

CFD-based optimal design of a portable and stackable alkaline water electrolyser for hydrogen production

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ABSTRACT

Hydrogen is increasingly recognized as a vital energy carrier for a sustainable future. Among the various methods for hydrogen production, alkaline water electrolysis (AWE) stands out as a well-established and commercially viable option. However, their more effective deployment requires more advanced, portable, and scalable designs. This study explores systematic model-based shape optimization of the next generation AWE based on computational fluid dynamic (CFD) aimed to enhance the hydrodynamics and electrochemical performance. Several design geometries and arrangements were proposed including flow baffles to enhance hydrodynamic and facilitate detachment of oxygen and hydrogen bubbles. The findings indicate that the optimal design and location of the baffles improve fluid mixing and enhance bubble detachment, resulting in a more uniform electrolyte distribution and decreased concentration polarization. Several key performance indicators were considered to analyse the performance of proposed designs including gas production rates, polarization curves, and fluid flow velocity profiles. The insights gained from this research offer valuable recommendations for optimizing flow field designs in alkaline water electrolyzers, aiming to enhance efficiency and operational robustness.

Keywords: Alkaline water electrolysis, zero-gap cell, CFD, Pyramidal pins, Mesh electrode, Multiphysics model

INTRODUCTION

Hydrogen is becoming essential in the transition to decarbonized energy systems, influenced by climate targets and energy security [1, 2]. The global demand for hydrogen is expected to increase significantly, shifting from fossil-based “grey hydrogen” to low-carbon “green hydrogen,” produced through water electrolysis using renewable energy [3]. Hydrogen production via water electrolysis is a key enabling technology for future low-carbon energy systems[4]. There are three primary methods for water electrolysis: alkaline water electrolysis (AWE), proton exchange membrane electrolysis (PEM), and solid oxide electrolysis (SOEC) and among them, alkaline water electrolysis (AWE) is the most established for hydrogen production [1, 3–6]. It offers advantages such as lower material costs, reliance on non-noble catalysts, longer stack lifetimes, and scalability for large deployments, especially in regions abundant in renewable resources [5, 7, 8]. AWE's reliability and adaptability to variable operating conditions are crucial as electrolysis

facilities align with fluctuating renewable energy supplies. This adaptability makes AWE an economically viable option for large-scale hydrogen production [9, 10]. As the world moves towards sustainable energy solutions, AWE is positioned to play a significant role in meeting the rising demand for green hydrogen[4].

Alkaline water electrolysis (AWE) faces significant challenges due to complex hydrodynamics, particularly the behavior of gas bubbles at the electrode-electrolyte interface [6, 11, 12]. These bubbles can create localized concentration gradients, increase ohmic losses, and generate thermal hotspots, ultimately diminishing energy efficiency [12]. Factors such as electrode shape, channel geometry, operating conditions, and cell integration strategies influence the distribution of gas and liquid, making the optimization of bubble behavior and internal flow essential for enhancing system performance [7, 9, 11]. Traditional AWE designs often utilize concave-convex spherical (SCC) flow channels to improve mixing; however, these can also lead to stagnant regions and bubble trapping, resulting in non-uniform mass transfer

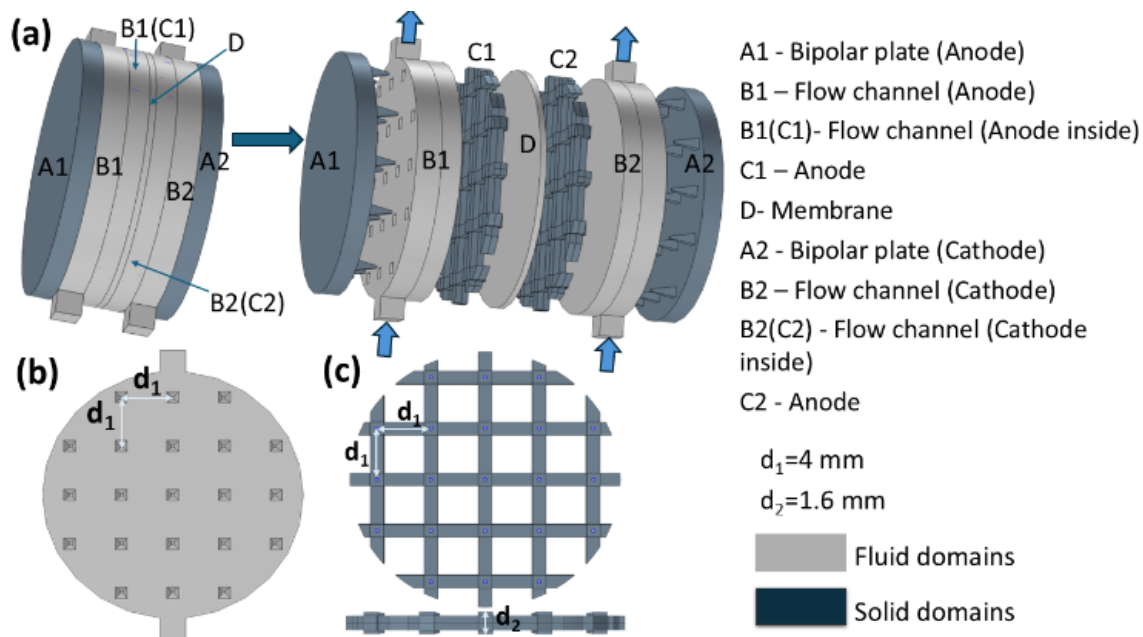


Figure 1. Schematics of the alkaline water electrolyzer with individual components, (b) arrangement of the pyramidal pins in the flow channel, and (c) mesh electrode.

[12]. A potential solution involves replacing porous electrodes with mesh-type structures, which may decrease bubble residence time and improve gas release [13]. Nonetheless, the interplay between mesh electrodes, SCC flow fields, and various operational variables have yet to be thoroughly investigated in a cohesive framework.

With increasing computational power, computational fluid dynamics (CFD) methods have gained widespread adoption across multiple disciplines. These methods have been widely implemented to support the optimal design and operation of multiphase systems across multiple scales, from microfluidic devices to mesoscale processes and full industrial-scale systems [14, 15]. Recent CFD applications highlight systematic geometry and shape optimization of small-scale packed-bed reactors with complex internal structures [16]. These methods have opened new opportunities for more effective in silico prototyping, enabling faster design, evaluation, and optimization of next-generation processes and technologies. The proposed CFD-based design framework of zero-gap alkaline electrolyzers allows more robust geometries and configuration through a detailed three-dimensional multiphysics simulation which addresses the limitations of the existing designs. The method incorporates crucial aspects such as heat transfer, gas-liquid transport, and electrochemical kinetics, facilitating a comprehensive assessment of how localized gradients affect system performance. The model evaluates critical parameters including cell voltage, temperature, and inlet

flowrate collectively, revealing their interactions and providing insights for optimizing device performance beyond single-parameter analysis. Most importantly, the CFD-based approach reveals more effective alternatives to the traditional porous electrodes such as mesh-type electrodes, enhancing productivity and hydrodynamic performance particularly more effective bubble detachment and transport. The identified optimal designs featuring pyramidal pin structures on the bipolar plates. The method also informed the best trade-offs between mixing and bubble detachment. Ultimately the framework offers essential design insights laying the foundation for enhanced efficiency and durability of industrial green hydrogen production systems.

METHODOLOGY

A numerical model representing a single cell of an alkaline water electrolyzer is illustrated in **Figure 1**. The computational domain encompasses flow channels, cathode and anode mesh electrodes, bipolar plates, and a porous membrane region that separates the two half-cells. The electrodes are of non-porous made of Nickel metal. Pyramidal pin structures are integrated into the flow channels and attached to the bipolar plates, with sharp edges oriented towards the electrodes to enhance flow distribution and induce local turbulence. The geometric dimensions and physical properties are detailed in **Table 1** and **Table 2**.

Table 1: Geometric parameters of the alkaline water electrolyser model.

Description	Value
Cathode and anode radius	10 mm
Cathode thickness	1.6 mm
Anode thickness	1.6 mm
Flow channel radius	10.1 mm
Flow channel thickness	3.6 mm
Bipolar plate radius	10 mm
Bipolar plate thickness	0.5 mm
Membrane radius	10.1 mm
Membrane thickness	0.5 mm

Table 2: Physical parameters of the alkaline water electrolyser model.

Parameter	Value
Membrane porosity	0.5
Reference exchange current density (anode)	100 A/m ²
Reference exchange current density (cathode)	0.1
Transfer coefficient (anode)	0.5
Transfer coefficient (cathode)	0.5
Inlet electrolyte velocity	0.01 m/s - 0.2 m/s
Outlet pressure	1 atm
Electrolyte conductivity	40 S/m
Bipolar plate conductivity	4.032e6 S/m
Nickel mesh electrode conductivity	13.8e6 S/m
Electrode active surface area	6.06 cm ²
Operating temperature	80 C
Cell voltage	1.3 V - 2.3 V
Electrolyte concentration (KOH)	3 M

Governing equations

The following equations are employed to solve the physics described above:

Electrochemical model

Alkaline water electrolysis splits water into hydrogen and oxygen using electrochemical reactions at the cathode and anode. An aqueous alkaline solution like KOH serves as the electrolyte, supplying hydroxide ions (OH^-) for charge transport, driven by electrical potential.

At cathode (hydrogen evolution reaction – HER):



At anode (oxygen evolution reaction – OER):



The total cell voltage is calculated by

$$E_{total} = E_{equi} + \eta_{acti} + \eta_{ohmic} \quad (3)$$

The equilibrium cell potential is calculated from the Nernst equation as follows:

$$E_{equi} = E_{0,ref}(T) + \frac{RT}{2F} \ln \left(\frac{p(O_2)^{0.5} p(H_2)}{p(H_2O)} \right) \quad (4)$$

The Butler-Volmer equation describes the relationship between the local current density and activation overpotential as follows:

$$i_{cathode} = a_{HER} i_{0,HER} (1 - s_g) \left[\exp \left(\frac{\alpha_c F \eta_{HER}}{RT} \right) - \exp \left(\frac{(1 - \alpha_c) F \eta_{HER}}{RT} \right) \right] \quad (5)$$

$$i_{anode} = a_{OER} i_{0,OER} (1 - s_g) \left[\exp \left(\frac{\alpha_a F \eta_{OER}}{RT} \right) - \exp \left(\frac{(1 - \alpha_a) F \eta_{OER}}{RT} \right) \right] \quad (6)$$

The equations for the transport of electrons and ions are given below:

$$\nabla \cdot \mathbf{i}_s = \nabla \cdot \left(-\sigma_s^{eff} \nabla \phi_s \right) = S_{\phi_s} \quad (7)$$

$$\nabla \cdot \mathbf{i}_l = \nabla \cdot \left(-\sigma_l^{eff} \nabla \phi_l \right) = S_{\phi_l} \quad (8)$$

$$\sigma_l^{eff} = \sigma_l (1 - s_g)^{1.5} \quad (9)$$

The ohmic overpotential resulting from the transport resistances of both electrons and ions is described as follows:

$$\eta_{ohmic} = i \left(\frac{\phi_l}{\sigma_l^{eff}} + \frac{\phi_s}{\sigma_s^{eff}} \right) \quad (10)$$

Mass transfer model

The Navier-Stokes equations are employed to determine the fluid velocity and pressure within the flow channels of the electrolyzer in the following manner.:

$$\frac{\partial \rho}{\partial t} + \nabla \cdot (\rho \mathbf{u}) = 0 \quad (11)$$

$$\rho \frac{\partial \mathbf{u}}{\partial t} + \rho (\mathbf{u} \cdot \nabla) \mathbf{u} = \nabla \cdot [-p\mathbf{I} + \mu(\nabla \mathbf{u} + (\nabla \mathbf{u})^T)] + \mathbf{F} \quad (12)$$

The phase transport equations have been adopted to describe the distribution of gas-liquid flow as follows:

$$\frac{\partial \rho_i s_i}{\partial t} + \nabla \cdot (\rho_i \mathbf{u}_i) = 0 \quad (13)$$

$$\frac{\partial \rho_i s_i}{\partial t} + \nabla \cdot \left[-\rho_i K \frac{K_{r_i}}{\mu_i} (\nabla p_i - \rho_i \mathbf{g}) \right] = Q_i \quad (14)$$

$$Q_{H_2} = \frac{M_{H_2}}{2F} i_v \quad (15)$$

$$Q_{O_2} = \frac{M_{O_2}}{4F} i_v \quad (16)$$

Heat transfer model

The energy equation has been employed to describe the thermal management inside the electrolyser:

$$(\rho C_p)_{eff} \frac{\partial T}{\partial t} + \rho C_p \mathbf{u} \cdot \nabla T + (-k_{eff} \nabla T) = S_{heat} \quad (17)$$

$$S_{heat} = |i_v| \eta_{acti} + \frac{i_v^2}{\sigma_s} + \frac{i_v^2}{\sigma_l} \quad (18)$$

The governing equations delineated herein were resolved utilizing CFD through the COMSOL Multiphysics 6.4, employing the finite element method (FEM) [12]. A convergence criterion of relative error less than 0.0001 is applied, using the backward difference formula (BDF) method for time-stepping. This analysis was conducted under specific boundary conditions and underlying assumptions.

Boundary conditions

The KOH electrolyte solution enters the flow channels of anode and cathode at their inlets with a defined velocity, respectively. The cell voltage is applied on the bipolar plate and other side of the bipolar is made electric ground. The pressure at the outlets of the flow channels is 0 atm. The gravitational forces during the operation are neglected. The OH^- ions are allowed to pass through the porous membrane.

Assumptions

The flow is assumed to be laminar. There is no crossover of hydrogen and oxygen gases across the membrane. Overpotential losses due to contact resistance inside the electrolyser are assumed to be negligible.

RESULTS AND DISCUSSION

Validation

To assess the accuracy of the multi-physics alkaline electrolyzer model, operational parameters from existing literature were employed [12, 17], specifically at 353.15 K and 1 atm, as shown in **Figure 2**. A comparative evaluation of simulation outcomes alongside experimental data [17] and other literature simulations [12] shows a strong correlation within a current density range of 0.1 A/cm² to 1.4 A/cm². However, at higher current densities, simulated voltages exhibit slight underestimations, likely attributable to the omission of ohmic losses and diffusion voltage effects.

Effect of pyramidal pins on the velocity distribution

The study analyzed the effect of inlet electrolyte velocity on flow patterns in channels with 10 and 24 pyramidal pins on each side of the electrode, as shown in **Figures 3** and **4**. It has been observed that the flow patterns at velocities from 0.01 m/s to 0.2 m/s demonstrated that the pyramidal pin structures induced changes in the flow field, including local redirection, shear-layer formation, and wake recirculation. These alterations were found to depend significantly on both the inlet velocity and the number of the pins.

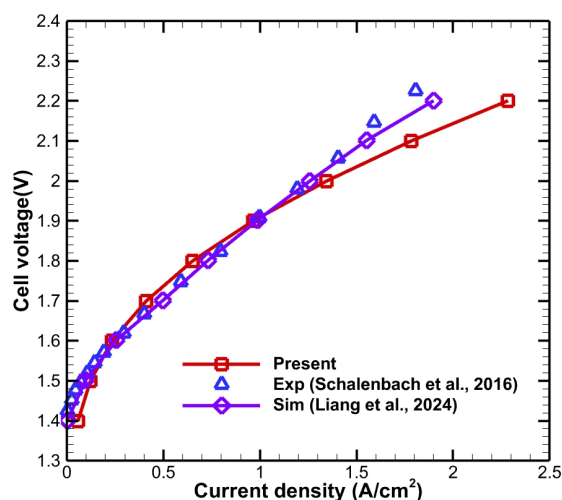


Figure 2. Comparison of the present simulation results against the experimental data [17] and other literature simulations [12].

At low velocity of 0.01 m/s, electrolyte motion was dominated by viscous forces. The 10 pins configuration caused minimal axial flow disruption (refer to **Figure 4(a)**), while the 24 pins setup resulted in increased tortuosity and narrower passages (refer to **Figure 4(a)**), leading to longer residence times and persistent recirculation zones, highlighting significant micro-circulation effects typically seen in creeping flow. Increasing inlet velocities of 0.05 m/s and 0.1 m/s intensified inertial effects, enhancing flow separation and wake formation. Higher pyramidal pin number improved hydrodynamic interactions, promoting vortex-dominated flow, which is crucial for enhancing bubble detachment and gas-liquid mass transfer in electrolyzer channels (refer to **Figures 3(b)-(c)** and **4(b)-4(c)**). At 0.2 m/s, strong convection dominated the flow field. In a 10 pins setup, limited recirculation occurred, while a 24 pins configuration enhanced flow complexity and inter-sphere mixing, resulting in maximum velocity uniformity and minimized small eddies with larger wake structures (refer to **Figures 3(d)** and **4(d)**).

Effect of inlet velocity on the gas volume fraction

The two-phase behavior in the channel arises from the hydrogen evolution reaction at the nickel mesh cathode in alkaline conditions. Gas bubbles form, grow, and detach due to nickel's wettability, leading to localized gas accumulation and high hydrogen volume near the cathode. Inlet electrolyte velocity impacts gas volume fraction distribution, as depicted in **Figures 5** and **6**. At 0.01 m/s, insufficient shear fails to remove bubbles from nickel mesh, increasing residence time and coalescence, leading to higher gas fractions near the cathode, reducing active surface area and hindering reactant replenishment

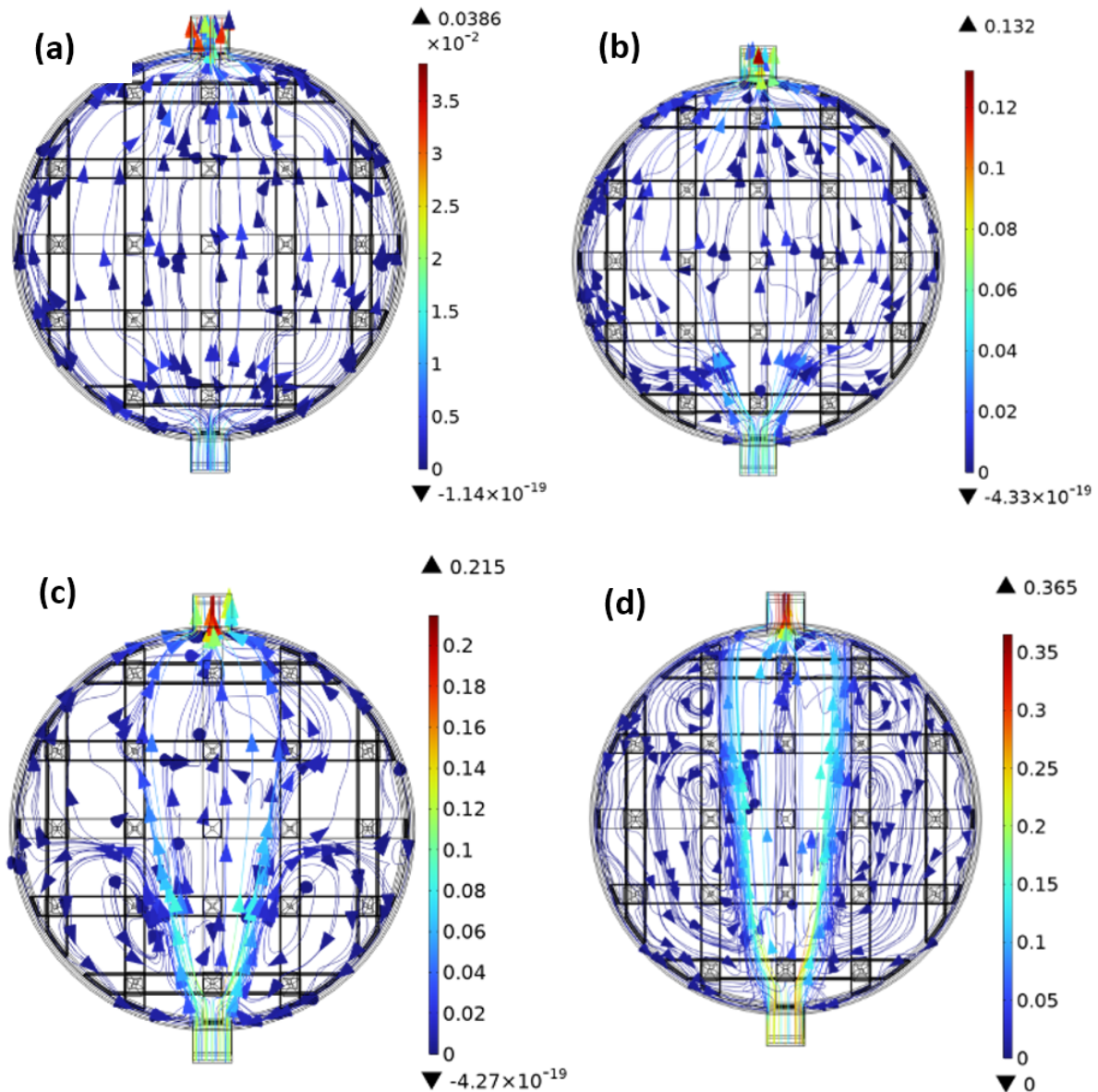


Figure 3. Velocity distribution in channels for 24 pyramidal pins, (a) $v_{in} = 0.01 \text{ m/s}$, (b) $v_{in} = 0.05 \text{ m/s}$, (c) $v_{in} = 0.1 \text{ m/s}$, and (d) $v_{in} = 0.2 \text{ m/s}$.

(refer to **Figures 5(a)** and **6(a)**). Increasing inlet velocity to 0.05–0.1 m/s improved hydrogen bubble removal by enhancing convective forces, reducing gas volume fraction near the cathode. This facilitated electrolyte access to nickel sites, minimized gas holdup, and maintained efficient gas-evolving cathode performance without raising channel pressure losses (refer to **Figures 5(b)–(c)** and **6(b)–(c)**). At 0.2 m/s, the gas volume fraction was minimized, with rapid bubble detachment reducing interaction time with the nickel surface (refer to **Figures 5(d)** and **6(d)**). This inhibited coalescence, promoting effective mass transfer and bubble removal, though it may

require higher pumping power for the system.

The study demonstrated minimal differences in gas volume fraction distributions within channels featuring 10 versus 24 pyramidal pins at varying velocities. While heightened pins number improved fluid tortuosity and localized micro-mixing, it did not significantly influence hydrogen bubble retention or removal on nickel mesh, underscoring the inlet velocity's critical impact on hydrogen gas holdup dynamics.

CONCLUSIONS

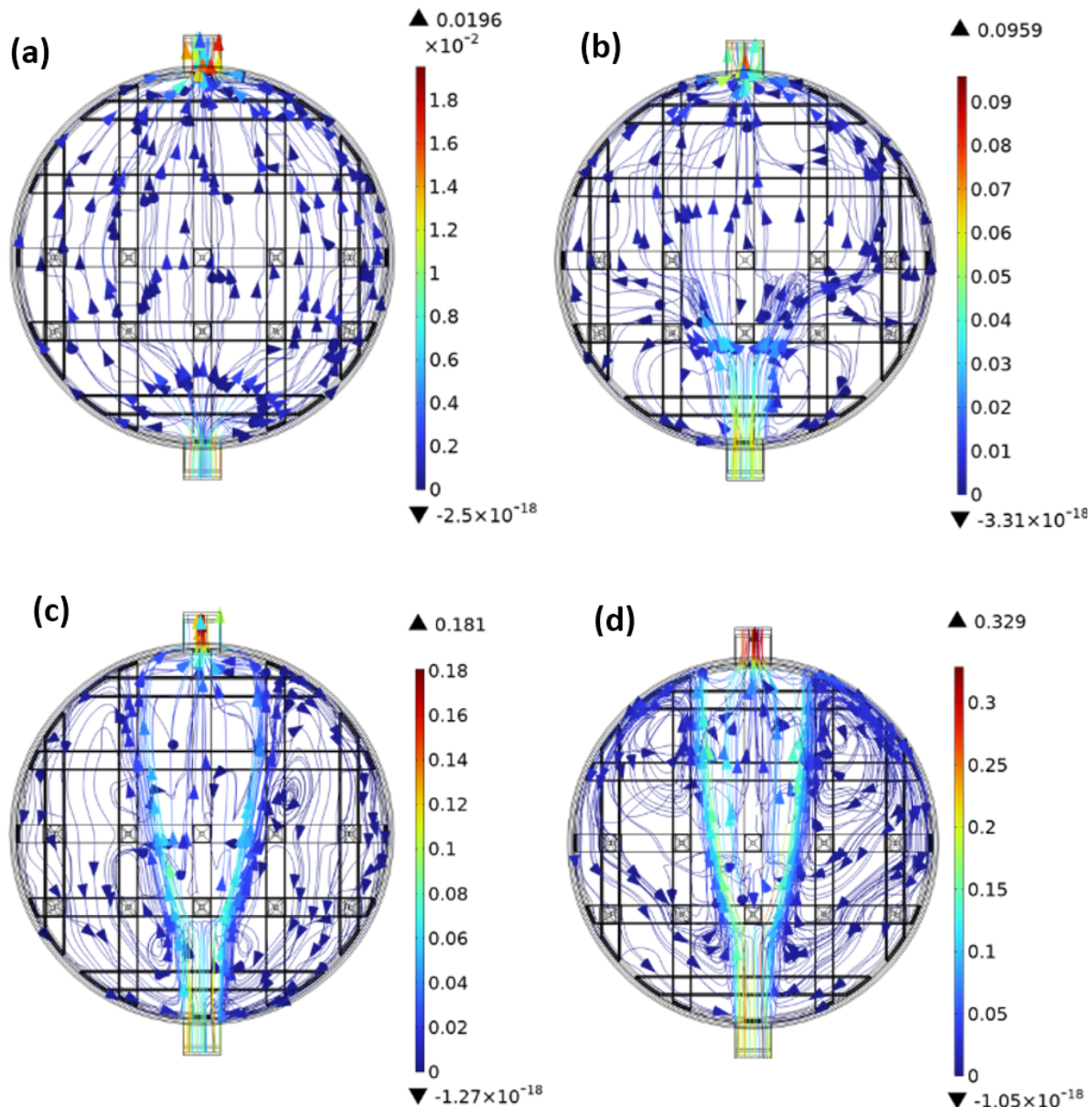


Figure 4. Velocity distribution in channels for 10 pyramidal pins, (a) $v_{in} = 0.01 \text{ m/s}$, (b) $v_{in} = 0.05 \text{ m/s}$, (c) $v_{in} = 0.1 \text{ m/s}$, and (d) $v_{in} = 0.2 \text{ m/s}$.

A three-dimensional multiphysics model was developed to optimize the design of a portable and stackable AWE for hydrogen production exhibiting two-phase flow dynamics and featuring nickel mesh electrodes, augmented by pyramidal pins to enhance flow disturbance and mixing. The simulations, conducted in COMSOL at a voltage of 1.8 V, 3 M KOH and a temperature of 80°C, were rigorously validated for reliability and accuracy. The findings indicated that the inlet electrolyte velocity plays a pivotal role in hydrogen bubble detachment and gas holdup; specifically, lower velocities resulted in increased gas fractions due to bubble retention, whereas higher

velocities facilitated bubble removal. Although increasing the number of pins improved flow tortuosity and micro-mixing, it did not significantly influence bubble detachment, suggesting that bubble dynamics are predominantly governed by bubble growth kinetics and convective shear forces. These findings imply that enhancing convective flow in proximity to gas-evolving electrodes can mitigate mass transfer limitations and enhance electrolyzer efficiency. Future research should prioritize the optimization of pyramidal pin design to maximize mixing while minimizing pressure drop challenges, advocating for multi-objective optimization to inform the

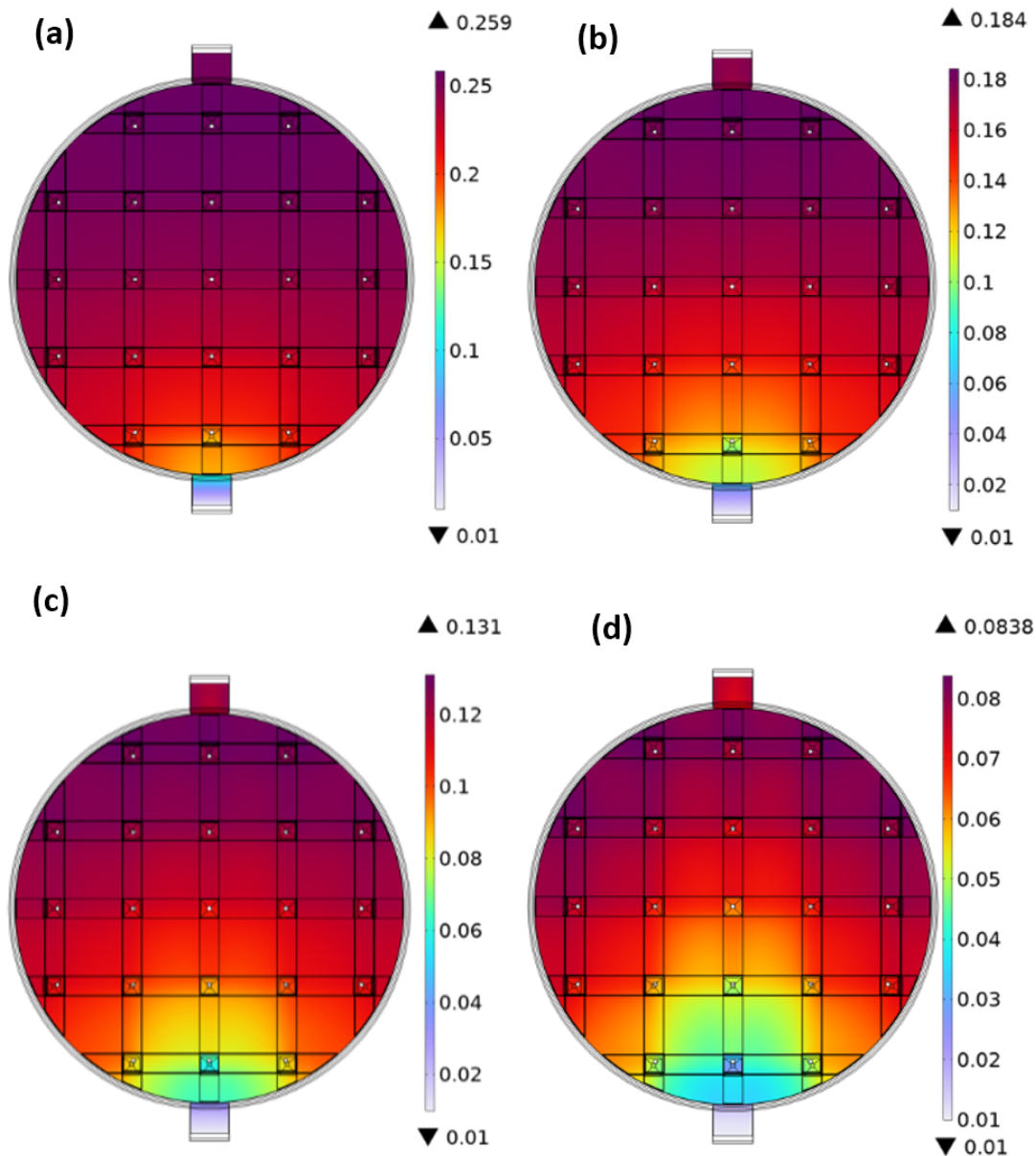


Figure 5. Gas volume fraction distribution in flow channels for 24 pyramidal pins, (a) $v_{in} = 0.01 \text{ m/s}$, (b) $v_{in} = 0.05 \text{ m/s}$, (c) $v_{in} = 0.1 \text{ m/s}$, and (d) $v_{in} = 0.2 \text{ m/s}$.

development of efficient designs of next-generation alkaline electrolyzers.

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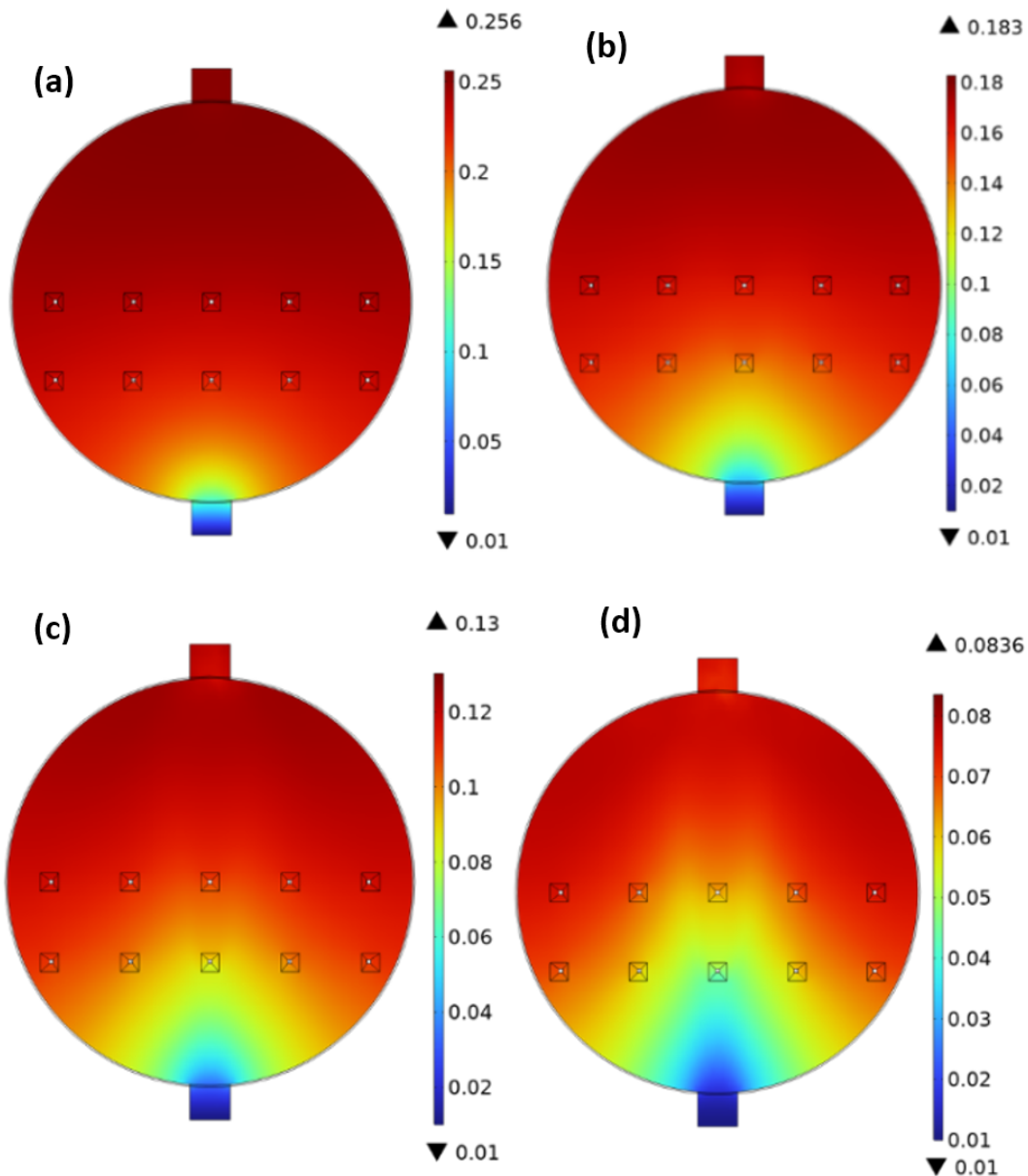


Figure 6. Gas volume fraction distribution in flow channels for 10 pyramidal pins, (a) $v_{in} = 0.01$ m/s, (b) $v_{in} = 0.05$ m/s, (c) $v_{in} = 0.1$ m/s, and (d) $v_{in} = 0.2$ m/s.

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