

1 **COMPARING MINI-DISK INFILTROMETER, BEST METHOD AND SOIL CORE**
2 **ESTIMATES OF HYDRAULIC CONDUCTIVITY OF A SANDY-LOAM SOIL**

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11

12 **ABSTRACT**

13 Saturated, K_s , and near-saturated, K , soil hydraulic conductivity control many hydrological
14 processes but they are difficult to measure. Comparing methods to determine K_s and K is a
15 means to establish how and why these soil hydrodynamic properties vary with the applied
16 method. A comparison was established between the K_s and K values of a sandy-loam soil
17 obtained, in the field, with the BEST (Beerkan Estimation of Soil Transfer parameters)
18 method of soil hydraulic characterization and an unconfined MDI (mini-disk infiltrometer)
19 experiment and, in the laboratory, with a confined MDI experiment and the CHP (constant-
20 head permeameter) method. Using for the BEST calculations the soil porosity instead of the
21 saturated soil water content yielded 1.4 to 1.1 times higher estimates of K_s and K , depending
22 on the pressure head, and differences decreased in more unsaturated soil conditions. The
23 confined MDI experiment yielded 22% - 77% higher K values than the unconfined MDI
24 experiment, depending on the established pressure head, h_0 , and differences were not
25 significant for $h_0 = -1$ cm. In the close to saturation region, the soil hydraulic conductivity

26 function predicted with BEST did not generally agree well with the K_s and K values obtained
27 in the laboratory by a direct application of the Darcy's law. In particular, BEST yielded a 5.6
28 times smaller K_s value than the CHP method and up to an 8.1 times higher K value than the
29 MDI. Overall, i) the two application methods of the MDI yielded relatively similar results,
30 especially close to saturation, and ii) there was not a satisfactory agreement between the field
31 (BEST) and the laboratory (MDI plus CHP) determination of soil hydraulic conductivity close
32 to saturation, unless a comparison was made with the same soil water content. The detected
33 differences were probably attributable to soil spatial variability, overestimation of K_s in the
34 laboratory due to preferential flow phenomena, underestimation of K_s in the field due to air
35 entrapment in the soil and infiltration surface disturbance, inability of BEST to describe the
36 actual soil hydraulic conductivity function at the sampled field site. Testing BEST predictions
37 of K_s and K in other soils appears advisable and combining the MDI and CHP methods
38 appears a rather simple means to make these checks. These additional investigations could
39 improve interpretation of the differences between methods, which is an important step for
40 properly selecting a method yielding K_s and K data appropriate for an intended use.

41

42 **Keywords:** Soil hydraulic conductivity; Field methods; Laboratory methods; Mini-disk
43 infiltrometer; Constant-head permeameter; BEST methods of soil hydraulic characterization.

44

45 **INTRODUCTION**

46 Knowledge of the hydrodynamic soil properties is essential for understanding water flow and
47 solute transport processes in the soil-plant system (Autovino et al., 2018; Basile et al., 2020;
48 Farzamian et al., 2021). Hydraulic conductivity of saturated, K_s , and near-saturated, K , soil
49 are particularly important since flow and solute transport processes occur at the highest
50 possible rates at or close to saturation. Saturated and near-saturated hydraulic conductivity

51 can be determined by many methods (Carter and Gregorich, 2007; Dane et al., 2018; Angulo-
52 Jaramillo et al., 2016), differing for various aspects such as the application ambit (laboratory,
53 field), the established flow field (one-, 1D, or three-, 3D, dimensional), the information used
54 to determine K_s or K (transient, steady-state, both transient and steady-state).

55 The choice of a method over another can be expected to have appreciable effects on
56 determination of K_s and K , which raises the problem of choosing an appropriate measurement
57 method in relation to the specific purpose of the sampling campaign and considering the
58 advantages and disadvantages of the possibly usable methods (Alagna et al., 2016; Paige and
59 Hillel, 1993; Reynolds et al., 2000). For example, laboratory methods are relatively
60 comfortable to apply and they can guarantee highly controlled conditions which positively
61 affect the reliability of the individual measurement. However, soil compaction and alteration
62 of pore connectivity represent two of the possible adverse consequences of using a
63 presumably undisturbed sample in the laboratory (Bouma, 1982; Lauren et al., 1988; Lee et
64 al., 1985). Soil disturbance can be controlled to some extent when measurements are
65 performed in the field, which also implies maintaining the connection between the sampled
66 soil volume and the surrounding soil. However, field experiments are generally more tiring
67 and also less accurate than the laboratory ones since they have to be performed in
68 environmental conditions that are not always fully favorable for carrying out measurement
69 activities. In addition, many potential limitations of several field methods can be identified
70 such as relatively small sample size, possible edge flow along the ring wall, disturbance of the
71 exposed soil surface due to water application, difficulty to guarantee a correspondence
72 between theory and practice (Bagarello and David, 2020; Reynolds et al., 2008; Xu et al.,
73 2012). In this complex context, one of the few sources of information from which
74 practitioners can choose the appropriate methods for their specific circumstances is provided
75 by comparisons between alternative methods for measuring K_s or K (Ghosh et al., 2019;

76 Reynolds et al., 2000). These comparisons are important also because, especially on large
77 areas, K_s or K data can be collected by applying different methods. According to Braud et al.
78 (2017), in this particular case it is necessary to develop appropriate methodologies for
79 creating an equivalent set of hydraulic conductivity data from data obtained with different
80 methods. Therefore, the comparison between K_s and K determination methods continues to
81 remain a central aspect of soil hydrology research.

82 Simple methods to determine soil hydraulic conductivity include BEST (Beerkan Estimation
83 of Soil Transfer parameters) methods (Angulo-Jaramillo et al., 2019, 2016; Bagarello et al.,
84 2014; Lassabatère et al., 2006; Yilmaz et al., 2010), the mini-disk infiltrometer (MDI; Dohnal
85 et al., 2010; METER Group, 2021) and the constant-head permeameter (CHP) method
86 (Reynolds and Elrick, 2002).

87 With BEST, a 3D field infiltration run under a nearly null ponded depth of water yields an
88 estimate of K_s and the η parameter of the Brooks and Corey (1964) hydraulic conductivity
89 function. Therefore, a given function is assumed to describe the relationship between K and
90 the volumetric soil water content, θ , and the methodology produces an estimate of the
91 parameters of this function.

92 The MDI is a miniaturized tension infiltrometer that allows simple and rapid determination of
93 the soil hydraulic conductivity corresponding to fixed pressure head values, h , in the range
94 from -0.5 cm to -6 cm. Typically, the device is used in the field to establish a 3D infiltration
95 process at an established h value (Alagna et al., 2013; Fodor et al., 2011; Gonzalez-Sosa et al.,
96 2010), but it was also applied to anthropic soils and green infrastructures substrates (Bondi et
97 al., 2023; Gadi et al., 2017; Radinja et al., 2019). The corresponding K value is then obtained
98 according to Zhang (1997) and Dohnal et al. (2010). However, the MDI has also been used in
99 the laboratory on soil columns to establish 1D infiltration processes (Assouline and Narkis,
100 2011; Kargas et al., 2018). Using the unit hydraulic gradient (UHG) method (Klute and

101 Dirksen, 1986) with the MDI, a given sample can be equilibrated at fixed, and high (close to
102 zero), h values to obtain points of the hydraulic conductivity curve close to saturation
103 (Bagarello et al., 2007).

104 The CHP represents the standard method for determining K_s in the laboratory and it is often
105 used as a benchmark for evaluating other methods (Reynolds et al., 2000). A 1D flow process
106 is established under a constant hydraulic head on an initially saturated soil sample (Madsen et
107 al., 2008). Knowledge of the hydraulic head gradient and measurement of volumetric flow
108 rate yields the K_s value by direct application of the Darcy's law.

109 Considering BEST, the MDI and the CHP, alone or in some combination among them, as
110 possible methods to obtain K_s or K data leads to recognize that there are at least three issues
111 that require investigation and development.

112 According to the original BEST application procedure (Lassabatère et al., 2006), the saturated
113 soil has to be sampled at the end of an infiltration run to determine the saturated gravimetric
114 water content which is then transformed into a volumetric value, θ_s , by considering the dry
115 soil bulk density. With another simpler and largely applied approach, θ_s is assumed to
116 coincide with soil porosity, ϕ (Bagarello et al., 2011; Di Prima, 2015; Mubarak et al., 2009a;
117 Xu et al., 2009; Yilmaz et al., 2010). The effect of the θ_s estimating method on the BEST
118 prediction of soil hydraulic properties has been tested with somewhat contrasting results. For
119 example, Alagna et al. (2016) suggested that sampling the soil confined by the ring at the end
120 of the beerkan run to obtain an experimental value of θ_s could be expected to yield a more
121 reliable estimation of soil hydraulic properties in comparison with that obtained by assuming
122 a coincidence between θ_s and ϕ . Instead, the conclusion by Di Prima et al. (2017) was that the
123 assumed coincidence between θ_s and ϕ as an alternative approach to the direct measurement
124 of θ_s could be expected not to have a strong effect on estimation of K_s . Therefore, it does not
125 seem clear to what extent ϕ represents a valid alternative to the direct measurement of θ_s .

126 For a fixed pressure head, h , the mean K value of the undisturbed soil in an area of interest
127 can be obtained by field or laboratory MDI runs. The dependence of K on the MDI
128 application method is unknown since the MDI has rarely been applied to establish both 3D
129 and 1D infiltration processes. An exception is the investigation by Kargas et al. (2018), whose
130 objective however was to determine the infiltration shape parameter, γ , of the infiltration
131 model by Haverkamp et al. (1994). Consequently, the unconfined 3D and confined 1D MDI
132 runs were carried out in the laboratory on repacked soil samples. The outcome of a
133 comparison between field and laboratory determinations of K on undisturbed soil is difficult
134 to predict *a-priori*. On the one hand, a certain similarity can be expected since the size of the
135 sample, that can be expected to affect K determination (Reynolds et al., 2000), does not vary
136 much between a field and a laboratory experiment. On the other hand, however, several other
137 factors could induce a difference between field and laboratory determination of K with the
138 MDI. For example, differences in the established flow field (3D in the field and 1D in the
139 laboratory) could determine differences in K estimation since flow is not forced to follow a
140 pre-established direction only in the first case (Reynolds and Elrick, 1985). Soil spatial
141 variability (Logsdon and Jaynes, 1996) can affect a comparison between 3D and 1D MDI
142 experiments. A reason is that, in the laboratory, all K values can be determined on a single
143 sample regardless of the established h values whereas, in the field, each $K(h)$ data point is
144 obtained at a different sampling point. Further, differences can also be expected as a
145 consequence of the applied method to analyze the data, that is the Darcy law in the laboratory
146 (Klute and Dirksen, 1986) and an infiltration model in the field (Dohnal et al., 2010; Zhang,
147 1997).

148 BEST (Lassabatère et al., 2006) allows a field determination of the unsaturated hydraulic
149 conductivity function according to the Brooks and Corey (1964) model. An independent
150 estimation of near-saturated K values can be obtained by collecting an undisturbed soil

151 sample in the field and using it in the laboratory for a sequence of 1D MDI runs followed by a
152 CHP run. In the former case, the experiment is very simple but it is assumed that K decreases
153 for smaller (more negative) pressure heads according to a pre-established law. In the latter
154 case, the experiment is longer and it only yields some discrete K values, depending on the
155 number of applied pressure heads. Comparing these two methods to obtain hydraulic
156 conductivity is advisable. A reason is that BEST methods have been largely applied in many
157 circumstances (Angulo-Jaramillo et al., 2019) but their predictions have been compared with
158 soil hydraulic properties obtained with independent methods only in an overall limited
159 number of investigations, not always with unequivocal results (Alagna et al., 2016; Bagarello
160 and Iovino, 2012; Castellini et al., 2018). Supporting the usability of BEST methods could
161 open new perspectives of practical interest. For example, BEST can potentially be used to
162 also obtain an estimate of the macroscopic capillary length (Di Prima et al., 2020; White and
163 Sully, 1987) and this soil parameter allows estimating bulb geometric variables for both
164 buried and surface infiltration point sources (Baiamonte et al., 2024; Philip, 1984). Therefore,
165 BEST experiments could be suggested for designing point irrigation systems taking into
166 account spatial variability of soil hydraulic properties, with implications in terms of water
167 saving and efficiency of water distribution.

168 The general objective of this investigation was to compare saturated and near-saturated
169 hydraulic conductivity of a sandy-loam soil obtained with BEST, MDI and CHP methods.
170 The specific objectives were to: i) compare soil hydraulic conductivity obtained with BEST
171 when two different methods for estimating the saturated volumetric water content are used; ii)
172 compare, for fixed pressure head values, the soil hydraulic conductivity obtained with field
173 and laboratory application of the MDI; and iii) compare the soil hydraulic conductivity
174 relationship obtained with BEST with that determined by using 1D MDI and CHP runs for the
175 close to saturation region.

176

177 **MATERIALS AND METHODS**

178

179 **Field site**

180 The experimental site is located near Palermo (Western Sicily, Italy), in the area formerly
181 known as Conca d'Oro (Golden Basin), where the soil is fertile and there is a good supply of
182 freshwater (38°04'53.1" N and 13°25'08.4" E). In the field, there is a 30-year-old mandarin
183 orchard planted with a spacing of 5 m × 5 m. The soil is not tilled and only mechanical weed
184 control is performed. The altitude is 35 m a.s.l. and the surface is flat. The soil is a typic
185 Rhodoxeralf with a depth of nearly 1 m and a moderate gravel content. According to the
186 USDA classification, the soil texture, determined on two replicate soil samples, is sandy-loam
187 with percentages of clay, $cl = 16.6\%$, silt, $si = 20.2\%$ and sand, $sa = 63.2\%$. The sampled area
188 was of about 50 m².

189 At the beginning of the field campaign, disturbed soil samples were collected at three
190 randomly chosen points within the sampling area and at two depths (0-5 and 5-10 cm) for
191 each point. This soil was used to determine the gravimetric soil water content, w (kg/kg). The
192 mean of these six w values was assumed to represent the antecedent gravimetric soil water
193 content, w_i (kg/kg), at the field site since the sampled area was small and all field runs were
194 carried out in a short time, that is in two consecutive days.

195

196 **Experimental methods**

197

198 ***Beerkan infiltration experiments***

199 Small diameter ($D = 0.08$ m) rings were inserted on the soil surface to a depth of 0.01 m for
200 the beerkan infiltration runs (Lassabatère et al., 2006). Rings were inserted manually or by

201 gently using a rubber hammer and ensuring that the upper rim of the ring remained horizontal
202 during insertion. The rings were relatively small since the soil surface layer was moderately
203 stony and the small size of the ring simplified finding appropriate surfaces for soil sampling
204 (**Fig. 1a**). A total of 15 infiltration runs were carried out in a single day at randomly selected
205 locations. For each run, 20 water volumes, each of 57 mL, were successively poured in nearly
206 3 s for each volume on the confined infiltration surface. Therefore, with each volume, the
207 initial ponded depth of water was equal to 11.3 mm. For each water volume (1st, 2nd, ...,
208 20th), the infiltration time was measured from water application to disappearance of all water,
209 when the subsequent water volume was poured on the infiltration surface (Bagarello et al.,
210 2021; Lassabatère et al., 2006). Energy of the applied water was dissipated on the fingers of
211 the hand in an attempt to minimize soil disturbance due to water application. A cumulative
212 infiltration, I (mm), vs. time, t (h), curve, comprising 20 data points, was therefore obtained at
213 each sampling point.

214

215 *Mini-disk field infiltration experiments*

216 Mini-disk infiltrometers (MDI; METER Group, 2021), having a disk diameter of 4.5 cm,
217 were used to perform three-dimensional (3D) infiltration experiments in the field. In
218 particular, the MDI was used to obtain 3D infiltration data for established pressure heads, h_0 ,
219 equal to -6, -3 and -1 cm. Each individual infiltration process for an established h_0 value was
220 carried out at a different sampling point, so that all infiltration curves were obtained under
221 similar initial soil water content conditions. For a given h_0 value, the experiment was
222 replicated at 15 different, randomly chosen, sampling points, for a total of 45 MDI infiltration
223 runs in the field. The soil surface at a sampling point was gently leveled with a trowel and
224 small amounts of loose soil were used when necessary to improve the contact between the
225 device and the infiltration surface (**Fig. 1b**). The MDI was fixed to a support to keep it still

226 during the run and infiltration was measured until the reservoir emptied. Readings were taken
227 visually at ≤ 1 min, during the first stage of the run, to 5 min intervals in the most advanced
228 stages of the infiltration process. A cumulative infiltration curve, $I(t)$, was obtained at each
229 sampling point.

230

231 *Mini-disk laboratory infiltration experiments*

232 Mini-disk infiltrometers were also used to perform 1D infiltration experiments in the
233 laboratory. At this aim, undisturbed soil cores were collected at 15 randomly chosen points of
234 the soil surface, after scraping out the first cm of soil, in 5-cm-inner diameter by 10-cm-high
235 stainless-steel cylinders to determine unsaturated soil hydraulic conductivity, K (mm/h), in the
236 laboratory. Each cylinder was inserted vertically into the soil by hammering gently on the top
237 of the cylinder with a rubber hammer and progressively removing the surrounding soil up to
238 the established depth to reduce disturbance during sampling. A nylon guard cloth was
239 attached to the base of the core to prevent soil loss from the bottom of the sample. To improve
240 the contact between the MDI and the soil, its surface was gently leveled in the laboratory with
241 a sharp knife and, when necessary, small amounts of loose soil were applied to the top of the
242 sample.

243 To establish a given h_0 value at the base of a soil core, a plastic box of 38 (length) \times 17
244 (width) \times 13 (height) cm^3 was filled with a bed of sand and several small holes (diameter = 1
245 cm) were made on the walls of the box at a downward distance $h^* = h_0$ (L) from the surface of
246 the sand bed (**Fig. 1c**). A metal net was glued to each hole to prevent sand from escaping.
247 Water was added to the box to form a saturated zone below the holes and an unsaturated zone
248 above them. At hydrostatic equilibrium, the soil water pressure head at the surface of the sand
249 bed was assumed to be equal to h_0 . Different boxes were prepared, depending on the
250 considered h_0 value ($h_0 = -6, -3, -1$ cm). The first established pressure head was $h_0 = -6$ cm.

251 The soil cores were placed on the surface of the sand box and left to equilibrate for 24-48
252 hours. During this period, small volumes of water were periodically added to the box to
253 maintain a constant h_0 value at the surface of the sand bed. Then, the MDI, set at this h_0 value,
254 was placed on the soil surface by gently pressing the device and using a support to maintain it
255 in place (**Fig. 1c**) and infiltration was measured. The small space between the walls of the
256 cylinder and the porous plate of the device (5 mm) was not sealed to enable air to freely
257 escape from the soil core during the run. After the run, the soil sample was left to freely drain
258 for nearly 12 hours. Then, the same core was equilibrated for 48 hours at -3 cm and the MDI
259 run at $h_0 = -3$ cm was carried out. Finally, after another 12 hours of free drainage, the core
260 was equilibrated for 48 hours at -1 cm and the last MDI run at $h_0 = -1$ cm was performed.
261 Generally, each individual run continued until the reservoir of the device emptied. For
262 particularly slow runs, infiltration was stopped after 6 hours. Readings were taken visually at
263 1 to 5 min time intervals, with shorter intervals in the early stages of the run and for the higher
264 (closer to zero) pressure heads. A run with a given h_0 value was replicated on 14 soil cores
265 since a soil core broke during laboratory treatment. Immediately after each run with a given h_0
266 value, the soil columns were weighed to later determine the final gravimetric, w (kg/kg), soil
267 water content.

268

269 *Laboratory constant-head permeameter experiments*

270 After the 1D MDI experiment at $h_0 = -1$ cm, the soil cores were left exposed to the air for a
271 few days and then they were used for measuring the saturated soil hydraulic conductivity, K_s
272 (mm/h), with the constant-head laboratory permeameter (CHP) method. Preliminarily, these
273 cores were saturated from the bottom according to Booltink and Bouma (2002). The
274 saturation procedure lasted a total of 24 hours, during which, specifically, the soil cores were
275 placed inside a plastic box and the water level was raised five times in 2 cm increments. A

276 funnel was used to support the sample and to collect percolating water (**Fig. 1d**). A Mariotte
277 bottle was used to establish the constant head of about 1 cm above the soil surface. The
278 amount of water passing through the sample was measured by weighing the collected water
279 volume at fixed intervals of 1 min. A Scout Pro portable electronic balance 4000 g connected
280 to a CR1000 datalogger was used to automate the measurements. The average value of the
281 flux density was calculated for a fixed time interval. The experiment was considered
282 concluded when the flow approached a steady-state condition characterized by a near constant
283 steady-state value, i.e. when the flux density appear nearly stable in 10 consecutive time
284 intervals. At the end of the run, the soil was dried in an oven at 105° C for 48 h and the dry
285 soil bulk density, ρ_b (g/cm³), was determined from the oven-dry soil mass and the bulk soil
286 volume.

287

288 **Calculations**

289 An estimate of the antecedent volumetric soil water content, θ_i (m³/m³), that is, the soil water
290 content at the beginning of the field campaign of measurements and sampling, was obtained
291 by the product between w_i and the mean of the 14 ρ_b values obtained after the CHP
292 experiment.

293 The volumetric soil water content, θ (m³/m³), at the end of a 1D run with the MDI set at a
294 given pressure head ($h_0 = -6, -3$ or -1 cm) was calculated from the gravimetric soil water
295 content and the dry soil bulk density of the considered soil core.

296 The BEST-steady algorithm (Bagarello et al., 2014) was applied to estimate the soil water
297 retention curve (van Genuchten, 1980) and the hydraulic conductivity function (Brooks and
298 Corey, 1964) from the experimentally determined intercept, b_s (mm), and slope, i_s (mm/h), of
299 the straight line fitted to the last three (I, t) data points describing steady-state conditions on
300 the cumulative infiltration plot. The shape parameters of the retention and hydraulic

301 conductivity curves were obtained from the particle-size distribution data (Lassabatère et al.,
302 2006). BEST-steady requires antecedent, θ_i (m^3/m^3), and saturated, θ_s (m^3/m^3), volumetric
303 soil water content that, in this investigation, were assumed not to change from point to point,
304 since the sampled area was small and the beerkan runs were carried out in a single day. The
305 value of θ_i was obtained from the w_i determination. To determine θ_s , it was considered that
306 field-saturated soil water content is generally lower than porosity, ϕ (m^3/m^3), due to the
307 presence of entrapped air (Reynolds and Elrick, 2002; Reynolds and Topp, 2008). According
308 to several investigations, θ_s/ϕ can vary from 0.70 to 0.95 (Alagna et al., 2016; Dane and
309 Hopmans, 2002; Gonzalez-Sosa et al., 2010; Mubarak et al., 2009a; Somaratne and Smettem,
310 1993; Verbist et al., 2013). Therefore, in this investigation, θ_s was estimated from the fitted
311 line to the $\theta(h)$ values that were determined after the 1D MDI runs. The results of BEST
312 application obtained with this estimate of θ_s were indicated as BEST_R (R indicating the use
313 of water retention data) calculations. However, in practical application of BEST methods, θ_s
314 is often set equal to the porosity, that is easily determined from the ρ_b measurements (Auteri
315 et al., 2020; Bagarello et al., 2023; Mubarak et al., 2009b). Therefore, this approach was also
316 applied for comparative purposes and these results were indicated as BEST_P (P indicating
317 porosity).

318 For each MDI infiltration run in the field, the two-parameter infiltration model (Philip, 1957)
319 was fitted to the cumulative infiltration, I (mm), vs. time, t (h), data by minimizing the sum of
320 the squared residuals between the measured and the predicted I values (Lassabatère et al.,
321 2006) to simultaneously estimate the C_1 ($\text{mm}/\text{h}^{1/2}$) and C_2 (mm/h) parameters of the model.
322 The soil hydraulic conductivity value corresponding to a given pressure head was then
323 calculated according to Zhang (1997) and Dohnal et al. (2010). The required soil water
324 retention parameters for calculating K were taken from Castellini et al. (2018), who applied
325 the evaporation method to characterize this field site in a previous investigation.

326 The 1D MDI measurements were made applying the same pressure head at the two ends of
327 the soil core. Therefore, the assumption was that, at steady-state, a unit hydraulic gradient was
328 established, i.e. the pressure head was the same throughout the soil core. Consequently,
329 steady-state flux density was equivalent to the unsaturated soil hydraulic conductivity
330 corresponding to the imposed pressure head, i.e. K_{-6} , K_{-3} or K_{-1} (mm/h), depending on the run.
331 Finally, the Darcy's law was applied to calculate K_s from the CHP laboratory data.

332

333 **Data analysis**

334 Three sets of K_s values (BEST_P, BEST_R, CHP method) and, for each negative pressure
335 head, four sets of K values (BEST_P, BEST_R, 1D MDI, 3D MDI) were overall obtained. For
336 each of these 15 datasets, the hypothesis that the data were normally distributed was never
337 rejected according to the Lilliefors (1967) test at $P = 0.05$. Consequently, the arithmetic mean
338 and the associated coefficient of variation, CV (%), were used to summarize each dataset.
339 Three different comparisons were carried out.

340 A comparison was established between the soil hydraulic conductivity values obtained with
341 BEST_R and BEST_P. At this aim, a two-tailed paired t test at $P = 0.05$ was applied for K_s , K_{-1} ,
342 K_{-3} and K_{-6} . This comparison was made since i) field-saturated soil water content can be
343 expected to be smaller than soil porosity (e.g., Reynolds and Elrick, 2002), ii) the BEST
344 protocol assumes that θ_s is directly measured (Lassabatère et al., 2006), but iii) in many
345 practical applications of BEST, θ_s is assumed to coincide with soil porosity (Bagarello et al.,
346 2011; Mubarak et al., 2009b; Xu et al., 2009; Yilmaz et al., 2010).

347 The K values obtained with the 1D and 3D MDI experiments were compared with each other.
348 An F test and a two-tailed t test at $P = 0.05$ were applied for each h_0 value and hence for K_{-1} ,
349 K_{-3} and K_{-6} . Moreover, the cumulative empirical frequency distributions (CFDs) of the
350 laboratory and field data were compared to succinctly visualize all the data for a given

351 pressure head. This comparison was made because, to our knowledge, little is known about
352 what to expect when exactly the same device, that is the MDI, is used to determine the
353 unsaturated hydraulic conductivity of an undisturbed soil with methods which differ by the
354 established infiltration process (3D, 1D) and the method of data analysis for determining K
355 (fitting an infiltration model to the data, directly using the Darcy's law).
356 Finally, the K values obtained with BEST-steady were compared with those obtained by the
357 CHP method (K_s) and the 1D MDI experiments (K_{-1} , K_{-3} and K_{-6}). Also in this case, F and
358 two-tailed t tests at $P = 0.05$ were applied for each considered variable. The objective of this
359 comparison was to evaluate differences between a direct measurement of hydraulic
360 conductivity values at and near saturation using undisturbed soil samples and the Darcy's law
361 with a field estimate of these values. This comparison was made since there is much practical
362 interest for BEST methods (Angulo-Jaramillo et al., 2019) but the predicted soil hydraulic
363 properties with this methodology have been compared with those obtained with other methods
364 only in a few investigations.

365

366 **RESULTS**

367

368 **Dry soil bulk density and soil water content**

369 The mean dry soil bulk density, ρ_b , was equal to 1.329 g/cm³ (coefficient of variation, $CV =$
370 4.0%; sample size, $N = 14$) and the mean antecedent gravimetric soil water content, w_i , was
371 equal to 0.094 kg/kg ($CV = 11.0\%$; $N = 6$). Consequently, the mean antecedent volumetric soil
372 water content, θ_i , was of 0.125 m³/m³.

373 The relationship between θ and h was approximately linear in the $-6 \leq h \leq -1$ cm range with a
374 coefficient of determination, R^2 , of 0.69 (**Fig. 2**). The θ vs. h data were described a little better
375 ($R^2 = 0.73$) by a power relationship but this relationship was not considered since it was not

376 usable to estimate the θ value corresponding to a null pressure head. According to the fitted
377 linear regression line, $\theta(0) = \theta_s$ was equal to $0.382 \text{ m}^3/\text{m}^3$. Therefore, $\theta_s = 0.382 \text{ m}^3/\text{m}^3$ was
378 considered for the BEST_R calculations. The soil porosity, ϕ , obtained from the mean ρ_b
379 value and assuming a soil particle density of $2.65 \text{ g}/\text{cm}^3$, was equal to $0.499 \text{ m}^3/\text{m}^3$. Therefore,
380 $\theta_s = 0.499 \text{ m}^3/\text{m}^3$ was considered for the BEST_P calculations. The θ_s/ϕ ratio, equal to 0.77,
381 was rather small but it appear plausible since it fell in the range of the θ_s/ϕ values found in the
382 literature (Alagna et al., 2016; Dane and Hopmans, 2002; Gonzalez-Sosa et al., 2010;
383 Mubarak et al., 2009a; Somaratne and Smettem, 1993; Verbist et al., 2013).
384 The θ_i/θ_s and θ_i/ϕ ratios were equal to 0.33 and 0.25, respectively. The θ_i/θ_s ratio was a little
385 higher than the threshold of 0.25 recommended by Lassabatère et al. (2006) for applying
386 BEST. However, wetter conditions can occur in practice (Xu et al., 2012) and Di Prima et al.
387 (2016) showed that, with BEST-steady, the estimated soil hydrodynamic parameters can be
388 expected to be accurate even in initially relatively wet conditions for many soils. Therefore, a
389 θ_i/θ_s ratio of 0.33 was considered not to impede application of BEST in this investigation.

390

391 **Infiltration and soil hydrodynamic parameters**

392 Generally, the established beerkan infiltration processes appeared consistent with theory since
393 the concavity of the I vs. t curves was faced downwards, denoting that the infiltration rates
394 initially decreased during the run, and the I vs. t relationship assumed a nearly linear shape at
395 longer times. Consequently, soil hydraulic conductivity data were obtained at each sampling
396 point with both BEST_R and BEST_P (**Table 1**).

397 Also in the case of the field MDI experiments, infiltration appeared consistent with theory
398 since infiltration rates initially decreased during the run and they stabilized at longer times.
399 The method by Zhang (1997) and Dohnal et al. (2010) was successfully applied to calculate
400 K_{-1} , K_{-3} and K_{-6} at each sampling point (**Table 1**).

401 For the majority of the 1D laboratory runs with the MDI, the I vs. t relationship was nearly
402 linear from the early stages of the infiltration process or it appeared to some extent concave
403 upwards (**Fig. 3**). Therefore, infiltrations rates, ir (L/T), were nearly stable during the run or
404 they stabilized after a phase of increasing values. For each run, the stabilized ir value obtained
405 by linear regression of the last I vs. t data points, ir_s , was compared with the slope of the
406 linear regression line fitted to all I vs. t data and forced to pass through the origin of the axes,
407 sl . A similarity between ir_s and sl was expected when the I vs. t relationship was nearly linear
408 for the entire infiltration process whereas $ir_s > sl$ denoted an upwards concavity of this
409 relationship (Bondi et al., 2023). On average, ir_s and sl differed by 1.12, 1.22 and 1.27 times
410 for $h_0 = -1, -3$ and -6 cm respectively. Moreover, a linear regression analysis between sl and
411 ir_s was carried out (**Fig. 4**). According to the calculated 95% confidence intervals for the
412 intercept and the slope, the linear regression line between these two variables did not differ
413 from the identity line by jointly considering all pressure heads ($-7.42 - 0.42$ and $0.98 - 1.07$,
414 respectively) and also for $h_0 = -1$ cm ($-27.5 - 13.2$ and $0.91 - 1.19$). However, it differed from
415 the identity line for both $h_0 = -3$ cm ($-1.10 - 2.70$ and $0.69 - 0.87$) and $h_0 = -6$ cm ($0.06 - 1.53$
416 and $0.57 - 0.77$). Therefore, a smaller h_0 value produced a greater upwards concavity.
417 However, taking into account that the estimate of the steady-state infiltration rate coincides
418 with the estimate of K for the 1D MDI experiment and that an error of 25% can be considered
419 negligible even in more stringent conditions, that is when the data are free of any
420 experimental error (Reynolds, 2013), the detected concavity did not introduce any relevant
421 uncertainty on estimation of K . Therefore, all infiltration runs were included in the developed
422 K dataset for each established pressure head and, for each run, K was assumed to coincide
423 with ir_s (**Table 1**).

424 All CHP experiments were successful and they yielded a K_s value for each sampling point
425 (**Table 1**).

426

427 **Comparisons**

428

429 ***BEST-R vs. BEST-P***

430 Regardless of h , higher K values were obtained with BEST_P as compared with BEST_R
431 (**Table 1**) but differences decreased monotonically as the pressure head became smaller (more
432 negative). In particular, two corresponding estimates of K differed by 1.37, 1.36, 1.30 and
433 1.08 times for $h = 0, -1, -3$ and -6 cm, respectively. Relative variability of the K values was
434 nearly independent of the saturated soil water content estimation approach.

435 In the following, the BEST_R calculations were considered for the comparison with other
436 estimates of K for the following reasons: i) air is usually entrapped in a porous medium when
437 it is saturated by downward infiltrating water under ponded conditions (e.g., Reynolds and
438 Elrick, 2002), such as in the case of the beerkan infiltration runs, ii) use of θ_s is conceptually
439 more consistent with the original BEST method (Lassabatère et al., 2006), and iii) using
440 BEST with a saturated soil water content smaller than ϕ can be expected to represent the best
441 choice to satisfactorily reproduce laboratory measured soil water retention values (Alagna et
442 al., 2016).

443

444 ***Field vs. laboratory MDI experiments***

445 The 1D MDI experiment yielded higher K values than the 3D one by 22% for $h_0 = -1$ cm,
446 35% for $h_0 = -3$ cm and 77% for $h_0 = -6$ cm (**Table 1**). Differences between two
447 corresponding datasets were statistically significant for the two lowest pressure heads but not
448 for the highest h_0 value. In the field, the highest relative variability of the data was detected
449 for the smallest pressure head. Instead, in the laboratory, relative variability was highest for
450 the highest pressure head. Consequently, the 1D MDI K values were 1.8 times more variable

451 than the 3D MDI ones for $h_0 = -1$ cm (high, for the 1D data, vs. medium, for the 3D data,
452 variation) (Warrick, 1998) and 1.8 times less
453 variable for $h_0 = -6$ cm (medium vs. high variation). Relative variability of the two estimates
454 of K was similar, and medium, for $h_0 = -3$ cm ($CV = 32-37\%$). For both $h_0 = -6$ and -3 cm, the
455 cumulative empirical frequency distribution (CFD) of the field K values was entirely located
456 to the left of the one corresponding to the laboratory values (**Fig. 5**). For $h_0 = -1$ cm, the two
457 CFDs intersected with each other since the laboratory method yielded both the highest and the
458 lowest of the overall determined K values.

459

460 ***BEST_R vs. CHP and 1D MDI experiments***

461 Regardless of the considered variable (K_s , K_{-1} , K_{-3} , K_{-6}), the differences between the field
462 (BEST_R) and the laboratory (CHP and 1D MDI) estimates of K were statistically significant
463 (**Table 1**). The CHP method yielded a 5.6 times higher K_s value than BEST_R and the lowest
464 laboratory value of K_s was 1.4 times larger than the highest K_s value obtained in the field (**Fig.**
465 **5**). The 1D MDI estimates of K_{-1} were 1.7 times larger than those obtained with BEST_R. For
466 K_{-3} and K_{-6} , BEST_R yielded higher estimates than the 1D MDI by 3.4 and 8.1 times,
467 respectively. In both cases, K increased monotonically as the pressure head became less
468 negative (**Table 1**), but at a very different rate for the two tested methods (**Fig. 6**). In
469 particular, the K_s/K_{-6} ratio was equal to 1.23 with BEST_R and 55.4 with the laboratory soil
470 cores. Therefore, BEST_R predicted a nearly flat soil hydraulic conductivity curve for $h \geq -6$
471 cm. This shape was not consistent with the K data obtained in the laboratory that instead
472 suggested that even a small variation of h induced large changes of K . The BEST_R $K(h)$
473 curves intersected the data obtained in the laboratory (**Fig. 6**). In particular, the former curves
474 were positioned below the laboratory K data for $h = 0$ and above them for $h \leq -3$ cm. A certain
475 overlap between the curves obtained with BEST_R and the K values measured in the

476 laboratory was detected for $h = -1$ cm. Relative variability of K_s did not differ appreciably
477 between BEST_R and the CHP method and it was medium in both cases (**Table 1**). In
478 unsaturated conditions, BEST_R predicted nearly constant CV values that instead decreased,
479 although not exactly monotonically, from high to low pressure heads with the 1D MDI
480 experiments. According to Warrick (1998), relative variability of the unsaturated K values
481 was generally medium, with two exceptions (BEST_R, $h = -6$ cm; 1D MDI, $h = -1$ cm), in
482 which variation was high. Even in this case, however, the CV values were not appreciably
483 greater than the value that discriminates between a medium and a high variation ($CV = 50\%$).

484

485 **DISCUSSION**

486

487 **Estimating saturated soil water content for the BEST calculations**

488 The choice of the θ_s value to be used for the BEST calculations is expected to be important to
489 recognize a correspondence between estimated and independently measured water retention
490 values (Alagna et al., 2016) but it seems that the same cannot be said with reference to soil
491 hydraulic conductivity. The reason is that the estimates of K_s with BEST_P and BEST_R
492 differed by 1.4 times (**Table 1**) which can be considered a rather small difference (Elrick and
493 Reynolds, 1992). Moreover, for another sandy-loam soil, Di Prima et al. (2017) reported that
494 changing the estimate of θ_s (porosity instead of the field measured value) implied that the K_s
495 estimates differed by only 1.2 times. Probably, the effect was smaller than that detected in this
496 investigation since our θ_s/ϕ value was equal to 0.77 whereas it was 0.85 (i.e., closer to one) in
497 the study by Di Prima et al. (2017).

498 This investigation also demonstrated that the effect of the used approach for estimating θ_s
499 decreased for more negative pressure heads. To explain this last result, that apparently was

500 not discussed so far, it has to be noted that, with the applied BEST-steady algorithm, K_s and K
501 are given by (Bagarello et al., 2014):

$$502 \quad K_s = \frac{C i_s}{\frac{\gamma b_s}{r(\theta_s - \theta_i)} + C} \quad (1a)$$

$$503 \quad K(\theta) = K_s \left(\frac{\theta}{\theta_s} \right)^\eta \quad (1b)$$

504 where i_s (L/T) and b_s (L) are the slope and the intercept, respectively, of the linear regression
505 line fitted to last data points that describe steady-state conditions on the I vs. t plot, C is a
506 constant that, for an initial soil hydraulic conductivity, $K_i \ll K_s$, does not depend on the soil
507 water content, θ , and is equal to 0.639, γ is a parameter for geometrical correction of the
508 infiltration front shape, usually assumed to be equal to 0.75, r (L) is the radius of the source
509 and η is a shape parameter. An increase of θ_s (e.g., using ϕ instead of $\theta_s < \phi$) implies a smaller
510 denominator in eq.(1a) and hence a higher estimate of K_s (Di Prima et al., 2017). According to
511 eq.(1b), the increase of K_s is partially compensated by a decrease of θ/θ_s , which explains why
512 the estimate of θ_s had a smaller impact on the K calculations for more negative pressure head
513 values.

514 In any case, when $\theta_s < \phi$, the BEST_P calculations appear conceptually less reliable than the
515 BEST_R ones since, in the former case, infiltration parameters (i_s , b_s) obtained in a soil that
516 contains air are treated as if they had been obtained in a completely saturated porous medium.

517

518 **Upwards concavity of cumulative infiltration for the laboratory mini-disk runs**

519 An attempt to explain the unexpected upwards concavity of the $I(t)$ curves obtained in the
520 laboratory with the 1D MDI runs (**Fig. 3**) was made and at least three possible reasons were
521 identified.

522 A possible reason was that the contact between the device and the infiltration surface
523 improved during the run, notwithstanding that this surface appeared leveled and smoothed

524 before firmly putting the MDI in place. In other terms, the actual infiltration surface was
525 smaller than expected at the beginning of the run and then it became larger. Non-uniform
526 wetting even under controlled laboratory conditions on repacked soil columns was reported
527 by Close et al. (1998). These authors also concluded that contact problems can be particularly
528 noticeable in the case of low established pressure heads. There was agreement between this
529 suggestion and our results since a smaller h_0 value produced a greater upwards concavity.

530 An upwards concave cumulative infiltration curve can be obtained when the soil is initially
531 water repellent but water repellency decreases during infiltration (Alagna et al., 2019). Water
532 repellency should not have a strong effect on infiltration in initially wet soil conditions (de
533 Jonge et al., 1999; Dekker et al., 2001) that were those of this experiment given that, at the
534 beginning of a run, the base of a soil core was equilibrated at not less than -6 cm of water,
535 However, this interpretation was not excluded because other authors also signaled water
536 repellency phenomena in initially relatively wet soil conditions (Carrick et al., 2011).

537 According to Faybishenko (1995), air can initially be entrapped in the smallest soil pores but,
538 under the influence of capillary forces, water is drawn into these pores so that the entrapped
539 air is displaced into the largest pores. Therefore, another possible interpretation was that some
540 air was entrapped in the smallest soil pores at the beginning of the infiltration run and then it
541 escaped. Infiltration rates increased during the run with the smallest pressure head because the
542 hydraulically active pores were small and they initially contained some entrapped air. This
543 entrapped air did not affect appreciably infiltration rates at the highest pressure head since, in
544 this case, the hydraulically active pores were large enough not to be blocked by air escaping
545 from the smallest pores.

546 Of course, a less uncertain interpretation of the detected concavity would likely require
547 additional experimental investigations that should particularly be carried out for small
548 pressure heads. However, it does not seem that these investigations constitute a priority in a

549 practical perspective since the detected concavities were not so appreciable as generating
550 great doubts on the reliability of the K estimates.

551 An upward concavity was not observed in the field since, in this case, infiltration rates tended
552 to stabilize after a transient decreasing stage. Therefore, it appeared plausible to believe that:
553 i) the contact between the device and the soil was better in the field, probably because the
554 leveling of the contact surface was easier in the absence of any confinement of the infiltration
555 surface; ii) in the field, possible soil water repellency effects were masked by lateral
556 capillarity forces that were not active in the laboratory; and/or iii) entrapped air effects were
557 less noticeable in the field since air could escape more easily due to the lack of any
558 confinement of the sampled soil volume. Moreover, infiltration occurred under larger pressure
559 head gradients in the field than in the laboratory. Perhaps, even this difference contributed to
560 determine a different shape of the experimental I vs. t relationship.

561

562 **Comparing mini-disk experiments**

563 With reference to saturated hydraulic conductivity of undisturbed soils, differences from a
564 reference value by nearly 60% (Yilmaz et al., 2023) or by a factor of two or three (Elrick and
565 Reynolds, 1992) could be considered negligible, at least for some practical purposes.
566 Assuming that these suggestions also apply to the case of the near-saturated soil hydraulic
567 conductivity, it could be suggested that the 1D and 3D MDI experiments overall yielded
568 similar results, particularly close to saturation (**Table 1**). However, another interpretation was
569 that the 1D experiment tended to generally yield higher K values than the 3D experiment,
570 more noticeably for the smallest pressure heads.

571 Obtaining a larger K value with a 1D experiment than a 3D one could be due to a significant
572 contribution to total flow of macropores extending from the surface to the bottom of the soil
573 sample (Bagarello et al., 2007) or to an overestimation of the steady-state 1D flow rate

574 (Bagarello et al., 2010). However, explaining the differences between the 1D and 3D data as a
575 consequence of preferential flow phenomena did not appear convincing since the largest
576 discrepancies were detected with the lowest established pressure head, which did not activate
577 the largest voids in the sample.

578 Instead, it can be supposed that $1D K > 3D K$ was obtained since ir_s (slope of the stabilized
579 part of the I vs. t relationship) was used instead of sl (slope of the linear regression line fitted
580 to all the I vs. t data points) for calculating $1D K$ and $ir_s > sl$ was obtained for the smallest
581 pressure heads (**Fig. 4**). Although this interpretation could find a numerical support, there
582 were physical reasons for using ir_s instead of sl . The assumption that K coincides with the
583 steady-state infiltration rate can only be made if the flow process is stable. The last part of
584 each infiltration run appeared clearly linear in all cases (**Fig. 3**) denoting that, starting from a
585 certain point, the process stabilized. Instead, considering a not perfectly stable process as if it
586 was stable, i.e. using sl for the K calculations, would have made the reliability of the
587 estimated slopes more questionable in the perspective to determine K .

588 It was also deemed unlikely that differences were attributable to soil compaction during
589 sampling since, in this case, the opposite result ($3D K > 1D K$) would have been expected.

590 An effect of the methods used to determine K from the MDI infiltration data was not
591 completely excluded since a dependence of the K values on the applied calculation method is
592 documented in the literature (Dohnal et al., 2010; Jacques et al., 2002; Logsdon and Jaynes,
593 1993). Nor can it be ruled out that differences occurred as a consequence of spatial variability
594 of soil hydrodynamic properties at the field site, given that different points were sampled with
595 the 3D and 1D MDI runs. Moreover, it could also be considered that the 1D data were
596 expressive of a vertical infiltration process whereas the 3D data were representative of a
597 combined vertical and lateral flow process. Therefore, forcing water to move vertically
598 perhaps reduced the overall tortuosity of the flow paths, especially with reference to the

599 smallest active pores given that the differences between the 1D and 3D results increased as h_0
600 decreased.

601

602 **Field vs. laboratory determination of soil hydraulic conductivity**

603 According to the BEST_R, CHP and 1D MDI data (**Table 1** and **Fig. 6**), the laboratory
604 prediction of K_s was appreciably larger than the field one, that is by 5.6 times. For unsaturated
605 soil conditions, the K estimates were nearly independent of h with BEST_R but they
606 decreased appreciably with smaller pressure heads according to the MDI data. Consequently,
607 the two approaches yielded relatively similar results for $h = -1$ cm (difference by 1.7 times)
608 but BEST_R predicted appreciably higher K values than the MDI in more unsaturated
609 conditions (by 3.4 and 8.1 times for $h = -3$ and -6 cm, respectively).

610 A possible reason of the differences between the laboratory and the field determination of K_s ,
611 was that the laboratory experiment actually yielded excessively high K_s values. It would not
612 be the first time that soil cores yield higher (even by orders of magnitude) K_s values than
613 those obtained by establishing in the field an infiltration process on an initially unsaturated
614 soil (e.g., Bagarello and Provenzano, 1996; Jačka et al., 2014; Paige and Hillel, 1993;
615 Reynolds et al., 2000). High K_s values could depend on rapid pipe flow through worm holes,
616 old root channels and cracks that extended through the core (Reynolds et al., 2000) or on
617 cracks and fissures created during the collection procedure (Jačka et al., 2014). According to
618 Paige and Hillel (1993), discontinuous macropores in the field can become continuous in a
619 particular soil sample. It cannot be said without any doubt that pipe flow phenomena occurred
620 in this investigation since the length of the soil cores (10 cm) was appreciably greater than
621 that considered in other investigations (e.g. 3 cm in Paige and Hillel, 1993) and continuity of
622 large pores between the upper and the bottom ends of the soil sample appears less probable
623 with a longer sample. On the other hand, it could also be suspected that these cavities may

624 have formed during the experiment given that K_s was measured after three previous K
625 determinations with the MDI, that is, after an intense use of the sample albeit with all possible
626 precautions.

627 On the other hand, it cannot ever be ruled out that the K_s values obtained with the field
628 experiment were too low. In this investigation, there were some signs that this circumstance
629 occurred even if these signs were not unequivocal. In particular, the 1D MDI experiments (but
630 also the 3D MDI ones) yielded $K_{-1} > K_s$ (**Table 1**), which is physically impossible. This result
631 did not necessarily represent a proof that the field K_s values were too low since it could also
632 be a consequence of spatial variability of soil hydrodynamic properties (e.g., Logsdon and
633 Jaynes, 1996; Prieksat et al., 1994). In other words, these differences occurred because the
634 points sampled with the beerkan runs were inherently less permeable than those sampled for
635 the MDI runs. However, a rather large number of runs were carried out with each method on
636 an overall small area, according to existing guidelines (Reynolds et al., 2002), and this
637 circumstance induced to be cautious in proposing an interpretation exclusively based on
638 spatial variability considerations. Instead, the conclusion that $K_{-1} > K_s$ signaled that BEST_R
639 yielded too low K_s values appeared more convincing than, or at least as plausible as, the
640 suggestion that particularly low permeability points were sampled with the beerkan runs but
641 not with the MDI experiments.

642 One of the possible reasons why field K_s values were too low was that some air was entrapped
643 in the soil during the ponding infiltration runs (Lee et al., 1985; Mohanty et al., 1994). Indeed,
644 there were many opportunities to induce some air entrapment in the sampled soil volume
645 since the beerkan run was performed in accordance with Lassabatère et al. (2006) and hence
646 by adding a new water volume when the previous water volume had completely infiltrated
647 and the infiltration surface was entirely exposed to air (Bagarello et al., 2021). Field-saturated
648 soil hydraulic conductivity values can be expected to be two or even more times smaller than

649 completely saturated soil values (Gupta et al., 1993; Jačka et al., 2014; Reynolds and Elrick,
650 1987). Moreover, the results of this investigation were consistent with the conclusion by
651 Sakaguchi et al. (2005) that the saturated hydraulic conductivity measured on a soil
652 containing entrapped air can be smaller than the unsaturated hydraulic conductivity close to
653 saturation.

654 Another possible reason why the field K_s values were too small was that repeatedly pouring
655 water on an initially unsaturated soil altered the upper soil layer that became progressively
656 less conductive. Mechanical impact of the applied water volumes was minimized by applying
657 water close to the infiltration surface and dissipating the energy of the water on the fingers of
658 the hand. However, some slaking perhaps occurred in the early stages of the run since water
659 was suddenly applied on an initially unsaturated soil (Le Bissonnais, 1996). Consequently,
660 pore sizes decreased and flow paths became perhaps more tortuous. Slaking did not occur in
661 the laboratory experiments since, in this case, the soil was initially wetted slowly from the
662 bottom.

663 Finally, another possible explanation for low K_s values was that soil structure collapsed to
664 some extent during ring insertion. However, this explanation appeared rather unrealistic since
665 the ring was inserted to a very short depth in the soil (1 cm) and with great caution.

666 With reference to the unsaturated soil hydraulic conductivity, a similar result to that of this
667 investigation was obtained by Alagna et al. (2016) in a comparison, for a loam soil, between
668 BEST and the classical tension infiltrometer (TI). In particular, differences between
669 corresponding K values were relatively small (by 1.2-3.0 times, depending on the BEST
670 algorithm) for $h = -1$ cm but BEST yielded 9 to 35 times higher K values than the TI for $-12 \leq$
671 $h \leq -3$ cm. According to these authors, this difference occurred because the assumed hydraulic
672 conductivity function in BEST did not reproduce satisfactorily the changes in the soil pore

673 system for $h < -1$ cm. In other words, representation of the soil as a single permeability
674 system was responsible of the poor matching between the two tested methods.

675 Even in this investigation, differences between the predicted and the measured K values for a
676 given pressure head appeared to depend on the inability of BEST to describe the soil
677 hydraulic properties close to saturation. In particular, the experimental θ values decreased
678 appreciably as h decreased from -1 to -6 cm (from 0.371 to 0.284 m^3/m^3) but the BEST_R
679 predictions of θ varied only minimally in this range of h values (from 0.382 to 0.377 m^3/m^3 ;
680 **Fig. 2**). The experimental and modelled θ values were rather similar for $h = -1$ cm and an
681 approximate similarity was also detected with reference to the corresponding estimates of K
682 (**Table 1** and **Fig. 6**). Moreover, plotting K against θ (**Fig. 7**) showed that i) regardless of the
683 imposed h_0 value, the 1D MDI experiment yielded increasing K values with θ , as expected;
684 and ii) the K values predicted with BEST_R fell in a zone of the figure which indicated a
685 certain correspondence between the laboratory and the field K data for similar θ values. In
686 particular, with BEST_R, the means of θ and K were equal to 0.380 m^3/m^3 and 67.5 mm/h,
687 respectively. According to the fitted regression line to the $K(1D\ MDI)$ vs. θ data, $K_{\theta=0.38}$ was
688 equal to 94.0 mm/h, that is larger than the BEST_R prediction by 39.3%. This difference was
689 rather small (Elrick and Reynolds, 1992; Yilmaz et al., 2023) and it suggested that the
690 BEST_R predictions of K and the 1D MDI values were of the same order of magnitude when
691 the soil water content was the same. In other words, BEST_R overestimated K at small
692 pressure heads since it was unable to predict the same decrease in θ that was detected
693 experimentally. This result reinforces the need to define the setup of BEST-2K, that extends
694 the existing BEST methods for use in dual-permeability soils (Lassabatère et al., 2014, 2019).

695 In this investigation, standard approaches were applied to determine K with the different
696 devices and experimental methodologies, meaning that different representations of the $K(h)$
697 relationship were considered. For example, the Brooks and Corey (1964) model was assumed

698 for BEST whereas no assumptions were made with the 1D MDI since individual data points
699 (i.e., a K value for a pre-established h value) were obtained by direct application of the Darcy
700 law. Moreover, a specific BEST algorithm was used to analyze the infiltration data collected
701 by the beerkan runs but other algorithms are available in the literature (Lassabatère et al.,
702 2006; Yilmaz et al., 2010). Future developments of this investigation should also explore
703 these methodological issues taking into account that soil hydraulic conductivity may be
704 expected to vary with the adopted model (Lenhard et al., 1989; Mubarak et al., 2009a;
705 Valiantzas, 2011) and different BEST algorithms could yield different estimates of the soil
706 hydrodynamic properties, depending on the specific circumstances (Angulo-Jaramillo et al.,
707 2016, 2019).

708

709 **CONCLUSIONS**

710 This investigation contributed to expand, for a sandy-loam soil, our knowledge on different
711 simple field and laboratory methods usable to determine the saturated and near-saturated soil
712 hydraulic conductivity.

713 Using, for the BEST (Beerkan Estimation of Soil Transfer parameters) calculations, the soil
714 porosity, ϕ , instead of the true saturated soil water content, θ_s , yields higher estimates of soil
715 hydraulic conductivity but differences decrease in more unsaturated soil conditions. It is
716 recommended to make use of θ_s since the established beerkan infiltration process will likely
717 give rise to air entrapment in the soil. In practice, however, using ϕ instead of θ_s could be
718 expected not to introduce large uncertainties in soil hydraulic conductivity estimation.

719 Pooling the data from the unconfined MDI (mini-disk infiltrometer) infiltration measurements
720 performed in the field and the confined MDI measurements performed in the laboratory
721 appears a possible way to proceed in the perspective to obtain a mean K value for close to
722 saturation soil with reference to an area of interest. The validity of this conclusion becomes

723 weaker in more unsaturated conditions but even in this case it can be expected that only a
724 moderate noise will be introduced in the estimate of K .

725 In the close to saturation region, the soil hydraulic conductivity function predicted with BEST
726 does not generally reproduce direct measurements of K obtained in the laboratory at different
727 pressure heads by a direct application of the Darcy's law with the MDI and the CHP
728 (constant-head permeameter) method. In particular, the expectation could be that BEST will
729 yield a too small K_s value and too high K values for the more unsaturated conditions.
730 However, a satisfactory correspondence between BEST and laboratory determination of K can
731 be expected for the same soil water content.

732 Supporting these conclusions with other comparisons is of course necessary. Based on the
733 experience gained in this study, improving the organization of the experiment could be
734 advisable even if delineating these improvements is not easy. For example, spatial variability
735 of soil hydrodynamic properties was suggested to perhaps influencing to some degree some of
736 the established comparisons. In principle, spatial variability effects could be prevented or
737 appreciably reduced by applying all measurement methods at a single sampling point
738 according for example to the sequence i) 3D MDI, ii) beerkan run, iii) collection of the
739 undisturbed soil core, iv) 1D MDI and, finally, v) CHP application. In this case, all
740 measurements refer to nearly the same soil volume. However, it cannot be said that this is the
741 best choice, since the experiment will become unavoidably longer, for example because the
742 soil needs to dry out after the 3D MDI run and before performing the beerkan run. Moreover,
743 repeated solicitations on exactly the same soil volume could promote soil structure alterations
744 having an impact that would be difficult to detect. Therefore, a possible alternative could be
745 to reduce uncertainties attributable to soil spatial variability by performing more runs for each
746 applied measurement method. However, interpreting differences between methods does not
747 solve any problem since the most appropriate measurement method for an intended use of the

748 data has to be chosen. A way to reach this objective could be comparing a monitored soil
749 hydrological process with the corresponding one predicted by a mechanistic model and the
750 measured soil hydrodynamic properties.

751

752

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764 **Vincenzo Alagna:** Investigation, Writing - Reviewing and Editing. **Dario Autovino:**
765 Investigation, Data Curation, Writing- Original draft preparation. **Vincenzo Bagarello:**
766 Conceptualization, Writing- Original draft preparation. Methodology, Formal analysis, Data
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