[\frac{t_1 - x_2 - y_2 t_1}{t_1(1 - x_2)}, 1 \right], & \text{if } x_2 + y_2 t_1 < t_1. \end{cases}$$

Proof. As from Proposition 4 the set $[0, 1]^3$ on $(B|C, \bar{B}|A, A|(A \vee C))$ is totally coherent, then \mathcal{I} is totally coherent too. Then, $\Sigma = \bigcup_{\mathcal{P} \in \mathcal{I}} [z'_{\mathcal{P}}, z''_{\mathcal{P}}] = [z^*, z^{**}]$, where $z^* = \inf_{\mathcal{P} \in \mathcal{I}} z'_{\mathcal{P}}$ (i.e., $z^* = \inf\{z'_{\mathcal{P}} : \mathcal{P} \in \mathcal{I}\}$) and $z^{**} = \sup_{\mathcal{P} \in \mathcal{I}} z''_{\mathcal{P}}$ (i.e., $z^{**} = \sup\{z''_{\mathcal{P}} : \mathcal{P} \in \mathcal{I}\}$). We distinguish three alternative cases: (i) $x_1 + y_1 t_1 > 1$; (ii) $x_2 + y_2 t_1 < t_1$; (iii) $(x_2 + y_2 t_1 \geq t_1) \wedge (x_1 + y_1 t_1 \leq 1)$.

Of course, for all three cases $z^{**} = \sup_{\mathcal{P} \in \mathcal{I}} z''_{\mathcal{P}} = 1$.

Case (i). We observe that the function $x + yt : [0, 1]^3$ is nondecreasing in the arguments x, y, t . Then, in this case, $x + yt \geq x_1 + y_1 t_1 > 1$ for every $\mathcal{P} = (x, y, t) \in \mathcal{I}$ and hence by Theorem 7 $z'_{\mathcal{P}} = f(x, y, t) = \frac{x+yt-1}{tx}$ for every $\mathcal{P} \in \mathcal{I}$. Moreover, $f(x, y, t) : [0, 1]^3$ is nondecreasing in the arguments x, y, t , thus $z^* = \frac{x_1 + y_1 t_1 - 1}{t_1 x_1}$.

Case (ii). We observe that the function $x + yt - t : [0, 1]^3$ is nondecreasing in the arguments x, y and nonincreasing in the argument t . Then, in this case, $x + yt - t \leq x_2 + y_2 t_1 - t_1 < 0$ for every $\mathcal{P} = (x, y, t) \in \mathcal{I}$ and hence by Theorem 7 $z'_{\mathcal{P}} = g(x, y, t) = \frac{t-x-yt}{t(1-x)}$ for every $\mathcal{P} \in \mathcal{I}$. Moreover, $g(x, y, t) : [0, 1]^3$ is nonincreasing in the arguments x, y and nondecreasing in the argument t . Thus, $z^* = \frac{t_1 - x_2 - y_2 t_1}{t_1(1 - x_2)}$. Case (iii). In this case there exists a vector $(x, y, t) \in \mathcal{I}$ such that $t \leq x + yt \leq 1$ and hence by Theorem 7 $z'_{\mathcal{P}} = 0$. Thus, $z^* = 0$. \square

Remark 11. By instantiating Theorem 8 with the imprecise assessment $\mathcal{I} = \{1\} \times [y_1, 1] \times [t_1, 1]$, where $t_1 > 0$, we obtain the following lower and upper bounds for the conclusion $[z^*, z^{**}] = [y_1, 1]$. Thus, for every $t_1 > 0$: z^* depends only on the value of y_1 .

5.2. Traditionally valid syllogisms of Figure II.

In this section we consider the probabilistic interpretation of the traditionally valid syllogisms of Figure II (Camestres, Camestrop, Baroco, Cesare, Cesaro, Festino; see Table 1). Like in Figure I, all syllogisms of Figure II without existential import assumptions are probabilistically non-informative. Indeed, by instantiating S, M, P for A, B, C , respectively, in Proposition 3, we observe that the imprecise assessment $[0, 1]^3$ on $(M|P, \bar{M}|S, \bar{P}|S)$ is t-coherent. For instance, Camestres (“Every P is M , No S is M , therefore No S is P ”) without existential import assumption corresponds to the probabilistically non-informative inference: from the premises $p(M|P) = 1$ and $p(\bar{M}|S) = 1$ infer that every $p(\bar{P}|S) \in [0, 1]$ is coherent (see Proposition 3). Therefore we add the conditional event existential import assumption: $p(S|(S \vee P)) > 0$ (see Definition 8). In what follows, we construct (s-)valid versions of the traditionally valid syllogisms of Figure II, by suitable instantiations in Theorem 7.

Camestres. By instantiating S, M, P in Theorem 7 for A, B, C with $x = y = 1$ and $t > 0$ it follows that $z' = \frac{x+yt-1}{tx} = 1$ and $z'' = 1$. Then, the set Σ of coherent extensions on $\bar{P}|S$ of the imprecise assessment $\{1\} \times \{1\} \times (0, 1]$ on $(M|P, \bar{M}|S, S|(S \vee P))$ is $\Sigma = \{1\}$. Thus, by Definition 7,

$$\{1\} \times \{1\} \times (0, 1] \text{ on } (M|P, \bar{M}|S, S|(S \vee P)) \models_s \{1\} \text{ on } \bar{P}|S. \quad (34)$$

In terms of probabilistic constraints, (34) can be equivalently expressed by (see Table 2)

$$(p(M|P) = 1, p(M|S) = 0, p(S|(S \vee P)) > 0) \models_s p(P|S) = 0, \quad (35)$$

which is a s-valid version of Camestres.

Camestrop. From (35), by weakening the conclusion of Camestres, it follows that

$$(p(M|P) = 1, p(M|S) = 0, p(S|(S \vee P)) > 0) \models p(P|S) < 1, \quad (36)$$

which is equivalent to

$$(p(M|P) = 1, p(M|S) = 0, p(S|(S \vee P)) > 0) \models p(\bar{P}|S) > 0. \quad (37)$$

Inference (37) is a valid (but not s-valid) version of Camestrop (*Every P is M, No S is M, therefore Some S is not P*).

Baroco. By instantiating S, M, P in Theorem 7 for A, B, C with $x = 1$, any $y > 0$, and any $t > 0$, it follows that $z' = \frac{x+yt-1}{tx} = \frac{1+yt-1}{t} = y > 0$. Then, the set Σ of coherent extensions on $\bar{P}|S$ of the imprecise assessment $\{1\} \times (0, 1] \times (0, 1]$ on $(M|P, \bar{M}|S, S|(S \vee P))$ is $\Sigma = \bigcup_{\{(x,y,t) \in \{1\} \times (0,1] \times (0,1]\}} [y, 1] = (0, 1]$. Thus, by Definition 7,

$$\{1\} \times (0, 1] \times (0, 1] \text{ on } (M|P, \bar{M}|S, S|(S \vee P)) \models_s (0, 1] \text{ on } \bar{P}|S. \quad (38)$$

In terms of probabilistic constraints, (38) can be expressed by,

$$(p(M|P) = 1, p(\bar{M}|S) > 0, p(S|(S \vee P)) > 0) \models_s p(\bar{P}|S) > 0. \quad (39)$$

Therefore, inference (39) is a s-valid version of Baroco (*Every P is M, Some S is not M, therefore Some S is not P*). Notice that Camestrop (37) also follows from Baroco (39) by strengthening the minor premise.

Cesare. By instantiating S, M, P in Theorem 7 for A, B, C with $x = y = 0$ and any $t > 0$, it follows that $z' = \frac{t-x-yt}{t(1-x)} = 1$ (and $z'' = 1$). Then, the set Σ of coherent extensions on $\bar{P}|S$ of the imprecise assessment $\{0\} \times \{0\} \times (0, 1]$ on $(M|P, \bar{M}|S, S|(S \vee P))$ is $\Sigma = \{1\}$. Thus, by Definition 7,

$$\{0\} \times \{0\} \times (0, 1] \text{ on } (M|P, \bar{M}|S, S|(S \vee P)) \models_s \{1\} \text{ on } \bar{P}|S. \quad (40)$$

In terms of probabilistic constraints, (40) can be expressed by,

$$(p(M|P) = 0, p(\bar{M}|S) = 0, p(S|(S \vee P)) > 0) \models_s p(\bar{P}|S) = 1,$$

or equivalently by

$$(p(M|P) = 0, p(M|S) = 1, p(S|(S \vee P)) > 0) \models_s p(P|S) = 0. \quad (41)$$

Therefore, inference (41) is a s-valid version of Cesare (*No P is M, Every S is M, therefore No S is P*). Notice that Cesare is equivalent to Camestres, because (41) is equivalent to (35) when M is replaced by \bar{M} (and the probabilities are adjusted accordingly).

Cesaro. From (41), by weakening the conclusion of Cesare, it follows that

$$(p(M|P) = 0, p(M|S) = 1, p(S|(S \vee P)) > 0) \models p(\bar{P}|S) > 0, \quad (42)$$

which is a valid (but not s-valid) version of Cesare (*No P is M, Every S is M, therefore Some S is not P*). Notice that Cesare is equivalent to Camestrop, because (42) is equivalent to (37) when M is replaced by \bar{M} .

Festino. By instantiating S, M, P in Theorem 7 for A, B, C with $x = 0$, any $y < 1$ and any $t > 0$, as $x + yt < t$, it follows that $z' = \frac{t-x-yt}{t(1-x)} = \frac{t-yt}{t} > 1 - y > 0$ (and $z'' = 1$). Then, the set Σ of coherent extensions on $P|S$ of the imprecise assessment $\{0\} \times [0, 1] \times (0, 1]$ on $(M|P, \bar{M}|S, S|(S \vee P))$ is $\Sigma = \bigcup_{\{(x,y,t) \in \{0\} \times [0,1] \times (0,1]\}} [1 - y, 1] = (0, 1]$. Thus, by Definition 7,

$$\{0\} \times [0, 1] \times (0, 1] \text{ on } (M|P, \bar{M}|S, S|(S \vee P)) \models_s (0, 1] \text{ on } \bar{P}|S. \quad (43)$$

In terms of probabilistic constraints, (43) can be equivalently expressed by

$$(p(M|P) = 0, p(M|S) > 0, p(S|(S \vee P)) > 0) \models_s p(\bar{P}|S) > 0, \quad (44)$$

which is a s-valid version of Festino (*No P is M, Some S is M, therefore Some S is not P*). Notice that Festino is equivalent to Baroco, because (44) is equivalent to (39) when M is replaced by \bar{M} . Cesare (42) also follows from Festino (44) by strengthening the minor premise.

Remark 12. We observe that, traditionally, the conclusions of logically valid Aristotelian syllogisms of Figure II are neither in the form of sentence type I (some) nor of A (every). In terms of our probability semantics, indeed, this must be the case even if the existential import assumption $p(S|(S \vee P)) > 0$ is made: according to Theorem 7, the upper bound for the conclusion $p(\bar{P}|S)$ is always 1; thus, neither sentence type I ($p(P|S) > 0$, i.e. $p(\bar{P}|S) < 1$) nor sentence type A ($p(P|S) = 1$, i.e. $p(\bar{P}|S) = 0$) can be validated.

6. Figure III.

In this section, we observe that the probabilistic inference of $C|A$ from the premise set $(C|B, A|B)$, which corresponds to the general form of syllogisms of Figure III, is probabilistically non-informative (Proposition 5). Therefore, we add the probabilistic constraint $p(B|(A \vee B)) > 0$, as conditional event existential import assumption, to obtain probabilistic informativeness. Then, we prove the precise and imprecise probability propagation rules for the inference from $(C|B, A|B, B|(A \vee B))$ to $C|A$. We apply these results in Section 6.2, where we study the valid syllogisms of Figure III.

6.1. Coherence and probability propagation in Figure III.

Proposition 5. Let A, B, C be logically independent events. The imprecise assessment $[0, 1]^3$ on $\mathcal{F} = (C|B, A|B, C|A)$ is totally coherent.

Proof. By exchanging B and A and by reordering the sequence \mathcal{F} , Proposition 5 is equivalent to Proposition 1. \square

Now we show that the imprecise assessment $[0, 1]^3$ on the sequence of conditional events $(C|B, A|B, B|(A \vee B))$ is t-coherent. Note that the strategy used in the proof of Proposition 5 cannot be applied for proving Proposition 6.

Proposition 6. *Let A, B, C be logically independent events. The imprecise assessment $[0, 1]^3$ on $\mathcal{F} = (C|B, A|B, B|(A \vee B))$ is totally coherent.*

Proof. Let $\mathcal{P} = (x, y, t) \in [0, 1]^3$ be a probability assessment on \mathcal{F} . The constituents C_h and the points Q_h associated with $(\mathcal{F}, \mathcal{P})$ are given in Table 7. By Theorem 2, coherence of $\mathcal{P} = (x, y, z)$ on \mathcal{F} requires that

Table 7: Constituents C_h and points Q_h associated with the probability assessment $\mathcal{P} = (x, y, t)$ on $\mathcal{F} = (C|B, A|B, B|(A \vee B))$ involved in the premise set of Figure III.

	C_h	Q_h	
C_1	ABC	$(1, 1, 1)$	Q_1
C_2	$ABC\bar{C}$	$(0, 1, 1)$	Q_2
C_3	$A\bar{B}$	$(x, y, 0)$	Q_3
C_4	$\bar{A}BC$	$(1, 0, 1)$	Q_4
C_5	$\bar{A}B\bar{C}$	$(0, 0, 1)$	Q_5
C_0	$\bar{A}\bar{B}$	(x, y, t)	$Q_0 = \mathcal{P}$

the following system is solvable

$$(\mathfrak{S}) \quad \mathcal{P} = \sum_{h=1}^5 \lambda_h Q_h, \quad \sum_{h=1}^5 \lambda_h = 1, \quad \lambda_h \geq 0, \quad h = 1, \dots, 5,$$

or equivalently

$$\left\{ \begin{array}{l} \lambda_1 + \lambda_4 = x(\lambda_1 + \lambda_2 + \lambda_4 + \lambda_5), \\ \lambda_1 + \lambda_2 = y(\lambda_1 + \lambda_2 + \lambda_4 + \lambda_5), \\ \lambda_1 + \lambda_2 + \lambda_4 + \lambda_5 = t(\lambda_1 + \lambda_2 + \lambda_3 + \lambda_4 + \lambda_5), \\ \lambda_1 + \lambda_2 + \lambda_3 + \lambda_4 + \lambda_5 = 1, \\ \lambda_i \geq 0, \quad i = 1, \dots, 5, \end{array} \right. \iff \left\{ \begin{array}{l} \lambda_1 + \lambda_4 = xt, \\ \lambda_1 + \lambda_2 = yt, \\ \lambda_1 + \lambda_2 + \lambda_4 + \lambda_5 = t, \\ \lambda_3 = 1 - t, \\ \lambda_i \geq 0, \quad i = 1, \dots, 5, \end{array} \right. \quad (45)$$

that is

$$\left\{ \begin{array}{l} \lambda_2 = yt - \lambda_1, \\ \lambda_3 = 1 - t, \\ \lambda_4 = xt - \lambda_1, \\ \lambda_5 = t - xt - yt + \lambda_1, \\ \lambda_i \geq 0, \quad i = 1, \dots, 5. \end{array} \right.$$

System (\mathfrak{S}) is solvable because $t \max\{0, x + y - 1\} \leq t \min\{x, y\}$, for every $(x, y, t) \in [0, 1]^3$ and the set of solutions \mathcal{S} consists of the vectors $\Lambda = (\lambda_1, \dots, \lambda_5)$ such that

$$\left\{ \begin{array}{l} t \max\{0, x + y - 1\} \leq \lambda_1 \leq t \min\{x, y\}, \\ \lambda_2 = yt - \lambda_1, \\ \lambda_3 = 1 - t, \\ \lambda_4 = xt - \lambda_1, \\ \lambda_5 = t - xt - yt + \lambda_1. \end{array} \right.$$

Moreover, for each $\Lambda \in \mathcal{S}$ it holds that $\Phi_1(\Lambda) = \Phi_2(\Lambda) = \sum_{h: C_h \subseteq B} \lambda_h = \lambda_1 + \lambda_2 + \lambda_4 + \lambda_5 = t$, and $\Phi_3(\Lambda) = \sum_{h: C_h \subseteq A \vee B} \lambda_h = 1$. If $t > 0$, it follows that, for each $\Lambda \in \mathcal{S}$, $\Phi_1(\Lambda) = \Phi_2(\Lambda) > 0$, and $\Phi_3(\Lambda) > 0$. Then, $I_0 = \emptyset$ and by Theorem 2, the assessment (x, y, t) is coherent. If $t = 0$, it follows that for each $\Lambda \in \mathcal{S}$, $\Phi_1(\Lambda) = \Phi_2(\Lambda) = 0$. Then, $I_0 = \{1, 2\}$ and as it is well known that the sub-assessment (x, y) on $(C|B, A|B)$ is coherent for every $(x, y) \in [0, 1]^2$, it follows by Theorem 2 that (x, y, t) is coherent. Then, (x, y, t) is coherent for every $(x, y, t) \in [0, 1]^3$. \square

The next theorem presents the coherent probability propagation rules in Figure III under the conditional event existential import assumption.

Theorem 9. *Let A, B, C be three logically independent events and $(x, y, t) \in [0, 1]^3$ be a (coherent) assessment on the family $(C|B, A|B, B|(A \vee B))$. Then, the extension $z = p(C|A)$ is coherent if and only if $z \in [z', z'']$, where*

$$z' = \begin{cases} 0, & \text{if } t(x + y - 1) \leq 0, \\ \frac{t(x + y - 1)}{1 - t(1 - y)}, & \text{if } t(x + y - 1) > 0, \end{cases} \quad z'' = \begin{cases} 1, & \text{if } t(y - x) \leq 0, \\ 1 - \frac{t(y - x)}{1 - t(1 - y)}, & \text{if } t(y - x) > 0. \end{cases}$$

Proof. In order to compute the lower and upper probability bounds z' and z'' on the further event $C|A$ (i.e., the conclusion), we apply Algorithm 1 in a symbolic way.

Computation of the lower probability bound z' on $C|A$.

Input. The assessment (x, y, t) on $\mathcal{F} = (C|B, A|B, B|(A \vee B))$ and the event $C|A$.

Step 0. The constituents associated with $(C|B, A|B, B|(A \vee B), C|A)$ are $C_0 = \bar{A}\bar{B}$, $C_1 = ABC$, $C_2 = A\bar{B}C$, $C_3 = AB\bar{C}$, $C_4 = A\bar{B}\bar{C}$, $C_5 = \bar{A}BC$, $C_6 = \bar{A}\bar{B}\bar{C}$. We observe that $\mathcal{H}_0 = A \vee B$; then, the constituents contained in \mathcal{H}_0 are C_1, \dots, C_6 . We construct the starting system with the unknowns $\lambda_1, \dots, \lambda_6, z$:

$$\begin{cases} \lambda_1 + \lambda_2 = z(\lambda_1 + \lambda_2 + \lambda_3 + \lambda_4), \\ \lambda_1 + \lambda_5 = x(\lambda_1 + \lambda_3 + \lambda_5 + \lambda_6), \\ \lambda_1 + \lambda_3 = y(\lambda_1 + \lambda_3 + \lambda_5 + \lambda_6), \\ \lambda_1 + \lambda_3 + \lambda_5 + \lambda_6 = t(\sum_{i=1}^6 \lambda_i), \\ \sum_{i=1}^6 \lambda_i = 1, \lambda_i \geq 0, i = 1, \dots, 6, \end{cases} \iff \begin{cases} \lambda_1 + \lambda_2 = z(\lambda_1 + \lambda_2 + \lambda_3 + \lambda_4), \\ \lambda_1 + \lambda_5 = xt, \\ \lambda_1 + \lambda_3 = yt, \\ \lambda_1 + \lambda_3 + \lambda_5 + \lambda_6 = t, \\ \sum_{i=1}^6 \lambda_i = 1, \lambda_i \geq 0, i = 1, \dots, 6. \end{cases} \quad (46)$$

Step 1. By setting $z = 0$ in System (46), we obtain

$$\begin{cases} \lambda_1 + \lambda_2 = 0, \lambda_3 = yt, \lambda_5 = xt, \\ \lambda_3 + \lambda_5 + \lambda_6 = t, \\ \lambda_3 + \lambda_4 + \lambda_5 + \lambda_6 = 1, \\ \lambda_i \geq 0, i = 1, \dots, 6. \end{cases} \iff \begin{cases} \lambda_1 = \lambda_2 = 0, \\ \lambda_3 = yt, \lambda_4 = 1 - t, \lambda_5 = xt, \\ \lambda_6 = t(1 - x - y), \\ \lambda_i \geq 0, i = 1, \dots, 6. \end{cases} \quad (47)$$

As $(x, y, t) \in [0, 1]^3$, the conditions $\lambda_h \geq 0, h = 1, \dots, 5$, in System (47) are all satisfied. Then, System (47), i.e. System (46) with $z = 0$, is solvable if and only if $\lambda_6 = t(1 - x - y) \geq 0$. We distinguish two cases: (i) $t(1 - x - y) < 0$ (i.e. $t > 0$ and $x + y > 1$); (ii) $t(1 - x - y) \geq 0$, (i.e. $t = 0$ or $(t > 0) \wedge (x + y \leq 1)$). In Case (i), System (47) is not solvable and we go to Step 2 of the algorithm. In Case (ii), System (47) is solvable and we go to Step 3.

Case (i). By Step 2 we have the following linear programming problem:

Compute $\gamma' = \min(\sum_{i: C_i \subseteq AC} \lambda_r) = \min(\lambda_1 + \lambda_2)$ subject to:

$$\begin{cases} \lambda_1 + \lambda_5 = x(\lambda_1 + \lambda_3 + \lambda_5 + \lambda_6), \lambda_1 + \lambda_3 = y(\lambda_1 + \lambda_3 + \lambda_5 + \lambda_6), \\ \lambda_1 + \lambda_3 + \lambda_5 + \lambda_6 = t(\sum_{i=1}^6 \lambda_i), \lambda_1 + \lambda_2 + \lambda_3 + \lambda_4 = 1, \\ \lambda_i \geq 0, i = 1, \dots, 6. \end{cases} \quad (48)$$

We notice that y is positive since $x + y > 1$ (and $(x, y, t) \in [0, 1]^3$). Then, also $1 - t(1 - y)$ is positive and

the constraints in (48) can be rewritten as

$$\begin{cases} \lambda_1 + \lambda_5 = xt(1 + \lambda_5 + \lambda_6), \\ \lambda_1 + \lambda_3 = yt(1 + \lambda_5 + \lambda_6), \\ \lambda_5 + \lambda_6 = (t - yt)(1 + \lambda_5 + \lambda_6), \\ \lambda_1 + \lambda_2 + \lambda_3 + \lambda_4 = 1, \\ \lambda_i \geq 0, i = 1, \dots, 6, \end{cases} \iff \begin{cases} \lambda_5 + \lambda_6 = \frac{t(1-y)}{1-t(1-y)}, \\ \lambda_1 + \lambda_5 = xt\left(1 + \frac{t(1-y)}{1-t(1-y)}\right) = \frac{xt}{1-t(1-y)}, \\ \lambda_1 + \lambda_3 = yt\left(1 + \frac{t(1-y)}{1-t(1-y)}\right) = \frac{yt}{1-t(1-y)}, \\ \lambda_1 + \lambda_2 + \lambda_3 + \lambda_4 = 1, \\ \lambda_i \geq 0, i = 1, \dots, 6, \end{cases}$$

$$\iff \begin{cases} \max\{0, \frac{t(x+y-1)}{1-t(1-y)}\} \leq \lambda_1 \leq \min\{x, y\} \frac{t}{1-t(1-y)}, \\ 0 \leq \lambda_2 \leq \frac{1-t}{1-t(1-y)}, \quad \lambda_3 = \frac{yt}{1-t(1-y)} - \lambda_1, \quad \lambda_4 = \frac{1-t}{1-t(1-y)} - \lambda_2, \\ \lambda_5 = \frac{xt}{1-t(1-y)} - \lambda_1, \quad \lambda_6 = \frac{t(1-x-y)}{1-t(1-y)} + \lambda_1. \end{cases} \quad (49)$$

Thus, by recalling that $x + y - 1 > 0$, the minimum γ' of $\lambda_1 + \lambda_2$ subject to (48), or equivalently subject to (49), is obtained at $(\lambda'_1, \lambda'_2) = (\frac{t(x+y-1)}{1-t(1-y)}, 0)$. The *procedure stops* yielding as *output* $z' = \gamma' = \lambda'_1 + \lambda'_2 = \frac{t(x+y-1)}{1-t(1-y)}$.

Case (ii). We take Step 3 of the algorithm. We denote by Λ and \mathcal{S} the vector of unknowns $(\lambda_1, \dots, \lambda_6)$ and the set of solutions of System (47), respectively. We consider the following linear functions (associated with the conditioning events $H_1 = H_2 = B, H_3 = A \vee B, H_4 = A$) and their maxima in \mathcal{S} :

$$\begin{aligned} \Phi_1(\Lambda) &= \Phi_2(\Lambda) = \sum_{r: C_r \subseteq B} \lambda_r = \lambda_1 + \lambda_3 + \lambda_5 + \lambda_6, \\ \Phi_3(\Lambda) &= \sum_{r: C_r \subseteq A \vee B} \lambda_r = \lambda_1 + \lambda_2 + \lambda_3 + \lambda_4 + \lambda_5 + \lambda_6, \\ \Phi_4(\Lambda) &= \sum_{r: C_r \subseteq A} \lambda_r = \lambda_1 + \lambda_2 + \lambda_3 + \lambda_4, \quad M_i = \max_{\Lambda \in \mathcal{S}} \Phi_i(\Lambda), \quad i = 1, 2, 3, 4. \end{aligned} \quad (50)$$

By (47) we obtain: $\Phi_1(\Lambda) = \Phi_2(\Lambda) = 0 + yt + xt + t - xt - yt = t$, $\Phi_3(\Lambda) = 1$, $\Phi_4(\Lambda) = yt + 1 - t = 1 - t(1 - y)$, $\forall \Lambda \in \mathcal{S}$. Then, $M_1 = M_2 = t$, $M_3 = 1$, and $M_4 = 1 - (1 - y)t$. We consider two subcases: $t < 1$; $t = 1$. If $t < 1$, then $M_4 = yt + 1 - t > yt \geq 0$; so that $M_4 > 0$ and we are in the first case of Step 3 (i.e., $M_{n+1} > 0$). Thus, the *procedure stops* and yields $z' = 0$ as *output*. If $t = 1$, then $M_1 = M_2 = M_3 = 1 > 0$ and $M_4 = y$. Hence, we are in the first case of Step 3 (when $y > 0$) or in the second case of Step 3 (when $y = 0$). Thus, the *procedure stops* and yields $z' = 0$ as *output*.

Computation of the upper probability bound z'' on $C|A$. *Input* and *Step 0* are the same as in the proof of z' . *Step 1.* By setting $z = 1$ in System (46), we obtain

$$\begin{cases} \lambda_1 + \lambda_2 = \lambda_1 + \lambda_2 + \lambda_3 + \lambda_4, \quad \lambda_1 + \lambda_5 = xt, \quad \lambda_1 + \lambda_3 = yt, \\ \lambda_1 + \lambda_3 + \lambda_5 + \lambda_6 = t, \quad \lambda_1 + \lambda_2 + \lambda_3 + \lambda_4 + \lambda_5 + \lambda_6 = 1, \quad \lambda_i \geq 0, \quad i = 1, \dots, 6, \end{cases}$$

or equivalently

$$\begin{cases} \lambda_3 = \lambda_4 = 0, \quad \lambda_1 + \lambda_5 = xt, \\ \lambda_1 = yt, \quad \lambda_1 + \lambda_5 + \lambda_6 = t, \\ \lambda_1 + \lambda_2 + \lambda_5 + \lambda_6 = 1, \\ \lambda_i \geq 0, \quad i = 1, \dots, 6; \end{cases} \iff \begin{cases} \lambda_1 = yt, \quad \lambda_2 = 1 - t, \quad \lambda_3 = \lambda_4 = 0, \\ \lambda_5 = (x - y)t, \quad \lambda_6 = t(1 - x), \\ \lambda_i \geq 0, \quad i = 1, \dots, 6. \end{cases} \quad (51)$$

As $(x, y, t) \in [0, 1]^3$, the inequalities $\lambda_h \geq 0$, $h = 1, 2, 3, 4, 6$ are satisfied. Then, System (51), i.e. System (46) with $z = 1$, is solvable if and only if $\lambda_5 = (x - y)t \geq 0$. We distinguish two cases: (i) $(x - y)t < 0$,

i.e. $x < y$ and $t > 0$; (ii) $(x - y)t \geq 0$, i.e. $x \geq y$ or $t = 0$. In Case (i), System (51) is not solvable and we go to Step 2 of the algorithm. In Case (ii), System (51) is solvable and we go to Step 3.

Case (i). By Step 2 we have the following linear programming problem:

Compute $\gamma'' = \max(\lambda_1 + \lambda_2)$ subject to the constraints in (48). As $(x, y, t) \in [0, 1]^3$ and $x < y$, it follows that $\min\{x, y\} = x$ and $y > 0$. Then, in this case the quantity $1 - t(1 - y)$ is positive and the constraints in (48) can be rewritten as in (49). Thus, the maximum γ'' of $\lambda_1 + \lambda_2$ subject to (49), is obtained at $(\lambda_1'', \lambda_2'') = (\frac{xt}{1-t(1-y)}, \frac{1-t}{1-t(1-y)})$. The procedure stops yielding as output $z'' = \gamma'' = \lambda_1'' + \lambda_2'' = \frac{xt}{1-t(1-y)} + \frac{1-t}{1-t(1-y)} = \frac{1-t+xt}{1-t+yt} = 1 - \frac{t(y-x)}{1-t+yt}$.

Case (ii). We take Step 3 of the algorithm. We denote by Λ and \mathcal{S} the vector of unknowns $(\lambda_1, \dots, \lambda_6)$ and the set of solutions of System (51), respectively. We consider the functions $\Phi_i(\Lambda)$ and the maxima M_i , $i = 1, 2, 3, 4$, given in (50). From System (51), we observe that the functions Φ_1, \dots, Φ_4 are constant for every $\Lambda \in \mathcal{S}$, in particular it holds that $\Phi_1(\Lambda) = \Phi_2(\Lambda) = t$, $\Phi_3(\Lambda) = 1$ and $\Phi_4(\Lambda) = yt + 1 - t + 0 + 0 = 1 - t(1 - y)$ for every $\Lambda \in \mathcal{S}$. So that $M_1 = M_2 = t$, $M_3 = 1$, and $M_4 = 1 - t(1 - y)$. We consider two subcases: $t < 1$; $t = 1$.

If $t < 1$, then $M_4 = yt + 1 - t > yt \geq 0$; so that $M_4 > 0$ and we are in the first case of Step 3 (i.e., $M_{n+1} > 0$). Thus, the procedure stops and yields $z'' = 1$ as output.

If $t = 1$, then $M_1 = M_2 = M_3 = 1 > 0$ and $M_4 = y$. Hence, we are in the first case of Step 3 (when $y > 0$) or in the second case of Step 3 (when $y = 0$). Thus, the procedure stops and yields $z'' = 1$ as output. \square

Remark 13. From Theorem 9, we obtain $z' > 0$ if and only if $t(x + y - 1) > 0$. Moreover, we obtain $z'' < 1$ if and only if $t(y - x) > 0$. Moreover, it is easy to verify that

$$z'_{\{x,y,t\}} + z''_{\{1-x,y,t\}} = 1,$$

where $z'_{\{x,y,t\}}$ and $z''_{\{1-x,y,t\}}$ are the lower bound and the upper bound of the two assessments (x, y, z) and $(1 - x, y, z)$ on $((C|B), (A|B), B|(A \vee B))$, respectively.

Based on Theorem 9, the next result presents the set of coherent extensions of a given interval-valued probability assessment $\mathcal{I} = ([x_1, x_2] \times [y_1, y_2] \times [t_1, t_2]) \subseteq [0, 1]^3$ on $(C|B, A|B, B|(A \vee B))$ to the further conditional event $C|A$.

Theorem 10. Let A, B, C be three logically independent events and $\mathcal{I} = ([x_1, x_2] \times [y_1, y_2] \times [t_1, t_2]) \subseteq [0, 1]^3$ be an imprecise assessment on $(C|B, A|B, B|(A \vee B))$. Then, the set Σ of the coherent extensions of \mathcal{I} on $C|A$ is the interval $[z^*, z^{**}]$, where

$$z^* = \begin{cases} 0, & \text{if } t_1(x_1 + y_1 - 1) \leq 0, \\ \frac{t_1(x_1 + y_1 - 1)}{1 - t_1(1 - y_1)}, & \text{if } t_1(x_1 + y_1 - 1) > 0, \end{cases} \quad \text{and}$$

$$z^{**} = \begin{cases} 1, & \text{if } t_1(y_1 - x_2) \leq 0, \\ 1 - \frac{t_1(y_1 - x_2)}{1 - t_1(1 - y_1)}, & \text{if } t_1(y_1 - x_2) > 0. \end{cases}$$

Proof. Since the set $[0, 1]^3$ on $(C|B, A|B, B|(A \vee B))$ is totally coherent (Proposition 6), it follows that \mathcal{I} is also totally coherent. For every precise assessment $\mathcal{P} = (x, y, t) \in \mathcal{I}$, we denote by $[z'_{\mathcal{P}}, z''_{\mathcal{P}}]$ the interval of the coherent extension of \mathcal{P} on $C|A$, where $z'_{\mathcal{P}}$ and $z''_{\mathcal{P}}$ coincide with z' and z'' , respectively, as defined in Theorem 9. Then, $\Sigma = \bigcup_{\mathcal{P} \in \mathcal{I}} [z'_{\mathcal{P}}, z''_{\mathcal{P}}] = [z^*, z^{**}]$, where $z^* = \inf_{\mathcal{P} \in \mathcal{I}} z'_{\mathcal{P}}$ and $z^{**} = \sup_{\mathcal{P} \in \mathcal{I}} z''_{\mathcal{P}}$.

Concerning the computation of z^* we distinguish the following alternative cases: (i) $t_1(x_1 + y_1 - 1) \leq 0$; (ii) $t_1(x_1 + y_1 - 1) > 0$. Case (i). By Theorem 9 it holds that $z'_{\mathcal{P}} = 0$ for $\mathcal{P} = (x_1, y_1, t_1)$. Thus, $\{z'_{\mathcal{P}} : \mathcal{P} \in \mathcal{I}\} \supseteq \{0\}$ and hence $z^* = 0$.

Case (ii). We note that the function $t(x + y - 1) : [0, 1]^3$ is nondecreasing in the arguments x, y, t . Then, $t(x + y - 1) \geq t_1(x_1 + y_1 - 1) > 0$ for every $(x, y, t) \in \mathcal{I}$. Hence by Theorem 9, $z'_{\mathcal{P}} = \frac{t(x+y-1)}{1-t(1-y)}$ for every $\mathcal{P} \in \mathcal{I}$. Moreover, the function $\frac{t(x+y-1)}{1-t(1-y)}$ is nondecreasing in the arguments x, y, t over the restricted domain \mathcal{I} ; then, $\frac{t(x+y-1)}{1-t(1-y)} \geq \frac{t_1(x_1+y_1-1)}{1-t_1(1-y_1)}$. Thus, $z^* = \inf\{z'_{\mathcal{P}} : \mathcal{P} \in \mathcal{I}\} = \inf\left\{\frac{t(x+y-1)}{1-t(1-y)} : (x, y, z) \in \mathcal{I}\right\} = \frac{t_1(x_1+y_1-1)}{1-t_1(1-y_1)}$.

Concerning the computation of z^{**} we distinguish the following alternative cases: (i) $t_1(y_1 - x_2) \leq 0$; (ii) $t_1(y_1 - x_2) > 0$. Case (i). By Theorem 9 it holds that $z''_{\mathcal{P}} = 1$ for $\mathcal{P} = (x_2, y_1, t_1) \in \mathcal{I}$. Thus, $\{z''_{\mathcal{P}} : \mathcal{P} \in \mathcal{I}\} \supseteq \{1\}$ and hence $z^{**} = 1$.

Case (ii). We observe that $t(y - x) \geq t_1(y - x) \geq t_1(y_1 - x) \geq t_1(y_1 - x_2) > 0$ for every $(x, y, t) \in \mathcal{I}$. Then, the condition $t(y - x) > 0$ is satisfied for every $\mathcal{P} = (x, y, t) \in \mathcal{I}$ and hence by Theorem 9, $z''_{\mathcal{P}} = 1 - \frac{t(y-x)}{1-t(1-y)}$ for every $\mathcal{P} \in \mathcal{I}$. The function $1 - \frac{t(y-x)}{1-t(1-y)}$ is nondecreasing in the argument x and it is nonincreasing in the arguments y, t over the restricted domain \mathcal{I} . Thus, $1 - \frac{t(y-x)}{1-t(1-y)} \leq 1 - \frac{t(y-x_2)}{1-t(1-y)} \leq 1 - \frac{t_1(y_1-x_2)}{1-t_1(1-y_1)}$ for every $(x, y, t) \in \mathcal{I}$. Then $z^{**} = \sup\{z''_{\mathcal{P}} : \mathcal{P} \in \mathcal{I}\} = \sup\left\{1 - \frac{t(y-x)}{1-t(1-y)} : (x, y, z) \in \mathcal{I}\right\} = 1 - \frac{t_1(y_1-x_2)}{1-t_1(1-y_1)}$. \square

6.2. Traditionally valid syllogisms of Figure III.

In this section we consider the probabilistic interpretation of the traditionally valid syllogisms of Figure III (Darapti, Datisi, Disamis, Felapton, Ferison, and Bocardo; see Table 1). Like in Figure I and in Figure II, all syllogisms of Figure III without existential import assumptions are probabilistically non-informative. Indeed, by instantiating S, M, P for A, B, C , respectively, in Proposition 5, we observe that the imprecise assessment $[0, 1]^3$ on $(P|M, S|M, P|S)$ is t-coherent. Thus, for instance, from the premises $p(P|M) = 1$ and $p(S|M) > 0$ infer that every $p(P|S) \in [0, 1]$ is coherent. This means that Datisi (“Every M is P , Some M is S , therefore Some S is P ”) without existential import assumption is not valid. Therefore we add the conditional event existential import assumption: $p(M|(S \vee M)) > 0$ (see Definition 8). In what follows, we construct (s)-valid versions of the traditionally valid syllogisms of Figure III, by suitable instantiations in Theorem 9.

Darapti. By instantiating S, M, P in Theorem 9 for A, B, C with $x = 1$, any $y = 1$, and any $t > 0$, as $t(x + y - 1) = t > 0$, it follows that $z' = \frac{t(x+y-1)}{1-t(1-y)} = t > 0$. Concerning the upper bound z'' , as $t(y - x) = 0$, it holds that $z'' = 1$. Then, the set Σ of coherent extensions on $P|S$ of the imprecise assessment $\{1\} \times \{1\} \times (0, 1]$ on $(P|M, S|M, M|(S \vee M))$ is $\Sigma = \bigcup_{\{(x,y,t) \in \{1\} \times \{1\} \times (0,1]\}} [t, 1] = \bigcup_{\{t \in (0,1]\}} [t, 1] = (0, 1]$. Thus, by Definition 7,

$$\{1\} \times \{1\} \times (0, 1] \text{ on } (P|M, S|M, M|(S \vee M)) \models_s (0, 1] \text{ on } P|S. \quad (52)$$

In terms of probabilistic constraints, (52) can be expressed by

$$(p(P|M) = 1, p(S|M) = 1, p(M|(S \vee M)) > 0) \models_s p(P|S) > 0, \quad (53)$$

which is a s-valid version of Darapti.

Datisi. By instantiating S, M, P in Theorem 9 for A, B, C with $x = 1$, any $y > 0$, and any $t > 0$, as $t(x + y - 1) = ty > 0$, it follows that $z' = \frac{t(x+y-1)}{1-t(1-y)} = \frac{ty}{1-t(1-y)} > 0$. Concerning the upper bound z'' , as $t(y - x) = t(y - 1) \leq 0$, it holds that $z'' = 1$. Then, the set Σ of coherent extensions on $P|S$ of the imprecise assessment $\{1\} \times (0, 1] \times (0, 1]$ on $(P|M, S|M, M|(S \vee M))$ is $\Sigma = \bigcup_{\{(x,y,t) \in \{1\} \times (0,1] \times (0,1]\}} \left[\frac{ty}{1-t(1-y)}, 1 \right]$. We now prove that $\Sigma = (0, 1]$. Of course, $\Sigma \subseteq [0, 1]$. Moreover, as for $(y, t) \in (0, 1] \times (0, 1]$ it holds that $\frac{ty}{1-t(1-y)} > 0$, then $0 \notin \Sigma$ and hence $\Sigma \subseteq (0, 1]$. *Vice versa*, let $z \in (0, 1]$. By choosing any pair $(y, t) \in (0, 1] \times (0, 1]$ such that $0 < t \leq z$ and $y = 1$, we obtain

$$\frac{ty}{1-t(1-y)} = t \leq z \leq 1,$$

which implies that $z \in \Sigma$. Thus, by Definition 7,

$$\{1\} \times (0, 1] \times (0, 1] \text{ on } (P|M, S|M, M|(S \vee M)) \models_s (0, 1] \text{ on } P|S. \quad (54)$$

In terms of probabilistic constraints, (54) can be expressed by

$$(p(P|M) = 1, p(S|M) > 0, p(M|(S \vee M)) > 0) \models_s p(P|S) > 0, \quad (55)$$

which is a s-valid version of Datisi. Therefore, inference (55) is a probabilistically informative version of Datisi.

Disamis. We instantiate S, M, P in Theorem 9 for A, B, C with any $x > 0$, $y = 1$, and any $t > 0$. We observe that the imprecise assessment $I = (0, 1] \times \{1\} \times (0, 1]$ on $(P|M, S|M, M|(S \vee M))$ coincides with $I' \cup I''$, where $I' = \{1\} \times \{1\} \times (0, 1]$ and $I'' = (0, 1) \times \{1\} \times (0, 1]$ (notice that here $(0, 1)$ denotes the open unit interval). Then, the set Σ of coherent extensions on $P|S$ of the imprecise assessment I on $P|S$ coincides with $\Sigma' \cup \Sigma''$, where Σ' and Σ'' are the sets of coherent extensions of the two assessments I' and I'' , respectively. In case of I' (which implies $x = 1$), it holds that $\Sigma' = \bigcup_{\{(x,y,t) \in \{1\} \times \{1\} \times (0,1]\}} [t, 1] = (0, 1]$ (see Darapti). In case of I'' (which implies $x > 0$), as $t(x + y - 1) = tx > 0$, it follows that $z' = \frac{t(x+y-1)}{1-t(1-y)} = tx > 0$; concerning the upper bound, as $t(y - x) = t(1 - x) > 0$, it holds that $z'' = 1 - \frac{t(y-x)}{1-t(1-y)} = 1 - t(1 - x)$. Then, $\Sigma'' = \bigcup_{\{(x,y,t) \in (0,1) \times \{1\} \times (0,1]\}} [tx, 1 - t(1 - x)] = (0, 1)$. Hence, $\Sigma = \Sigma' \cup \Sigma'' = (0, 1]$. Thus, by Definition 7,

$$(0, 1] \times \{1\} \times (0, 1] \text{ on } (P|M, S|M, M|(S \vee M)) \models_s (0, 1] \text{ on } P|S. \quad (56)$$

In terms of probabilistic constraints, (56) can be expressed by

$$(p(P|M) > 0, p(S|M) = 1, p(M|(S \vee M)) > 0) \models_s p(P|S) > 0, \quad (57)$$

which is a s-valid version of Disamis (“Some M is P , Every M is S , therefore Some S is P ”). Notice that Darapti also follows from Disamis and from Datisi by strengthening the premise.

Felapton. By instantiating S, M, P in Theorem 9 for A, B, C with $x = 0$, any $y = 1$, and any $t > 0$, as $t(x + y - 1) = 0$, it follows that $z' = 0$. Concerning the upper bound z'' , as $t(y - x) = t > 0$, it holds that $z'' = 1 - \frac{t(y-x)}{1-t(1-y)} = 1 - t$. Then, the set Σ of coherent extensions on $P|S$ of the imprecise assessment $\{0\} \times \{1\} \times (0, 1]$ on $(P|M, S|M, M|(S \vee M))$ is $\Sigma = \bigcup_{\{(x,y,t) \in \{0\} \times \{1\} \times (0,1]\}} [0, 1 - t]$. Equivalently, the set $\bar{\Sigma}$ of coherent extensions on $\bar{P}|S$ is $\bar{\Sigma} = \bigcup_{\{(x,y,t) \in \{0\} \times \{1\} \times (0,1]\}} [t, 1] = \bigcup_{\{t \in (0,1]\}} [t, 1] = (0, 1]$. Thus, by Definition 7,

$$\{0\} \times \{1\} \times (0, 1] \text{ on } (P|M, S|M, M|(S \vee M)) \models_s (0, 1] \text{ on } \bar{P}|S. \quad (58)$$

In terms of probabilistic constraints, (58) can be expressed by

$$(p(P|M) = 0, p(S|M) = 1, p(M|(S \vee M)) > 0) \models_s p(\bar{P}|S) > 0, \quad (59)$$

which is a s-valid version of Felapton. Notice that Felapton is equivalent to Darapti, because (59) is equivalent to (53) when P is replaced by \bar{P} (and the probabilities are adjusted accordingly).

Ferison. By instantiating S, M, P in Theorem 9 for A, B, C with $x = 0$, any $y > 0$, and any $t > 0$, as $t(x + y - 1) = t(y - 1) \leq 0$, it follows that $z' = 0$. Concerning the upper bound z'' , as $t(y - x) = ty > 0$, it holds that $z'' = 1 - \frac{t(y-x)}{1-t(1-y)} = 1 - \frac{ty}{1-t(1-y)}$. Then, the set Σ of coherent extensions on $P|S$ of the imprecise assessment $\{0\} \times (0, 1] \times (0, 1]$ on $(P|M, S|M, M|(S \vee M))$ is $\Sigma = \bigcup_{\{(x,y,t) \in \{0\} \times (0,1] \times (0,1]\}} [0, 1 - \frac{ty}{1-t(1-y)}]$. Equivalently, as $p(\bar{P}|S) = 1 - p(P|S)$, the set of coherent extensions on $\bar{P}|S$, denoted by $\bar{\Sigma}$, of the imprecise assessment $\{0\} \times (0, 1] \times (0, 1]$ on $(P|M, S|M, M|(S \vee M))$ is $\bar{\Sigma} = \bigcup_{\{(x,y,t) \in \{0\} \times (0,1] \times (0,1]\}} [\frac{ty}{1-t(1-y)}, 1] = (0, 1]$. Thus, by Definition 7,

$$\{0\} \times (0, 1] \times (0, 1] \text{ on } (P|M, S|M, M|(S \vee M)) \models_s (0, 1] \text{ on } \bar{P}|S. \quad (60)$$

In terms of probabilistic constraints, (60) can be expressed by

$$(p(P|M) = 0, p(S|M) > 0, p(M|(S \vee M)) > 0) \models_s p(\bar{P}|S) > 0, \quad (61)$$

which is a s-valid version of Ferison. Notice that Ferison (61) is equivalent to Datisi (55), when P is replaced by \bar{P} .

Bocardo. We instantiate S, M, P in Theorem 9 for A, B, C with any $x < 1$, $y = 1$, and any $t > 0$. We observe that the imprecise assessment $I = [0, 1] \times \{1\} \times (0, 1]$ on $(P|M, S|M, M|(S \vee M))$ coincides with $I' \cup I''$, where $I' = \{0\} \times \{1\} \times (0, 1]$ and $I'' = (0, 1) \times \{1\} \times (0, 1]$ (notice that here $(0, 1)$ denotes the open unit interval). Then, the set Σ of coherent extensions on $P|S$ of the imprecise assessment I on $P|S$ coincides with $\Sigma' \cup \Sigma''$, where Σ' and Σ'' are the sets of coherent extensions of the two assessments I' and I'' , respectively. In case of I' (which implies $x = 0$), it holds that $\Sigma' = \bigcup_{\{(x,y,t) \in \{0\} \times \{1\} \times (0,1]\}} [0, 1 - t] = [0, 1]$ (see the set Σ in Felapton). In case of I'' (which implies $0 < x < 1$), it holds that $\Sigma'' = (0, 1)$ (see the set Σ'' in Disamis). Hence, $\Sigma = \Sigma' \cup \Sigma'' = [0, 1]$. Thus, by Definition 7,

$$[0, 1] \times \{1\} \times (0, 1] \text{ on } (P|M, S|M, M|(S \vee M)) \models_s [0, 1] \text{ on } P|S. \quad (62)$$

In terms of probabilistic constraints, (62) can be expressed by

$$(p(P|M) < 1, p(S|M) = 1, p(M|(S \vee M)) > 0) \models_s p(P|S) < 1,$$

which is equivalent to

$$(p(\bar{P}|M) > 0, p(S|M) = 1, p(M|(S \vee M)) > 0) \models_s p(\bar{P}|S) > 0. \quad (63)$$

Formula (63) is a s-valid version of Bocardo (“Some M is not P , Every M is S , therefore Some S is not P ”). We observe that Bocardo (63) is equivalent to Disamis (57), when P is replaced by \bar{P} .

Remark 14. Notice that, traditionally, the conclusions of logically valid Aristotelian syllogisms of Figure III are neither in the form of sentence type A (every) nor of E (no). In terms of our probability semantics, we study which assessments (x, y, t) on $(P|M, S|M, S|(S \vee M))$ propagate to $z' = z'' = p(P|S) = 1$ in order

to validate A in the conclusion. According to Theorem 9, $(x, y, t) \in [0, 1]^3$ propagates to $z' = z'' = 1$ if and only if

$$\begin{cases} (x, y, t) \in [0, 1]^3, \\ t(x + y - 1) > 0, \\ z' = \frac{t(x+y-1)}{1-t(1-y)} = 1, \\ t(y-x) \leq 0, \end{cases} \iff \begin{cases} (x, y, t) \in [0, 1]^3, \\ 1 + yt - t > 0, \\ tx = 1, ty \leq 1, \end{cases} \iff \begin{cases} x = 1, \\ 0 < y \leq 1, \\ t = 1. \end{cases}$$

Then, $z' = z'' = 1$ if and only if $(x, y, t) = (1, y, 1)$, with $0 < y \leq 1$. However, for the syllogisms it would be too strong to require $t = 1$ as an existential import assumption, we only require that $t > 0$. Similarly, in order to validate E in the conclusion, it can be shown that assessments (x, y, t) on $(P|M, S|M, S|(S \vee M))$ propagate to the conclusion $z' = z'' = p(P|S) = 0$ if and only if $(x, y, t) = (0, y, 1)$, with $0 < y \leq 1$. Therefore, if t is just positive neither A nor E can be validate within in our probability semantics of Figure III.

7. Applications to nonmonotonic reasoning.

We recall that the *default* $H \sim E$ denotes the sentence “ E is a plausible consequence of H ” (see, e.g., [59]). Moreover, the *negated default* $H \not\sim E$ denotes the sentence “it is not the case, that: E is a plausible consequence of H ”. Based on Definition 8 in [44], we interpret the default $H \sim E$ by the probability assessment $p(E|H) = 1$; while the negated default $H \not\sim E$ is interpreted by the imprecise probability assessment $p(E|H) < 1$. Thus, as the probability assessment $p(E|H) > 0$ is equivalent to $p(\bar{E}|H) < 1$, the negated default $H \not\sim \bar{E}$ is also interpreted by $p(E|H) > 0$. Then, the basic syllogistic sentence types (see Table 2) can be interpreted in terms of defaults or negated defaults as follows:

- (A) $S \sim P$ (Every S is P , $p(P|S) = 1$);
- (E) $S \sim \bar{P}$ (No S is P , $p(\bar{P}|S) = 1$);
- (I) $S \not\sim \bar{P}$ (Some S is P , $p(P|S) > 0$);
- (O) $S \not\sim P$ (Some S is not P , $p(\bar{P}|S) > 0$).

For example, recall the probabilistic modus Barbara (13), which is strictly valid and thus valid, can be expressed in terms of defaults and negated defaults as follows: $(M \sim P, S \sim M, (S \vee M) \not\sim \bar{S}) \models S \sim P$. As pointed out in [44] the default version of Barbara amounts to the well-known inference rule Weak Transitivity. We recall that Weak Transitivity is valid in the nonmonotonic System R ([62], i.e., System P ([59]) plus Rational Monotonicity), because it is equivalent to Rational Monotonicity ([34, Theorem 2.1]). For other nonmonotonic versions of transitivity see [8, 7]. We present the default versions of the (logically valid) syllogisms of Figures I, II, and III in Table 8. These versions, which involve defaults and negated defaults, are valid in our approach and can serve as inference rules for nonmonotonic reasoning.

Moreover, we observe that some syllogisms can be expressed in defaults only without using negated defaults. For example, if the conditional event existential import of Barbara is strengthened by $p(S|(S \vee M)) = 1$, we obtain the following valid default rule:

$$(M \sim P, S \sim M, (S \vee M) \sim S) \models_s S \sim P. \quad (64)$$

Note that inference (64) still satisfies AAA of Figure I. In probabilistic terms inference (64) means that the premises p -entails the conclusion (see Section 10.2 in [49]), i.e.,

$$(p(P|M) = 1, p(M|S) = 1, p(S|(S \vee M)) = 1) \models_s p(P|S) = 1. \quad (65)$$

In general, the probability propagation rules for the three figures can be used to generate new syllogisms. For example, from the probability propagation rule of Figure III (Theorem 9) we obtain a valid syllogism of type AAA with the (stronger) existential import $p(M|(S \vee M)) = 1$, which is in terms of defaults:

$$(M \sim P, M \sim S, (S \vee M) \sim M) \models_s S \sim P. \quad (66)$$

Equations (64) and (66) are p-valid inference rules for nonmonotonic reasoning and constitute syllogisms which are beyond traditional Aristotelian syllogisms (since, traditionally, AAA does not describe a valid syllogism of Figure III).

The procedure of replacing negated defaults by defaults, for obtaining inference (64), can also yield new syllogisms.

Figure I		
AAA	Barbara	$(M \sim P, S \sim M, (S \vee M) \not\sim \bar{S}) \models_s S \sim P.$
AAI	Barbari	$(M \sim P, S \sim M, (S \vee M) \not\sim \bar{S}) \models S \not\sim \bar{P}.$
AII	Darii	$(M \sim P, S \not\sim \bar{M}, (S \vee M) \not\sim \bar{S}) \models_s S \not\sim \bar{P}.$
EAE	Celarent	$(M \sim \bar{P}, S \sim M, (S \vee M) \not\sim \bar{S}) \models_s S \sim \bar{P}.$
EAO	Celaront	$(M \sim \bar{P}, S \sim M, (S \vee M) \not\sim \bar{S}) \models S \not\sim P.$
EIO	Ferio	$(M \sim \bar{P}, S \not\sim \bar{M}, (S \vee M) \not\sim \bar{S}) \models_s S \not\sim P.$
Figure II		
AEE	Camestres	$(P \sim M, S \sim \bar{M}, (S \vee P) \not\sim \bar{S}) \models_s S \sim \bar{P}.$
AEO	Camestrop	$(P \sim M, S \sim \bar{M}, (S \vee P) \not\sim \bar{S}) \models S \not\sim P.$
AOO	Baroco	$(P \sim M, S \not\sim M, (S \vee P) \not\sim \bar{S}) \models_s S \not\sim P.$
EAE	Cesare	$(P \sim \bar{M}, S \sim M, (S \vee P) \not\sim \bar{S}) \models_s S \sim \bar{P}.$
EAO	Cesaro	$(P \sim \bar{M}, S \sim M, (S \vee P) \not\sim \bar{S}) \models S \not\sim P.$
EIO	Festino	$(P \sim \bar{M}, S \not\sim \bar{M}, (S \vee P) \not\sim \bar{S}) \models_s S \not\sim P.$
Figure III		
AAI	Darapti	$(M \sim P, M \sim S, (S \vee M) \not\sim \bar{M}) \models_s S \not\sim \bar{P}.$
AII	Datisi	$(M \sim P, M \not\sim \bar{S}, (S \vee M) \not\sim \bar{M}) \models_s S \not\sim \bar{P}.$
IAI	Disamis	$(M \not\sim \bar{P}, M \sim S, (S \vee M) \not\sim \bar{M}) \models_s S \not\sim \bar{P}.$
EAO	Felapton	$(M \sim \bar{P}, M \sim S, (S \vee M) \not\sim \bar{M}) \models_s S \not\sim P.$
EIO	Ferison	$(M \sim \bar{P}, M \not\sim \bar{S}, (S \vee M) \not\sim \bar{M}) \models_s S \not\sim P.$
OAO	Bocardo	$(M \not\sim P, M \sim S, (S \vee M) \not\sim \bar{M}) \models_s S \not\sim P.$

Table 8: Traditional (logically valid) Aristotelian syllogisms of Figure I, II, and III (see Table 1) in terms of defaults and negated defaults, under the conditional event existential import assumption.

8. Conversion and reduction.

The most prominent methods of proof in Aristotelian syllogistics are *conversion*, *reductio* (by conversion), and *reductio ad impossibile* (by the compound law of transposition; see, e.g., [63, 86]). In this section we give some probabilistic results to show that *conversion* and *reductio* (by conversion) do not hold in our approach (Section 8.1). Then we show to what extent *reductio ad impossibile* can be applied within our approach: we will observe that by the application of the compound law of transposition to syllogisms of Figure II and Figure III the syllogisms can be reduced to Figure I and that they are hence *valid*. However, this method does not allow for distinguishing between *valid* and *s-valid* syllogisms and hence *reductio ad impossibile* is not *s-validity* preserving (Section 8.2).

8.1. Reductio by conversion.

According to Aristotle, three rules of *conversion* are sound (see, e.g., [63, 86]). Conversion means that the term position can be interchanged in sentence types I and E (i.e., *some S is P* logically implies *some P is S* and *no S is P* logically implies *no P is S*, respectively) and that *every S is P* logically implies *some P is S*. However, the assessment $p(P|S)$ does not constrain $p(S|P)$. Indeed, as we now show in Proposition 7, the assessment (x, y) on $(P|S, S|P)$ is coherent for every $(x, y) \in [0, 1]^2$. Therefore, none of these three rules of conversion hold in our approach.

Proposition 7 (Asymmetry of term order). *Let P, S be two logically independent events. The imprecise assessment $[0, 1]^2$ on $\mathcal{F} = (P|S, S|P)$ is t -coherent.*

Proof. Let P, S be two logically independent events. We show that the imprecise assessment $[0, 1]^2$ on $\mathcal{F} = (P|S, S|P)$ is totally coherent, by showing that every precise assessment $\mathcal{P} = (x, y) \in [0, 1]^2$ on \mathcal{F} is coherent. Let $\mathcal{P} = (x, y) \in [0, 1]^2$ be a precise assessment on \mathcal{F} . Then, the constituents C_h and the points Q_h associated with $(\mathcal{F}, \mathcal{P})$ are

$$C_1 = SP, C_2 = S\bar{P}, C_3 = \bar{S}P, C_0 = (x, y),$$

and

$$Q_1 = (1, 1), Q_2 = (0, y), Q_3 = (x, 0), Q_0 = (x, y) = \mathcal{P}.$$

We observe that $C_1 \vee C_2 \vee C_3 = S \vee P$. By Theorem 2, coherence of \mathcal{P} on \mathcal{F} requires that the following system

$$(\mathfrak{S}) \quad \mathcal{P} = \sum_{h=1}^3 \lambda_h Q_h, \quad \sum_{h=1}^3 \lambda_h = 1, \quad \lambda_h \geq 0, \quad h = 1, \dots, 3,$$

or equivalently

$$\begin{cases} \lambda_1 + x\lambda_3 = x, & \lambda_1 + y\lambda_2 = y, \\ \lambda_1 + \lambda_2 + \lambda_3 = 1, & \lambda_h \geq 0, \quad h = 1, 2, 3, \end{cases}$$

is solvable. In geometrical terms, this means that the condition $\mathcal{P} \in \mathfrak{S}$ is satisfied, where \mathfrak{S} is the convex hull of Q_1, Q_2, Q_3 . We distinguish three cases: (i) $x \neq 0$ and $y \neq 0$; (ii) $x = 0$; (iii) $y = 0$.

Case (i). We observe that $\mathcal{P} = \frac{xy}{x+y-xy}Q_1 + \frac{y(1-x)}{x+y-xy}Q_2 + \frac{x(1-y)}{x+y-xy}Q_3$, indeed it holds that

$$\frac{xy}{x+y-xy}(1, 1) + \frac{y(1-x)}{x+y-xy}(0, y) + \frac{x(1-y)}{x+y-xy}(x, 0) = \left(\frac{x^2+xy-x^2y}{x+y-xy}, \frac{xy+y^2-xy^2}{x+y-xy} \right) = \left(\frac{x(x+y-xy)}{x+y-xy}, \frac{y(x+y-xy)}{x+y-xy} \right) = (x, y).$$

Thus, system (\mathfrak{S}) is solvable and a solution is $\Lambda = (\lambda_1, \lambda_2, \lambda_3) = \left(\frac{xy}{x+y-xy}, \frac{y(1-x)}{x+y-xy}, \frac{x(1-y)}{x+y-xy} \right)$. From (3) we obtain that

$$\Phi_1(\Lambda) = \sum_{h:C_h \subseteq S} \lambda_h = \lambda_1 + \lambda_2 = \frac{y}{x+y-xy} > 0, \quad \Phi_2(\Lambda) = \sum_{h:C_h \subseteq P} \lambda_h = \lambda_1 + \lambda_3 = \frac{x}{x+y-xy} > 0.$$

Let $\mathcal{S}' = \left\{ \left(\frac{xy}{x+y-xy}, \frac{y(1-x)}{x+y-xy}, \frac{x(1-y)}{x+y-xy} \right) \right\}$ denote a subset of the set \mathcal{S} of all solutions of (\mathfrak{S}) . Then, $M'_1 = \max\{\Phi_1 : \Lambda \in \mathcal{S}'\} > 0$ and $M'_2 = \max\{\Phi_2 : \Lambda \in \mathcal{S}'\} > 0$ and hence $I'_0 = \emptyset$ (as defined in (5)). By Theorem 3, as (\mathfrak{S}) is solvable and $I'_0 = \emptyset$, the assessment $(x, y) \in]0, 1]^2$ is coherent.

Case (ii). In this case, as $x = 0$, it holds that $\mathcal{P} = (0, y) = Q_2$. Thus, system (\mathfrak{S}) is solvable and a solution is $\Lambda = (\lambda_1, \lambda_2, \lambda_3) = (0, 1, 0)$. From (3) we obtain that $\Phi_1(\Lambda) = \sum_{h:C_h \subseteq S} \lambda_h = \lambda_1 + \lambda_2 = 1$ and $\Phi_2(\Lambda) = \sum_{h:C_h \subseteq P} \lambda_h = \lambda_1 + \lambda_3 = 0$. Let $\mathcal{S}' = \{(0, 1, 0)\}$ denote a subset of the set \mathcal{S} of all solutions of (\mathfrak{S}) . Then, $M'_1 > 0$ and $M'_2 = 0$ and hence $I'_0 = \{2\}$ (as defined in (5)). We recall that the sub-assessment

$\mathcal{P}'_0 = (y)$ on $\mathcal{F}'_0 = \{S|P\}$ is coherent for every $y \in [0, 1]$. Then, by Theorem 3 the assessment $(0, y)$ on \mathcal{F} is coherent for every $y \in [0, 1]$. Then, every assessment $(x, y) \in \{0\} \times [0, 1]$ is coherent.

Case (iii). In this case, as $y = 0$, it holds that $\mathcal{P} = (x, 0) = Q_3$. Thus, system (\mathfrak{E}) is solvable and a solution is $\Lambda = (\lambda_1, \lambda_2, \lambda_3) = (0, 0, 1)$. From (3) we obtain that $\Phi_1(\Lambda) = \sum_{h: C_h \subseteq S} \lambda_h = \lambda_1 + \lambda_2 = 0$ and $\Phi_2(\Lambda) = \sum_{h: C_h \subseteq P} \lambda_h = \lambda_1 + \lambda_3 = 1$. Let $\mathcal{S}' = \{(0, 0, 1)\}$ denote a subset of the set \mathcal{S} of all solutions of (\mathfrak{E}) . Then, $M'_1 = 0$ and $M'_2 > 0$ and hence $I'_0 = \{1\}$ (as defined in (5)). We recall that the sub-assessment $\mathcal{P}'_0 = (x)$ on $\mathcal{F}'_0 = \{P|S\}$ is coherent for every $x \in [0, 1]$. Then, by Theorem 3 the assessment $(x, 0)$ on \mathcal{F} is coherent for every $x \in [0, 1]$. Then, every assessment $(x, y) \in [0, 1] \times \{0\}$ is coherent.

Therefore, every assessment $(x, y) \in [0, 1]^2$ is coherent and hence the imprecise assessment $[0, 1]^2$ on \mathcal{F} is t-coherent. \square

Moreover, Aristotle also proposed methods of *reduction* to prove validity. The method of reduction by conversion consists in “reducing” all syllogisms to “perfect” syllogisms of Figure 1. Only syllogisms of Figure 1 are perfect because the “transitivity of the connexion between the terms [is] obvious at a glance” ([58, p. 73]): perfect syllogisms can be seen as self-evident without requiring further proof (for a discussion of “perfect” see, e.g., [33]). More specifically, Aristotle’s full program consists in showing validity by reduction to *Barbara* and *Celarent*. Since this method of reduction requires conversion ([58, p. 236]), reduction is also not valid in our approach.

In the next two remarks we observe that the conditional event existential import of Figure II does not follow from any syllogism of Figure I (Remark 15) and *vice versa* (Remark 16). More specifically, assuming any degrees of belief in the premises of syllogisms of Figure I (Figure II, respectively) does not imply a positive degree of belief in the conditional event existential import of Figure II, i.e., $p(S|(S \vee P)) > 0$ (Figure I, i.e., $p(S|(S \vee M)) > 0$, respectively).

Remark 15. Let $\mathcal{P} = (x, y, t, 0)$, with $(x, y, t) \in [0, 1]^3$, be a probability assessment on $\mathcal{F} = (P|M, M|S, S|(S \vee M), S|(S \vee P))$, where S, M , and P are three logically independent events. We show that $\mathcal{P} = (x, y, t, 0)$ on \mathcal{F} is coherent for every $(x, y, t) \in [0, 1]^3$. The constituents C_h and the points Q_h associated with $(\mathcal{F}, \mathcal{P})$ are given in Table 9. By Theorem 2, coherence of $\mathcal{P} = (x, y, t, 0)$ on \mathcal{F} requires that

Table 9: Constituents C_h and points Q_h associated with the probability assessment $\mathcal{P} = (x, y, t, 0)$ on $\mathcal{F} = (P|M, M|S, S|(S \vee M), S|(S \vee P))$.

	C_h	Q_h	
C_1	SMP	$(1, 1, 1, 1)$	Q_1
C_2	$SM\bar{P}$	$(0, 1, 1, 1)$	Q_2
C_3	$S\bar{M}P$	$(x, 0, 1, 1)$	Q_3
C_4	$S\bar{M}\bar{P}$	$(x, 0, 1, 1)$	Q_4
C_5	$\bar{S}MP$	$(1, y, 0, 0)$	Q_5
C_6	$\bar{S}M\bar{P}$	$(0, y, 0, 0)$	Q_6
C_7	$\bar{S}\bar{M}P$	$(x, y, t, 0)$	Q_7
C_0	$\bar{S}\bar{M}\bar{P}$	$(x, y, t, 0)$	$Q_0 = \mathcal{P}$

the following system is solvable

$$(\mathfrak{E}) \quad \mathcal{P} = \sum_{h=1}^7 \lambda_h Q_h, \quad \sum_{h=1}^7 \lambda_h = 1, \quad \lambda_h \geq 0, \quad h = 1, \dots, 7,$$

In geometrical terms, this means that the condition $\mathcal{P} \in \mathfrak{S}$ is satisfied, where \mathfrak{S} is the convex hull of Q_1, \dots, Q_7 . We observe that $\mathcal{P} = Q_6$. Thus, system (\mathfrak{E}) is solvable and a solution is $\Lambda = (\lambda_1, \dots, \lambda_7) =$

$(0, 0, 0, 0, 0, 0, 1)$. From (3) we obtain that $\Phi_1(\Lambda) = \sum_{h:C_h \subseteq M} \lambda_h = \lambda_1 + \lambda_2 + \lambda_5 + \lambda_6 = 0$, $\Phi_2(\Lambda) = \sum_{h:C_h \subseteq S} \lambda_h = \lambda_1 + \lambda_2 + \lambda_3 + \lambda_4 = 0$, $\Phi_3(\Lambda) = \sum_{h:C_h \subseteq S \vee M} \lambda_h = \lambda_1 + \lambda_2 + \lambda_3 + \lambda_4 + \lambda_5 + \lambda_6 = 0$, $\Phi_4(\Lambda) = \sum_{h:C_h \subseteq S \vee P} \lambda_h = \lambda_1 + \lambda_2 + \lambda_3 + \lambda_4 + \lambda_5 + \lambda_7 = 1$. Let $\mathcal{S}' = \{(0, 0, 0, 0, 0, 0, 1)\}$ denote a subset of the set \mathcal{S} of all solutions of (Ξ) . Then, $M'_1 = M'_2 = M'_3 = 0$, $M'_4 = 1$ and hence $I'_0 = \{1, 2, 3\}$ (as defined in (5)). By Theorem 3, as (Ξ) is solvable and $I'_0 = \{1, 2, 3\}$, it is sufficient to check the coherence of the sub-assessment $\mathcal{P}'_0 = (x, y, t)$ on $\mathcal{F}'_0 = (P|M, M|S, S|(S \vee M))$ in order to check the coherence of $(x, y, t, 0)$ on \mathcal{F} . From Proposition 2, by replacing A, B, C with S, M, P , respectively, it holds that (x, y, t) on $\mathcal{F}'_0 = (P|M, M|S, S|(S \vee M))$ is coherent for every $(x, y, t) \in [0, 1]^3$. Therefore, $(x, y, t, 0)$ on \mathcal{F} is coherent for every $(x, y, t) \in [0, 1]^3$.

Remark 16. Let $\mathcal{P} = (x, y, t, 0)$, with $(x, y, t) \in [0, 1]^3$, be a probability assessment on $\mathcal{F} = (M|P, \bar{M}|S, S|(P \vee S), S|(S \vee M))$, where S, M , and P are three logically independent events. We show that $\mathcal{P} = (x, y, t, 0)$ on \mathcal{F} is coherent for every $(x, y, t) \in [0, 1]^3$. The constituents C_h and the points Q_h associated with $(\mathcal{F}, \mathcal{P})$ are given in Table 10. By Theorem 2, coherence of $\mathcal{P} = (x, y, t, 0)$ on \mathcal{F} requires

Table 10: Constituents C_h and points Q_h associated with the probability assessment $\mathcal{P} = (x, y, t, 0)$ on $\mathcal{F} = (M|P, \bar{M}|S, S|(S \vee P), S|(S \vee M))$.

	C_h	Q_h	
C_1	SMP	$(1, 0, 1, 1)$	Q_1
C_2	$SM\bar{P}$	$(x, 0, 1, 1)$	Q_2
C_3	$S\bar{M}P$	$(0, 1, 1, 1)$	Q_3
C_4	$S\bar{M}\bar{P}$	$(x, 1, 1, 1)$	Q_4
C_5	$\bar{S}MP$	$(1, y, 0, 0)$	Q_5
C_6	$\bar{S}M\bar{P}$	$(x, y, t, 0)$	Q_6
C_7	$\bar{S}\bar{M}P$	$(0, y, 0, 0)$	Q_7
C_0	$\bar{S}\bar{M}\bar{P}$	$(x, y, t, 0)$	$Q_0 = \mathcal{P}$

that the following system is solvable

$$(\Xi) \quad \mathcal{P} = \sum_{h=1}^7 \lambda_h Q_h, \quad \sum_{h=1}^7 \lambda_h = 1, \quad \lambda_h \geq 0, \quad h = 1, \dots, 7,$$

In geometrical terms, this means that the condition $\mathcal{P} \in \mathfrak{S}$ is satisfied, where \mathfrak{S} is the convex hull of Q_1, \dots, Q_7 . We observe that $\mathcal{P} = Q_6$. Thus, system (Ξ) is solvable and a solution is $\Lambda = (\lambda_1, \dots, \lambda_7) = (0, 0, 0, 0, 0, 1, 0)$. From (3) we obtain that $\Phi_1(\Lambda) = \sum_{h:C_h \subseteq P} \lambda_h = \lambda_1 + \lambda_3 + \lambda_5 + \lambda_7 = 0$, $\Phi_2(\Lambda) = \sum_{h:C_h \subseteq S} \lambda_h = \lambda_1 + \lambda_2 + \lambda_3 + \lambda_4 = 0$, $\Phi_3(\Lambda) = \sum_{h:C_h \subseteq S \vee P} \lambda_h = \lambda_1 + \lambda_2 + \lambda_3 + \lambda_4 + \lambda_5 + \lambda_7 = 0$, and $\Phi_4(\Lambda) = \sum_{h:C_h \subseteq S \vee M} \lambda_h = \lambda_1 + \lambda_2 + \lambda_3 + \lambda_4 + \lambda_5 + \lambda_6 = 1$. Let $\mathcal{S}' = \{(0, 0, 0, 0, 0, 1, 0)\}$ denote a subset of the set \mathcal{S} of all solutions of (Ξ) . Then, $M'_1 = M'_2 = M'_3 = 0$, $M'_4 = 1$ and hence $I'_0 = \{1, 2, 3\}$ (as defined in (5)). By Theorem 3, as (Ξ) is solvable and $I'_0 = \{1, 2, 3\}$, it is sufficient to check the coherence of the sub-assessment $\mathcal{P}'_0 = (x, y, t)$ on $\mathcal{F}'_0 = (M|P, \bar{M}|S, S|(P \vee S))$ in order to check the coherence of $(x, y, t, 0)$ on \mathcal{F} . From Proposition 4, by replacing A, B, C with S, M, P , respectively, it holds that (x, y, t) on $\mathcal{F}'_0 = (M|P, \bar{M}|S, S|(P \vee S))$ is coherent for every $(x, y, t) \in [0, 1]^3$. Therefore, $(x, y, t, 0)$ on \mathcal{F} is coherent for every $(x, y, t) \in [0, 1]^3$.

We observe from Remark 15 that the conditional event existential import of Figure II does not follow from any syllogism of Figure I, since $p(P|M) = x$, $p(M|S) = y$, and $p(S|(S \vee M)) = t > 0$ does not imply $p(S|(S \vee P)) > 0$, because the assessment $p(S|(S \vee P)) = 0$ is a coherent extension from (x, y, t) . Likewise, we observe from Remark 16 that the conditional event existential import of Figure I does not

follows from any syllogism of Figure II, since $p(M|P) = x$, $p(\bar{M}|S) = y$, and $p(S|(S \vee P)) = t > 0$ does not imply $p(S|(S \vee M)) > 0$, because the assessment $p(S|(S \vee M)) = 0$ is a coherent extension from (x, y, t) .

In Aristotelian syllogistics, for example, *Cesare* can be reduced by conversion to *Celarent* as follows (see, e.g., [86], table in Section 5.4): from the premises of *Cesare*, i.e., *no P is M* and *every S is M* it follows by conversion that *no M is P* and *every S is M*, which in turn implies by *Celarent* that *no S is P*. In our approach however, this inference does not hold: we observe that the premises of *Cesare*, i.e., $p(M|P) = 0$, $p(M|S) = 1$, $p(S|(S \vee P)) > 0$ (see (41)), do not imply the premises of *Celarent*, i.e., $p(P|M) = 0$, $p(M|S) = 1$, $p(S|(S \vee M)) > 0$, (see (19)), since $p(S|S \vee M) = 0$ is coherent under the premises of *Cesare* (Remark 16). Therefore, *Cesare* can not be reduced by conversion to *Celarent* (which requires that $p(S|S \vee M) > 0$) in our approach.

8.2. *Reductio ad impossibile*.

Aristotle described also validity proofs by *reductio ad impossibile*. According to Łukasiewicz, this should correspond to the application of the *compound law of transposition* ([63, p. 56]), i.e., *if (A and B, then C), then (if A and not-C, then not-B)*. For example, by instantiating *Barbara* in the first conditional (i.e., for A and B *Barbara*'s premises and for C its conclusion), implies logically *Baroco* by suitable instantiations in the second conditional of the compound law of transposition ([63, p. 56]).

In terms of defaults, it can be easily shown that *reductio ad impossibile* holds in our approach because each valid syllogism of Figure II and Figure III can be reduced to a valid syllogism of Figure I. For example, *Camestres* of Figure II can be reduced to *Darii* of Figure I as follows. The compound law of transposition applied to *Camestres* yields the inference: *from* $P \sim M$, $S \not\sim \bar{P}$, *and* $(S \vee P) \not\sim \bar{S}$ *infer* $S \not\sim \bar{M}$. By interchanging P and M, we obtain the valid inference *Darii*: *from* $M \sim P$, $S \not\sim \bar{M}$, *and* $(S \vee M) \not\sim \bar{S}$ *infer* $S \not\sim \bar{P}$. For a sample reduction of a Figure III syllogism to Figure I consider *Darapti*. The application of the compound law of transposition to *Darapti* yields the inference *from* $S \sim \bar{P}$, $M \sim S$, *and* $(S \vee M) \not\sim \bar{M}$ *infer* $M \not\sim P$. By interchanging S and M, we obtain the valid inference *Celarent* of Figure I: *from* $M \sim \bar{P}$, $S \sim M$, *and* $(S \vee M) \not\sim \bar{S}$ *infer* $S \not\sim P$. Note that while *Darapti* is *s-valid*, *Celarent* is *valid* but not *s-valid* in our semantics. Since the compound law of transposition ignores this difference, it does not preserve *s-validity*.

Our validity proofs are based on the probability propagation rules, which are different for each figure. To what extent they may be reduced to each other, given the asymmetries of the term order between the figures and the different existential import assumptions, is a topic of future research.

9. Generalized quantifiers.

The basic syllogistic sentence types A, E, I, O involve quantifiers which we represent by special cases of probability evaluations, namely equal to 1 or 0 for the universal quantifiers, and excluding 0 or 1 for the particular quantifiers. A natural generalization of such quantifiers is to use thresholds between 0 and 1. Then, we obtain generalized (or intermediate) quantifiers (see, e.g., [5, 66, 67]). For instance, the statement *Most S are P* (sentence type T, for the notation see [67] see also [64]) can be interpreted by the conditional probability assessment $p(P|S) \geq x$, where x denotes a suitable threshold (e.g., greater than 0.5). Likewise, the statement *Most S are not-P* (sentence type D) can be interpreted by $p(\bar{P}|S) \geq x$ with a suitable threshold. The choice of the threshold depends on the context of the speaker. By using such sentences, we can construct and check the validity of syllogisms involving generalize quantifiers. Specifically, validity can be investigated by suitable instatiations of the probability propagation rules, we proved in the previous sections. Consider for instance the following generalization of *Baroco*:

ADD-Figure II: *All P are M.*
Most S are not-M.
 Therefore, *Most S are not-P.*

In this syllogism, the first premise is of the sentence type A but the second premise and the conclusion consist of sentence type D. In our semantics this syllogism is interpreted as follows: from the premises $p(M|P) = 1$ and $p(\bar{M}|S) \geq y$ and the conditional event existential import assumption $p(S|(S \vee P)) > 0$ infer the conclusion $p(\bar{P}|S) \geq y$, where $y > 0.5$. To prove the validity of this syllogism instantiate S, M, P in Theorem 8 for A, B, C with $x_1 = x_2 = 1, y_1 > 0, y_2 = 1, t_1 > 0$, and $t_2 = 1$. Then, we obtain $z^* = y_1$ and $z^{**} = 1$. Therefore, the set Σ of coherent extensions on $\bar{P}|S$ of the imprecise assessment $\{1\} \times [y_1, 1] \times (0, 1]$ on $(M|P, \bar{M}|S, S|(S \vee P))$ is $\Sigma = [y_1, 1]$. Then, we obtain the following generalization of Equation (39):

$$(p(M|P) = 1, p(\bar{M}|S) \geq y_1, p(S|(S \vee P)) > 0) \models_s p(\bar{P}|S) \geq y_1. \quad (67)$$

By choosing $y_1 > 0.5$, Equation (67) validates ADD-Figure II.

Likewise, we can obtain an extension of Darii (17) involving generalized quantifiers. Indeed, by instantiating S, M, P in Theorem 6 for A, B, C with $x_1 = x_2 = 1, y_1 > 0, y_2 = 1, t_1 > 0$, and $t_2 = 1$. Then, we obtain $z^* = \max \left\{ 0, x_1 y_1 - \frac{(1-t_1)(1-x_1)}{t_1} \right\} = y_1$ and $z^{**} = 1$. Therefore, the set Σ of coherent extensions on $P|S$ of the imprecise assessment $\{1\} \times [y_1, 1] \times (0, 1]$ on $(P|M, M|S, S|(S \vee M))$ is $\Sigma = [y_1, 1]$. By Definition 7,

$$(p(P|M) = 1, p(M|S) \geq y_1, p(S|(S \vee M)) > 0) \models_s p(P|S) \geq y_1. \quad (68)$$

Equation (68) generalizes (17) and validates the following generalized syllogism, when $y_1 > 0.5$

ATT-Figure I: *All M are P.*
Most S are M.
 Therefore, *Most S are P.*

While, as pointed in Remark 4, valid inferences can generally be obtained from strengthening the premises or weakening the conclusion of valid inferences, it is also possible to check the validity of syllogisms with weaker premises by exploiting the respective probability propagation rules. For an example of generalized syllogism of Figure III consider the following which is a version of Darapti with weakened premises:

TTI-Figure III: *Most M are P.*
Most M are S.
 Therefore, *some S is P.*

Indeed, by instantiating S, M, P in Theorem 10 for A, B, C with $x_1 = y_1 > 0.5, x_2 = y_2 = 1, t_1 = t > 0$, and $t_2 = 1$. Then, as $x_1 + y_1 - 1 > 0$, we obtain $z^* = \frac{t(2x_1-1)}{1-t(1-x_1)}$ and, as $t_1(y_1 - x_2) \leq 0$, we obtain $z^{**} = 1$. We observe that $z^* > t(2x_1 - 1) > 0$ because $\frac{t}{1-t(1-x_1)} > t$ and $x_1 > 0.5$. Therefore, the set Σ of coherent extensions on $P|S$ of the imprecise assessment $[x_1, 1] \times [x_1, 1] \times (0, 1]$ on $(P|M, M|S, S|(S \vee M))$, with $x_1 > 0.5$, is $\Sigma = \bigcup_{t \in (0, 1]} \left[\frac{t(2x_1-1)}{1-t(1-x_1)}, 1 \right] = (0, 1]$. Then,

$$(p(P|M) \geq x_1, p(S|M) \geq x_1, p(M|(S \vee M)) > 0) \models_s p(P|S) > 0, \quad (69)$$

validates TTI-Figure III, which is a generalization of Darapti involving generalized quantifiers where the premises are weakened.

By applying the probability propagation rules (for precise or interval-valued probability assessments) of Figures I, II, and III further syllogisms with generalized quantifiers can be obtained.

10. Concluding remarks.

In this paper we presented a probabilistic interpretation of the basic syllogistic sentence types (A, E, I, O) and suitable existential import assumptions in terms of probabilistic constraints. By exploiting coherence, we introduced the notion of validity and strict validity for probabilistic inferences involving imprecise probability assessments.

For each Figure I, II, and III, we verified the coherence of any probability assessment in $[0, 1]^3$ on the three conditional events which are involved in the major and the minor premise and the conclusion. These results show that, without existential import assumption, all traditionally valid syllogisms are probabilistically non-informative. We also verified for all three figures the total coherence of the imprecise assessment $[0, 1]^3$ on the conditional events in the premise set including the existential import. Then, we derived the interval of all coherent extensions on the conclusion for every coherent (precise or interval-valued) probability assessment on the premise set for each of the three figures. These results were then exploited to prove the validity or strict validity of our probabilistic interpretation of all traditionally valid syllogisms of the three figures: Barbara, Barbari, Darii, Celarent, Celaront, and Ferio of Figure I; Camestres, Camestrop, Baroco, Cesare, Cesaro, and Festino of Figure II; Datisi, Darapti, Ferison, Felapton, Disamis, and Bocardo of Figure III. As mentioned before the coherence approach is more general compared to the standard approaches where the conditional probability $p(E|H)$ is defined by $p(E \wedge H)/p(H)$, where $p(H)$ must be positive. Indeed, we showed that the conditional event existential import assumption (which is sufficient for validity) is weaker than the requirement of positive conditioning events for the conditional events involved in the syllogisms.

We then built a bridge from our probability semantics of the Aristotelian syllogisms to nonmonotonic reasoning by interpreting the basic syllogistic sentence types by suitable defaults and negated defaults. We also showed how some new valid syllogisms can be obtained by strengthening our existential import assumption. Moreover, by this procedure, the traditionally not valid AAA of Figure III can be validated. These new syllogisms, which are expressed in terms of defaults only, are p-valid inference rules which we propose, together with default versions of the traditional ones for future research in nonmonotonic reasoning. Then we investigated Aristotelian methods of proof within our framework. We observed that *reductio* by conversion does not work while *reductio ad impossibile* can be applied in our approach. However, the method of *reductio ad impossibile* by suitable applications of the *compound law of transposition* yields only validity by reducing syllogisms of Figure II and Figure III to Figure I: it ignores our distinction between *valid* and *s-valid* syllogisms. Finally, we showed how the probability propagation rules can be used to analyze the validity and the strict validity of syllogisms involving generalized quantifiers. Specifically, sentence like *most S are P* can be interpreted by imprecise probability assessments.

We presented a general method to validate probabilistically non-informative inferences by adding additional premises. These additional premises can be existential import assumptions, (negated) defaults or other probabilistic constraints. These methods can be used to solve inference problems in general with applications in various disciplines. For instance, our probabilistic interpretation of Aristotelian syllogisms can serve as new rationality framework for the psychology of reasoning, which has a long tradition of using syllogistics for assessing the rationality of human inference. Moreover, our results on generalized quantifiers can be applied for investigating semantic and pragmatic problems involving quantification in linguistics. Furthermore, our bridges to nonmonotonic reasoning show the applicability of the proposed approach in reasoning under uncertainty, knowledge representation, and artificial intelligence. This selection of applications points to new bridges among our semantics, Aristotelian syllogistics, and various disciplines.

We will devote future work to apply our semantics to nonmonotonic reasoning and its relation to probability logic (see, e.g., [53, 54]). Specifically, we will investigate the validity of our default versions of the

syllogisms in the light of different systems of nonmonotonic reasoning.

Future work will also be devoted to the full probabilistic analysis of Figure IV. Indeed, categorical syllogisms of Figure IV go beyond the scope of this paper for two reasons. Firstly, they were introduced after Aristotle's *Analytica Priora* and are therefore not considered as (proper) Aristotelian syllogisms. Secondly, in contrast to the first three figures, based on preliminary results, there seems not to exist a unique conditional event existential import assumption for validating syllogisms of Figure IV ([74]). Therefore, several probability propagation rules should be developed only for this figure, which cannot be done in this paper owing to lack of space.

Finally, another strand of future research will focus on further generalizations of Aristotelian syllogisms by applying the theory of compounds of conditionals under coherence (see, e.g., [48, 49]). While, in the present paper, we connected the syllogistic terms S and P in the basic syllogistic sentence types by conditional events $P|S$, this theory of compounds of conditionals allows for obtaining generalized syllogistic sentence types like *If S_1 are P_1 , then S_2 are P_2* (i.e., $(P_2|S_2)|(P_1|S_1)$) by suitable nestings of conditional events. Interestingly, in the context of conditional syllogisms, the resulting uncertainty propagation rules coincide with the respective non-nested versions (see, e.g., [84, 85, 83]). Future research is needed to investigate whether similar results can be obtained in the context of such generalized Aristotelian syllogisms.

The various possibilities for applications and generalizations of Aristotelian syllogisms call for future research and highlight the impressive research impact of Aristotle's original work.

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Declaration of interests

The authors declare that they have no known competing financial interests or personal relationships that could have appeared to influence the work reported in this paper.

The authors declare the following financial interests/personal relationships which may be considered as potential competing interests:

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