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Article Effect of rotational speed on mechanical properties of AA5083 / AA6082 friction stir welded T-joints for naval applications

Guido Di Bella 1,*, Chiara Borsellino 1, Mohamed Chairi 1, Davide Campanella 2, Gianluca Buffa 2

- ¹ Department of Engineering, University of Messina; guido.dibella@unime.it, chiara.borsellino@unime.it, mohamed.chiari@unime.it
- ² Department of Engineering, University of Palermo; davide.campanella@unipa.it, gianluca.buffa@unipa.it, livan.fratini@unipa.it
- * Correspondence: guido.dibella@unime.it; +390906765310

Abstract: This study evaluates the influence of rotational speed on the mechanical and microstruc-10 tural properties of T-joints fabricated via friction stir welding (FSW) using dissimilar aluminum 11 alloys, AA5083 and AA6082, for naval applications. Three types of joints were produced by main-12 taining a constant traverse speed of 100 mm/min and varying the tool rotational speed at 500, 700, 13 and 900 rpm. Mechanical performance was assessed through pull-out tests and microhardness 14 measurements. The joints fabricated at 500 rpm demonstrated superior mechanical properties, in-15 cluding a more uniform hardness distribution and higher pull-out strength, attributed to optimized 16 material mixing and heat input at this speed. In contrast, higher rotational speeds led to defect for-17 mation, such as wormholes, and compromised mechanical performance. These findings underscore 18 the importance of optimizing rotational speed to enhance joint quality, making FSW a viable solu-19 tion for manufacturing durable, lightweight structures in demanding marine environments. 20

Keywords: Friction Stir Welding; Joining; Aluminum; Shipbuilding; Manufacturing

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1. Introduction

Friction stir welding (FSW) has emerged as a pivotal technique across diverse indus-24trial sectors, including automotive, aerospace, and marine industries, where lightweight25and robust structures are indispensable[1,2]. As a solid-state joining process, FSW elimi-26nates the melting phase, thus minimizing thermal distortion, residual stresses, and defects27typically associated with conventional fusion welding techniques[3,4]. This unique capa-28bility makes FSW particularly suited for high-performance applications, especially in en-29vironments demanding corrosion resistance and structural integrity[5].

Initially developed for joining similar materials in simple butt joint configurations, 31 FSW has evolved to accommodate dissimilar material combinations and complex joint 32 geometries [6]. This adaptability is critical for marine applications, where aluminum alloys are widely used due to their low density, excellent corrosion resistance, and favorable 34 mechanical properties [7]. 35

The capacity of FSW to join dissimilar materials [8], such as various aluminum alloys 36 [9] or even aluminum with steel [10,11], presents significant strategic advantages. Alumi-37 num alloys, widely used in marine applications for their low density, high corrosion re-38 sistance, and favorable mechanical properties [12,13], benefit from FSW precision in join-39 ing without sacrificing the structural integrity of either material. Welding dissimilar alu-40 minum alloys, for example, allows to leverage the specific properties of each alloy within 41 a single structural component [14]. This adaptability can enhance the performance of na-42 val structures, enabling designs that are both lighter and more resistant to environmental 43 stressors. The FSW process thus supports the integration of high-strength components 44 while maintaining a balance between weight efficiency and structural robustness. 45

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Nor and Shazarel [15] apply FSW process to join aluminum alloys AA6061-T6 and 46 AA5083-H116 in butt joint configurations with specimens used for marine applications. 47 Key parameters are adjusted, including material thickness (3mm, 4mm, and 5mm), rota-48 tional speed (800, 1200, and 1600 rpm), feed rate (30, 60, and 90 mm/min), pin length 49 (92.5%, 95%, and 97.5% of material thickness), and dwell time (15, 20, and 25 minutes). 50 The optimization of tensile strength and hardness responses is conducted using Response 51 Surface Methodology (RSM). Osorio et al [16]identify a process window to improve me-52 chanical properties and reduce discontinuities in dissimilar friction stir welded joints of 53 AA6063-T6 and AA5052-H32 alloys. By testing various rotational and traverse speeds, 54 and analyzing microstructure through optical microscopy, X-ray diffraction, and SEM-55 EDS, they find that a speed ratio of 1800 rpm/163 mm/min yields high-quality joints with 56 increased microhardness and a tensile strength of 159 MPa. Verma and Kumar [17] use 57 FSW to join AA6061-T6 and AA5083-O plates, examining how tool pin profile, rotation 58 speed, feed rate, and tilt angle impact tensile strength and elongation. Using Box-Behnken 59 design and regression models, they find that strength and elongation increase with weld-60 ing parameters up to an optimal point before declining. The straight cylindrical (SC) pin 61 profile produced the highest strength (135.83 MPa) and elongation (4.35%) at 1568 rpm, 62 39.53 mm/min feed rate, and 1.11° tilt angle. 63

In addition to joining dissimilar materials, FSW accommodates various joint config-64 urations, expanding its applicability to complex geometries such as T-joints [18]. The T-65 joint, commonly used in marine frameworks to connect perpendicular components, is es-66 sential in constructing durable and stable structures. However, T-joints pose specific chal-67 lenges in FSW due to their geometry and the need for controlled heat distribution and 68 material flow to produce a high-quality weld. Achieving defect-free joints in such config-69 urations requires precise control over FSW parameters. Key process parameters—includ-70 ing tool rotational speed, travel speed, axial force, and tool tilt angle-directly impact the 71 heat generation, material flow, and ultimate quality of the joint. Of these, the tool rota-72 tional speed plays a critical role, as it influences both the temperature and the degree of 73 material mixing around the tool, affecting the weld's microstructure, mechanical proper-74 ties, and defect susceptibility. Inadequate or excessive rotational speeds may lead to in-75 complete mixing, void formation, or undesirable softening, thereby compromising joint 76 strength and fatigue resistance. 77

Tavares et al [19] explores FSW T-joints of dissimilar aluminum alloys, ideal for rein-78 forced panels where a tougher skin alloy and a stronger web alloy provide a damage-79 tolerant design. The proposed T-joint configuration excludes overlap interfaces, allowing 80 effective material flow for robust welds. Mechanical tests show high static and dynamic 81 strength but reduced elongation. Microstructural analysis of the weld zone, compared to 82 base materials and butt joints, confirms the feasibility of joining dissimilar aluminum al-83 loys in T-joints. Jesus et al [20] weld AA 5083-H111 and AA 6082-T6 plates in T-butt and 84 T-lap configurations using three tool pin geometries: tapered/threaded, quadrangular py-85 ramidal, and progressive pin. Welds with the pyramidal pin show tunnel defects, kissing 86 bonds, and oxide lines, while the tapered pin welds only have kissing-bond defects. The 87 progressive pin welds are defect-free. Hardness remains consistent across tools and joint 88 types, but the progressive pin in the T-butt configuration yields the best mechanical per-89 formance, with T-butt joints outperforming T-lap joints in FSW. Sabry et al [21] success-90 fully produce T-joints of AA6063-T6 using FSW and a specially developed fixture, result-91 ing in defect-free welds. They analyze the effects of tool rotation speed, axial force, and 92 travel speed on tensile strength, hardness in various zones (thermal, heat affected, and 93 nugget), and temperature distribution. Rana et al [22] examine FSW for joining highly 94 dissimilar materials, specifically Aluminum alloy 6156 and commercially pure Ti Grade 95 2, using both numerical simulation and experimental validation. The research highlights 96 the need for balanced parameters to achieve appropriate heat flux, influencing material 97 flow and properties. A numerical model predicts field variables and material flow in Al-98 Ti skin-stringer joints, with findings on material flow changes based on skin-stringer 99

positioning. Macrostructural and microstructural analyses reveal insights into grain refinement, intermetallic formation, and defects. Results show that joint strength in T-joints 101 is comparable to butt joints reported in literature. 102

Recent advancements in welding process optimization have integrated numerical 103 simulations, artificial intelligence (AI), and Internet of Things (IoT) technologies to en-104 hance joint quality and process efficiency. These methods enable precise control and pre-105 diction of welding outcomes, particularly in complex configurations like T-joints. Memon 106 et al [23] investigated the effects of friction stir welding (FSW) tool offset on the mixing 107 and bonding of Al–Mg–Si alloys in T-configurations. Using computational fluid dynamics 108 (CFD) simulations, they demonstrated that an appropriate tool offset is crucial for optimal 109 material flow and joint integrity. Specifically, a +0.2 mm offset on the advancing side re-110 sulted in the most robust joint, retaining over 60% of the base aluminum alloy's strength. 111 Similarly, Salloomi [24] conducted a fully coupled thermomechanical simulation of the 112 FSW process for aluminum 6061-T6 alloy T-joints. The study evaluated temperature dis-113 tribution, stress, strain, tool reaction forces, and energy dissipation during the welding 114phases. The simulation results showed symmetrical temperature distribution across the 115 T-joint width, with a high gradient in the weld stirring zone after the plunge stage. Exper-116 imental validation using embedded thermocouples confirmed the numerical findings, in-117 dicating good correlation with minimal deviation in peak values. Additionally, Silva et al 118 [25] focused on optimizing FSW T-joints using the Taguchi method. Mechanical testing of 119 27 different welded joints revealed that tool rotational speed significantly influences joint 120 mechanical properties and is strongly dependent on the shoulder-to-probe diameter ratio. 121 The study identified that a rotational speed of 1000 rpm, a probe depth of 3.90 mm, and a 122 shoulder/probe diameter ratio of 2.5 (with a shoulder diameter of 15 mm) yielded im-123 proved joint strength. Notably, under these optimized parameters, welding speed did not 124 significantly affect the outcomes. These studies underscore the importance of precise pa-125 rameter optimization in FSW of T-joints to achieve superior mechanical properties and 126 joint integrity. 127

This study examines the effect of rotational speed [26] on the mechanical properties 128 of T-joints fabricated via FSW from dissimilar aluminum alloys, AA5083 and AA6082, 129 specifically for naval applications. The research focuses on how variations in rotational 130 speed influence the formation of weld imperfections, such as wormholes, and the overall 131 mechanical performance of the joints. By investigating these aspects, the study aims to 132 establish a clear understanding of the relationship between process parameters and joint 133 quality. The primary objective is to optimize FSW process settings to achieve high-quality, 134 durable joints that balance mechanical performance and weight reduction, addressing the 135 stringent demands of marine environments. Particularly, joining aluminum alloys 136 AA5083 and AA6082 offers a balanced combination of properties ideal for demanding 137 applications. AA5083 provides excellent corrosion resistance, particularly in marine envi-138 ronments, while AA6082 contributes higher mechanical strength. This synergy creates a 139 lightweight, durable joint that is well-suited for structural applications in marine, auto-140 motive, and aerospace industries. Additionally, combining these alloys can be more cost-141 effective than using alternative materials, offering enhanced fatigue performance and ver-142 satility across various high-performance applications. 143

For the study in question, three different levels of heat input were considered. Spe-144 cifically, with a constant tool feed rate of 100 mm/min, the tool rotational speed was varied 145 from 500 rpm to 900 rpm, with an intermediate step at 700 rpm. Mechanical evaluation, 146 including pull-out tests and microhardness measurements, was performed to assess the 147 performance of each joint type. The results indicate that T-joints produced in transparency 148 modality at a rotational speed of 500 rpm exhibited enhanced mechanical properties, in-149 cluding higher pull-out strength and a stable hardness distribution. This study demon-150 strates that selecting a rotational speed of 500 rpm, which balances heat input, material 151 mixing, and defect minimization, significantly improves the mechanical quality and ro-152 bustness of T-joints. The results presented are the averages of three independent tests for 153 each welding condition, with standard deviations calculated to evaluate data variability. 154 Fracture surface analyses confirmed the presence of characteristic defects, such as worm-155 holes, particularly at higher rotational speeds, which correlate with decreased mechanical 156 performance. These findings were consistent across samples, supporting the robustness 157 of the conclusions drawn. These findings highlight the potential of FSW for creating du-158 rable, lightweight structures that meet the stringent demands of the marine industry.

2. Materials and Methods

2.1. Materials

The T-joint setup for this study employs two aluminum alloys, i.e., AA6082 and 162 AA5083, both with a thickness of 6 mm. The sizes are, respectively, 100 mm x70 mm and 163 100 mm x 50 mm. 164

The skin component is fabricated from AA6082, an aluminum-silicon-magnesium-165 manganese alloy from the 6000 series, known for its versatile use in general applications. 166 AA6082 offers high mechanical strength, positioned among the highest in its series, with 167 good corrosion resistance, excellent weldability, and machinability, making it suitable for 168 sheets, plates, bars, tubes, and profiles. It is typically available in the T6 temper, with other 169 tempers upon request. This alloy is frequently used in automotive and rail construction, 170 as well as in structural and architectural components where high corrosion resistance is a 171 key requirement. 172

The stringer is constructed from AA5083, an aluminum-magnesium alloy valued for 173 its outstanding oxidation and corrosion resistance, though with moderate mechanical 174 strength and good formability. AA5083 is also weldable by fusion and retains high tough-175 ness at both ambient and low temperatures. This alloy is commonly available in the 176 0/H111 temper for maximum formability and in the H22 temper, which balances forma-177 bility with increased strength. AA5083 finds wide application in marine and cryogenic 178 structures, pressure vessels, tankers, panels, wheels, and other components requiring fa-179 tigue resistance and good durability in corrosive environments without the need for high 180 static mechanical strength. It is a suitable choice for components to be integrated into 181 welded assemblies. 182

Table 1 and Table 2 show, the chemical composition and the main mechanical properties of the two alloys.

The metallurgical characteristics of AA5083 and AA6082 play a pivotal role in their 185 behavior during friction stir welding (FSW), particularly in dissimilar joint configurations. 186 AA5083, classified as a strain-hardenable aluminum-magnesium alloy, derives its 187 strength primarily from solid solution strengthening and strain hardening. Its high mag-188 nesium content enhances corrosion resistance, especially in marine environments, while 189 contributing to moderate mechanical strength. However, its non-heat-treatable nature 190 limits further strength enhancement through thermal treatments, making it sensitive to 191 the heat input during FSW. Excessive heat can result in a loss of strain hardening effects, 192 leading to localized softening. 193

Conversely, AA6082, a precipitation-hardenable alloy from the 6000 series, relies on 194 the formation of Mg2Si precipitates for its strength, particularly in the T6 temper. During 195 FSW, the thermal cycle can dissolve these precipitates and induce grain growth in the 196 weld zone (WZ) and adjacent areas, such as the heat-affected zone (HAZ). These changes 197 can reduce mechanical performance, necessitating precise control of the heat input to pre-198 serve the alloy's properties. 199

The combination of these two alloys in dissimilar FSW joints introduces additional 200 complexities. Studies have shown that process parameters, particularly rotational speed 201 and tool feed rate, significantly influence the joint's mechanical properties and microstruc-202 ture. Higher rotational speeds tend to enhance material mixing and interfacial bonding 203 but can also lead to defects such as voids or wormholes due to turbulent flow. On the 204

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other hand, lower rotational speeds reduce the risk of defect formation but may limit ef-205 fective mixing, especially in the stir zone (SZ), where both alloys interface. 206

Residual stress formation is another critical factor in dissimilar joints of AA5083 and 207 AA6082. AA5083, being softer, accommodates more deformation, resulting in an asym-208 metric distribution of residual stresses. This asymmetry affects the overall mechanical per-209 formance and fatigue resistance of the joint. 210

Optimizing FSW parameters for these alloys involves balancing heat input to achieve 211 effective mixing, minimize defects, and maintain the inherent mechanical properties of 212 both materials. A moderate rotational speed can help create a homogeneous weld zone 213 and ensure a smooth transition between the two base materials, which is essential for ap-214 plications requiring robust and reliable joints [27,28]. 215

Table 1. Chemical composition of AA6082 and AA5083 alloys (Weight %).

	Al	Cr	Cu	Fe	Mg	Mn	Si	Ti	Zn	Others
AA6082	95.20-98.30	< 0.25	< 0.1	< 0.5	0.6-1.2	0.4-1.0	0.7-1.3	0.10	0.20	0.15
AA5083	92.55-95.55	0.05-0.25	< 0.1	< 0.4	4.0-4.9	0.4-1.0	< 0.4	0.15	0.25	-

Table 2. Mechanical properties of AA6082 and AA5083 alloys.

	Rm [MPa]	Rp0.2 [MPa]	A [%]	HB
AA6082	310	260	10	94
AA5083	275	125	15	75

2.2. Joining manufacturing

The joints were produced in accordance with [18], under controlled laboratory con-219 ditions, with standard temperature and humidity levels, ensuring consistency in the weld-220 ing environment, using a 3-axis ESAB LEGIO™ 3ST FSW machine (OEMER Motori 221 elettrici, Rescaldina, Italy - Figure 1a), where the aluminum plates (i.e., skin and striger) 222 were fixed with a clamping device (see Figure 1b) [29].

This equipment, similar in structure to a manual milling machine, benefits from force-controlled operation in addition to positional control, enhancing the precision of the 225 friction stir welding (FSW) process. The machine operates under a PLC (Programmable 226 Logic Controller) interface, which provides real-time control and data recording for vari-227 ables such as applied force, spindle resistance torque, displacement along the z and x axes, 228 spindle current, and spindle power. 229

To ensure robust weld quality, a double-shoulder tool design was used (see. Figure 230 2), particularly beneficial in T-joint configurations to enhance heat distribution at the tool 231 edges and reduce the risk of tunnel defects. This design mitigates common issues in transparency-welded T-joints, where excessive heat generated by the shoulder on the skin can 233 cause an uneven heat spread, forming a comet-like expansion pattern on the skin. The 234 double-shoulder approach enables focused heat transfer, allowing the weld to forge effec-235 tively at the intersections with the skin and stringer, leading to well-forged connections. 236 The tool was made of H13 tool steel, selected for its high wear resistance and thermal 237 stability, with a hardness of approximately 50 HRC. 238

For this study, three distinct heat input levels (low, medium, and high) were tested 239 to observe variations in joint quality. Then, the welding parameters included three rota-240 tional speeds (900 rpm, 700 rpm, and 500 rpm) at a welding speed of 100 mm/min. These 241 rotational speeds were selected to represent a range of heat inputs, allowing the investi-242 gation of their influence on defect formation, material mixing, and mechanical perfor-243 mance. The experimental setup ensured a stable welding process with well-defined 244 steady-state regions, enabling a thorough analysis of the mechanical properties. 245

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Figure 1. a) FSW machine; b) Clamping device.



Figure 2. Double-shoulder tool.

Figure 3 shows a typical sample after the FSW process. For each configuration, three of these were manufactured. It is possible to observe:

- in the top view, the forging intersections between the skin and the stringer;
- in the bottom view, both the welding area with the points of start and end and the directions of advancing and retreating. 254

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Figure 3. Friction Stir Welded T-joint (top and bottom view).

2.3. Testing

The experimental testing in this study was solely conducted on the friction stir welded Tjoints, without performing additional tests on the base materials. This approach aligns with the study's primary objective of evaluating the joint performance and understanding the effects of rotational speed on weld quality and mechanical behavior.

2.3.1. Pull-out test

A Zwick-Roell 600 Universal Testing Machine (ZwickRoell S.r.l., Genova, Italy), equipped with a 10 kN load cell and tension clamps, was used (see Figure 4) to evaluate the pull-out resistance of the T-joints, following the procedure described in [18].



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To ensure the reliability of the results, all tests were conducted on at least three sam-269 ples for each welding condition. Samples, with a standardized width of 25 mm, were ex-270 tracted from the central regions of the welded joints to minimize variability and ensure 271 representativeness. Additionally, the pull-out tests were performed under controlled con-272 ditions, using calibrated equipment to guarantee consistent loading rates (i.e., 2 mm/min) 273 and measurement accuracy. 274

The pull-out test offers distinct advantages over conventional tensile tests when eval-275 uating T-joints. Unlike tensile testing, which applies a purely axial force, the pull-out test 276 more accurately simulates real-world loading conditions by focusing on the resistance of 277 a joint against detachment forces. This approach can provide insights into the adhesion 278 strength, failure mechanisms, and quality of the bond between materials, especially im-279 portant in assessing joints with complex geometries or varying cross-sectional properties. 280 Additionally, pull-out tests can better reveal weak points across different weld zones, such 281 as the Heat-Affected Zone (HAZ) or the Thermomechanically Affected Zone (TMAZ), 282 which are critical for understanding performance under operational stresses. 283

Fracture surfaces were examined to validate the observed failure modes and identify potential defects, such as wormholes.

2.3.2. Micro-hardness

The joint was sectioned to prepare a sample that is representative of the stable length 287 of weld. Its surface was first polished using sandpapers to achieve a mirror-like finish, 288 then microhardness measurements were conducted on cross sections extracted from the 289 center of the welds. Specifically, Vickers hardness tests were performed using a FUTURE-290 TECH FM-300e (FUTURE TECH CORP., Kawasaki-City, Japan) microhardness tester, ap-291 plying a 200g load. In accordance with ASTM E384-17 Standard [30], the spacing between 292 adjacent indentations was maintained at a minimum of 2.5 times the diagonal length of 293 each indentation to prevent any interference between measurements. 294

These measurements provide valuable insights into the hardness distribution across the weld zones, helping to assess the effects of friction stir welding on material properties. Hardness variations across different zones, such as the Stir Zone (SZ), Thermomechanically Affected Zone (TMAZ), and Heat-Affected Zone (HAZ), can reveal important information about the microstructural transformations induced by the welding process [31].

Figure 5a reports the test plan for the direction along the skin. The measurements were conducted along three parallel lines: Upper, Middle, and Lower, including about 44 measurements for line. Figure 5b reports the test plan for the direction along the stringer at the interface between the two alloys. The measurements were conducted along three parallel lines: Left, Middle, and Right, including about 23 measurements for sample.



Figure 5. Test Plan: a) along the kin direction; b) along the stringer direction.

3. Results and Discussion

Joints produced at different rotational speeds exhibited notable visual differences. At 500 rpm, the joint surface appeared smooth and defect-free, while at higher speeds (700 309

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rpm and 900 rpm), surface irregularities and indications of wormhole defects were more 310 prominent. These observations align with the mechanical and microstructural analyses 311 discussed in this study. 312

3.1. Pull-out test

To understand the junction mechanical performance of the specimens, T-pull tests 314 were chosen as the first analysis. Figure 6 shows the load-displacement curve for the sam-315 ple welded at 500 rpm, accompanied by sequential images illustrating the fracture evolu-316 tion at corresponding points along the curve. This comprehensive representation eluci-317 dates the material behavior under load and the progression of failure mechanisms. 318



Figure 6. Typical stress-displacement curve for 500 rpm sample.

Particularly, it is possible to observe the following steps:

- Initial Loading Phase: At the onset, the curve exhibits a linear increase in load with displacement, indicating elastic deformation of the material. During this phase, the material responds proportionally to the applied load without permanent deformation.
- Onset of Plastic Deformation and Crack Initiation: As the load continues to increase, the curve begins to deviate from linearity, marking the transition to plastic deformation. At this stage, microstructural changes occur, leading to the initiation of cracks. The first accompanying image captures the sample during the initial stages of the test, prior to visible crack formation. 330
- Crack Propagation: With further loading, the curve approaches its peak, and the ma-331 terial undergoes significant plastic deformation. The second image illustrates the 332 propagation of initial cracks, as denoted by the circles. This phase is characterized by 333 the growth and coalescence of microvoids, leading to the advancement of cracks 334 through the material. The material's ability to undergo plastic deformation allows for 335 the redistribution of stress, delaying catastrophic failure. 336
- Peak Load and Onset of Final Fracture: The curve reaches its maximum load-bearing 337 capacity at the peak, beyond which the load begins to decline. This decline signifies 338 the material's reduced ability to withstand the applied load due to extensive internal 339 damage. The third image captures the final ductile fracture occurring in the central 340 region of the sample. This type of fracture is characterized by significant plastic de-341 formation, often presenting as a cup-and-cone fracture surface, indicative of the ma-342 terial's ductile nature. 343
- Post-Fracture Behavior: Following the peak, the load decreases steadily as the mate-344 rial can no longer sustain the applied stress, leading to complete separation. The 345 gradual slope of the descending curve reflects the material's capacity to absorb 346

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energy through plastic deformation before final failure, a desirable trait in applications requiring toughness and resistance to sudden fracture. 348

Then, this curve for the 500 rpm welded sample demonstrates a typical ductile fracture behavior, characterized by initial elastic deformation, followed by plastic deformation with crack initiation and propagation, culminating in a ductile fracture with significant energy absorption. This behavior suggests that the welding parameters at 500 rpm facilitated optimal material flow and bonding, resulting in a joint capable of sustaining substantial deformation before failure.

Figure 7 illustrates the load-displacement curve for the sample welded at 700 rpm, accompanied by sequential images depicting key stages in the fracture process.





This representation provides insight into the material's behavior under load and highlights the influence of internal defects, particularly wormholes, on the fracture mechanism.

Also in this case, it is possible to observe several steps:

- Initial Elastic Phase: The curve begins with a linear increase in load relative to displacement, indicating elastic deformation. During this phase, the material responds proportionally to the applied load without permanent deformation.
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- First Peak and Wormhole Wall Fracture: As the load increases, the curve reaches an initial peak, corresponding to the fracture of the wormhole wall within the weld 367 zone. This initial peak is absent in the 500 rpm sample, suggesting that higher rotational speeds may contribute to the formation of internal defects such as wormholes. 369 The first image captures this stage, highlighting the initial crack formation at the 370 wormhole site. 371
- Crack Propagation on Opposite Side: Following the initial peak, the load decreases 372 slightly before increasing again, indicating the material's attempt to redistribute 373 stress. During this phase, a crack initiates on the side opposite to the wormhole and 374 begins to propagate. The second image illustrates this crack propagation, as denoted 375 by the arrows. This behavior suggests that the presence of the wormhole creates 376 stress concentrations, leading to crack initiation on the opposing side. 377
- Second Peak and Central Fracture: The curve reaches a second peak as the material's 378 load-bearing capacity is temporarily restored. However, as the crack propagates to-379 wards the center, the load decreases sharply, culminating in a central fracture. The 380 third image captures this final fracture, characterized by a brittle failure mode with 381 minimal plastic deformation. 382
- Post-Fracture Behavior: After the central fracture, the load drops to zero, indicating 383 complete separation of the material. The steep decline in the curve reflects the 384

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material inability to absorb energy through plastic deformation, a characteristic of 385 brittle fracture. 386

The load-displacement curve for the 700 rpm welded sample exhibits a distinct initial 387 peak corresponding to the fracture of internal defect structures, followed by crack initia-388 tion and propagation on the opposite side, leading to a central brittle fracture. This behav-389 ior contrasts with the ductile fracture observed in the 500 rpm sample and suggests that 390 higher rotational speeds may introduce internal defects that compromise the joint's integ-391 rity. Although internal defects are also present in the 500 rpm sample, their influence is 392 less pronounced, likely due to smaller size and reduced stress concentration effects, re-393 sulting in a more ductile fracture behavior. Fracture surface observations revealed the 394 presence of weld imperfections, particularly wormholes, which were most prominent in 395 joints fabricated at rotational speeds of 700 rpm and 900 rpm. These defects, likely caused 396 by turbulent material flow and insufficient consolidation, acted as stress concentrators, 397 contributing to premature failure. In contrast, joints fabricated at 500 rpm exhibited sig-398 nificantly fewer and smaller imperfections, indicating more stable material mixing and a 399 better thermal balance during welding. This correlation between defect formation and 400 joint performance highlights the critical role of optimizing rotational speed to minimize 401 imperfections and enhance joint quality. These findings underscore the importance of op-402 timizing welding parameters to minimize defect formation and enhance joint perfor-403 mance [32]. 404

The sample welded at 900 rpm exhibits a similar load-displacement behavior to the 700 rpm sample, as evidenced in Figure 8, indicating that higher rotational speeds may lead to comparable internal defects and fracture mechanisms.



Figure 8. Comparison of Stress-Displacement curves.

The comparative analysis of joint strengths for samples welded at rotational speeds 410 of 500, 700, and 900 rpm (Figure 9) reveals a notable dispersion in the data. Despite the 411 scatter, the results indicate that joints welded at 500 rpm generally exhibit higher strength 412 due to better material flow and fewer defects, such as wormholes. This highlights the crit-413 ical influence of rotational speed on joint quality. Lower rotational speeds generate less 414 heat, promoting a more controlled material flow and reducing the likelihood of defect 415 formation. This controlled environment facilitates better consolidation of the material, re-416 sulting in joints with fewer internal voids and improved mechanical properties. 417

Conversely, higher rotational speeds (700 and 900 rpm) result in excessive heat gen-418 eration, leading to turbulent material flow and an increased likelihood of internal defects, 419

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such as wormholes. The elevated temperatures also induce microstructural changes, such 420 as grain coarsening, that adversely affect the joint's strength. These findings underline that 421 rotational speed directly impacts the mechanical performance of welded joints. Specifi-422 cally, the results demonstrate that 500 rpm provides a balance between heat input, mate-423 rial flow, and defect minimization, resulting in superior joint quality. This study offers 424 actionable insights into the optimization of welding parameters to achieve high-quality 425 joints for industrial applications. 426





In Figure 10, the observations of fracture surfaces in friction stir welded (FSW) samples at rotational speeds of 500, 700, and 900 rpm reveals notable differences in three key regions: the Stir Zone (a), the Wormhole Defect area (b), and the Transition Zone (c).

At 500 rpm, the SZ exhibits a uniform and well-mixed appearance, indicating effec-432 tive material stirring. In contrast, at 700 and 900 rpm, the SZ becomes less homogeneous, 433 displaying signs of turbulence and irregular material flow. 434

Regarding the Wormhole Defect area, while wormholes are present across all sam-435 ples, their positioning differs. In the 500 rpm sample, the wormhole is situated in a manner 436 that influences the fracture path differently compared to the 700 and 900 rpm samples. 437 This positional variation affects how the wormhole impacts the mechanical integrity of the joint.

The Transition Zone, which lies between the SZ and the base material, also varies 440 with rotational speed. At 500 rpm, this zone appears more gradual, suggesting a smoother 441 transition between stirred and unstirred material. In contrast, at 700 and 900 rpm, the 442 Transition Zone becomes more pronounced, with sharper boundaries and thinner fea-443 tures, indicating a steeper gradient in thermal and mechanical effects. 444

In the 500 rpm sample, the Transition Zone (Region C) appears smoother and more 445 gradual in its transition from the Stir Zone to the base material. This gradual shift suggests 446 a more balanced thermal gradient and mechanical transition due to the controlled heat 447 input at this lower rotational speed, which may contribute to a more stable microstructure 448 and improved mechanical properties. In contrast, at higher rotational speeds (700 and 900 449 rpm), the Transition Zone shows sharper boundaries and thinner features, indicating a 450 steeper gradient and increased stress, which could lead to residual stresses and reduced 451 weld quality. 452

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These observations suggest that higher rotational speeds may lead to increased heat 453 input and turbulent material flow, resulting in more pronounced defects and transition 454 zones. Conversely, a lower rotational speed appears to promote more stable material flow 455 and fewer defects, leading to improved weld quality [33]. 456



Figure 10. Failure surfaces.

3.2. Micro-hardness

The microhardness profiles along the skin direction for samples welded at rotational speeds of 500, 700, and 900 rpm exhibit distinct characteristics, reflecting the microstructural changes induced by each welding parameter, as illustrated in Figure 11.

- 500 rpm Sample: The microhardness distribution is relatively uniform across the three measurement lines (Upper, Middle, Lower), with values ranging approximately between 75 HV and 90 HV, centering around 80 HV. This uniformity indicates a stable and homogeneous microstructure, suggesting that the heat input at this rotational speed is sufficient for effective material plasticization without causing overheating. Moderate heat input promotes the formation of a fine and consistent microstructure, as supported by studies on friction stir welding (FSW) of aluminum alloys [34].
- 700 rpm Sample: The microhardness profiles display more pronounced variations, with values oscillating between 70 HV and 100 HV. The three measurement lines show significant discrepancies, indicating a less uniform microstructure. The increased rotational speed leads to higher heat input, which can cause grain growth and uneven hardness distribution. This behavior aligns with findings in the literature, where excessive heat input during FSW results in undesirable microstructural changes [35].
- 900 rpm Sample: The profiles exhibit even more marked fluctuations, with hardness values ranging from 65 HV to 95 HV. The distinct separation among the three lines reflects significant heterogeneity in the microstructure. The elevated heat input at this rotational speed may lead to overheating, causing excessive grain growth and a reduction in hardness. Studies have shown that high heat input can negatively affect the microstructure and mechanical properties of welded joints [36].

The analysis of microhardness profiles highlights how rotational speed directly influences heat input and, consequently, the microstructure of the welded joint. A rotational speed of 500 rpm appears to offer an optimal balance, ensuring adequate heat input for

effective plasticization without causing overheating. This results in a uniform microstruc-488 ture and consistent hardness values, which are crucial for maintaining the mechanical integrity of the joint. In contrast, higher rotational speeds introduce variability in microstructure and hardness, potentially compromising the joint's performance. 491



Figure 11. Micro-hardness measurements along the skin direction.

The microhardness profiles along the stringer direction, represented in Figure 12, il-496 lustrate the transition between the skin (AA6082) and stringer (AA5083) materials at the 497 midpoint of the x-axis (0 mm). The presence of three distinct measurement lines (Left, 498

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Middle, Right) provides a detailed view of the interface behavior under different rotational speeds. 500

Figure 12. Micro-hardness measurements along the stringer direction.

500 rpm Sample: The transition from AA5083 to AA6082 exhibits a smooth and gradual increase in hardness across all three measurement lines, with values ranging from approximately 40 HV to 80 HV. This gradual transition is consistent across the Left, Middle, and Right lines, indicating effective material mixing and a homogeneous interface. The moderate heat input at 500 rpm ensures controlled material flow, 509

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enabling a seamless blend between the skin and stringer materials. The consistent510alignment of the three lines demonstrates excellent repeatability and stability, high-511lighting this rotational speed as optimal for minimizing stress concentrations and en-512hancing joint integrity.513700 rpm Sample: At 700 rpm, the transition becomes noticeably sharper compared to514the 500 rpm sample. Hardness increases abruptly from approximately 40 HV to 80515HV near the boundary. The three measurement lines begin to diverge slightly, with516the Left and Right lines showing more pronounced fluctuations compared to the517

- the Left and Right lines showing more pronounced fluctuations compared to the Middle line. This suggests uneven material mixing, potentially caused by the higher heat input disrupting the flow dynamics. The abrupt transition reflects limited intermixing between the skin and stringer materials, potentially leading to stress concentrations and reduced joint stability. This behavior may result in a less ductile and more brittle interface.
- 900 rpm Sample: The profiles at 900 rpm exhibit the most abrupt transition, with 523 hardness values sharply increasing from 40 HV to 80 HV within a very narrow zone. 524 Significant discrepancies between the Left, Middle, and Right lines highlight incon-525 sistent material behavior at this rotational speed. This irregularity is indicative of lo-526 calized overheating and turbulent material flow, which inhibit effective inter-diffu-527 sion between AA6082 and AA5083. The distinct separation of the three curves sug-528 gests a lack of uniformity in the interface, likely resulting in higher stress concentra-529 tions and structural weaknesses in the joint. 530

The comparative analysis of the microhardness profiles underscores the critical role of rotational speed in determining the quality of the skin-stringer interface. The 500 rpm sample demonstrates superior material mixing and uniformity, resulting in a gradual transition and reduced stress concentrations. In contrast, the 700 and 900 rpm samples exhibit increasingly abrupt transitions and greater variability between the measurement lines, reflecting limited mixing and potential weaknesses at the boundary [37].

This behavior correlates strongly with the fracture surface conformations observed537during mechanical testing. The smoother and more homogeneous hardness transition in538the 500 rpm sample aligns with ductile fracture characteristics and enhanced joint toughness. Conversely, the sharper transitions and variability in hardness profiles for the 700540and 900 rpm samples are consistent with brittle fracture surfaces, characterized by localized stress concentrations and defects at the interface.541

5. Conclusions

This study investigates the influence of rotational speed on the mechanical and microstructural properties of friction stir welded T-joints made from AA5083 and AA6082 alloys. The results demonstrate that rotational speed significantly affects defect formation and joint performance. 547

Joints fabricated at 500 rpm exhibit higher mechanical strength and a more uniform microhardness profile, attributed to moderate heat input, which facilitates controlled material mixing and minimizes defect formation. In contrast, joints produced at 700 and 900 rpm show reduced mechanical performance and irregular hardness profiles due to increased heat input, leading to grain coarsening and the formation of defects such as wormholes. Fracture surface analysis confirms that these defects act as stress concentrators, significantly compromising joint integrity.

The correlation between welding parameters, defect formation, and mechanical properties underscores the critical role of optimizing rotational speed to balance heat input and material flow. Specifically, a rotational speed of 500 rpm achieves a favorable balance, resulting in fewer defects and improved joint performance. These findings provide valuable insights for the development of robust FSW joints, particularly for applications requiring lightweight and durable structures, such as in the marine industry. 555

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Future research should explore additional process parameters, such as tool design	561
and welding speed, to further enhance the quality of friction stir welded joints and mini-	562
mize residual stresses associated with defect formation. <mark>Future research should focus on</mark>	563
the impact properties of FSW T-joints, phase characterization in the weld zones, and the	564
integration of AI-driven approaches for parameter optimization to further enhance joint	565
quality and performance.	566
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