






Non-Nilpotent Leibniz Algebras with One-Dimensional Derived Subalgebra

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Abstract. In this paper we study non-nilpotent non-Lie Leibniz \mathbb{F} -algebras with one-dimensional derived subalgebra, where \mathbb{F} is a field with $\text{char}(\mathbb{F}) \neq 2$. We prove that such an algebra is isomorphic to the direct sum of the two-dimensional non-nilpotent non-Lie Leibniz algebra and an abelian algebra. We denote it by L_n , where $n = \dim_{\mathbb{F}} L_n$. This generalizes the result found in Demir et al. (Algebras and Representation Theory 19:405-417, 2016), which is only valid when $\mathbb{F} = \mathbb{C}$. Moreover, we find the Lie algebra of derivations, its Lie group of automorphisms and the Leibniz algebra of biderivations of L_n . Eventually, we solve the *coquecigrue problem* for L_n by integrating it into a Lie rack.

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Introduction

Leibniz algebras were introduced by Loday in [19] as a non-skew symmetric version of Lie algebras. Earlier such algebraic structures were also considered by A. Blokh, who called them D-algebras [5] for their strict connection

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with derivations. Leibniz algebras play a significant role in different areas of mathematics and physics.

Many results of Lie algebras are still valid for Leibniz algebras. One of them is the *Levi decomposition*, which states that any Leibniz algebra over a field \mathbb{F} of characteristic zero is the semidirect sum of its radical and a semisimple Lie algebra. This makes clear the importance of the problem of classification of solvable and nilpotent Lie/Leibniz algebras, which has been dealt with since the early 20th century (see [2–4, 9–11, 13] and [14], just for giving a few examples).

In [16] and [17] nilpotent Leibniz algebras L with one-dimensional derived subalgebra $[L, L]$ were studied and classified. It was proved that, up to isomorphism, there are three classes of *indecomposable* Leibniz algebras with these properties, namely the *Heisenberg* algebras \mathfrak{h}_{2n+1}^A , which are parameterized by their dimension $2n + 1$ and by a matrix A in canonical form, the *Kronecker* algebra \mathfrak{k}_n and the *Dieudonné* algebra \mathfrak{d}_n , both parameterized by their dimension only. We want to complete this classification by studying non-nilpotent Leibniz \mathbb{F} -algebras with one-dimensional derived subalgebra, where \mathbb{F} is a field with $\text{char}(\mathbb{F}) \neq 2$. Using the theory of non-abelian extensions of Leibniz algebras introduced in [18], we prove that a non-nilpotent non-Lie Leibniz algebra L with $\dim_{\mathbb{F}} L = n$ and $\dim_{\mathbb{F}} [L, L] = 1$ is isomorphic to the direct sum of the two-dimensional non-nilpotent non-Lie Leibniz algebra S_2 , i.e. the algebra with basis $\{e_1, e_2\}$ and multiplication table given by $[e_2, e_1] = e_1$, and an abelian algebra of dimension $n - 2$. We denote it by L_n . This generalizes the result found in Theorem 2.6 of [11], where the authors proved that a *complex* non-split non-nilpotent non-Lie Leibniz algebra with one-dimensional derived subalgebra is isomorphic to S_2 .

We study in detail the properties of the algebra L_n and we compute the Lie algebra of derivations $\text{Der}(L_n)$, its Lie group of automorphism $\text{Aut}(L_n)$ and the Leibniz algebra of biderivations $\text{Bider}(L_n)$.

Finally, we solve the *coquecigrue problem* for the Leibniz algebra L_n . We mean the problem, formulated by J.-L. Loday in [19], of finding a generalization of Lie third theorem to Leibniz algebras. Using M. K. Kinyon’s results for the class of real *split Leibniz algebras* (see [15]), we show how to explicitly integrate L_n into a Lie rack defined over the vector space \mathbb{R}^n .

1. Preliminaries

We assume that \mathbb{F} is a field with $\text{char}(\mathbb{F}) \neq 2$. For the general theory we refer to [1].

Definition 1.1. A *left Leibniz algebra* over \mathbb{F} is a vector space L over \mathbb{F} endowed with a bilinear map (called *commutator* or *bracket*) $[-, -] : L \times L \rightarrow L$ which satisfies the *left Leibniz identity*

$$[x, [y, z]] = [[x, y], z] + [y, [x, z]], \quad \forall x, y, z \in L.$$

In the same way we can define a *right Leibniz algebra*, using the right Leibniz identity

$$[[x, y], z] = [[x, z], y] + [x, [y, z]], \quad \forall x, y, z \in L.$$

Given a left Leibniz algebra L , the multiplication $[x, y]^{\text{op}} = [y, x]$ defines a right Leibniz algebra structure on L .

A Leibniz algebra that is both left and right is called *symmetric Leibniz algebra*. From now on we assume that $\dim_{\mathbb{F}} L < \infty$.

We have a full inclusion functor $i: \mathbf{Lie} \rightarrow \mathbf{Leib}$ that embeds Lie algebras over \mathbb{F} into Leibniz algebras over \mathbb{F} . Its left adjoint is the functor $\pi: \mathbf{Leib} \rightarrow \mathbf{Lie}$, which associates to each Leibniz algebra L the quotient $L/\text{Leib}(L)$, where $\text{Leib}(L)$ is the smallest bilateral ideal of L such that the quotient $L/\text{Leib}(L)$ becomes a Lie algebra. $\text{Leib}(L)$ is defined as the subalgebra generated by all elements of the form $[x, x]$, for any $x \in L$, and it is called the *Leibniz kernel* of L .

We define the *left* and the *right center* of a Leibniz algebra

$$Z_l(L) = \{x \in L \mid [x, L] = 0\}, \quad Z_r(L) = \{x \in L \mid [L, x] = 0\}.$$

The intersection of the left and right center is called the *center* of L and it is denoted by $Z(L)$. In general for a left Leibniz algebra L , the left center $Z_l(L)$ is a bilateral ideal, meanwhile the right center is not even a subalgebra. Furthermore, one can check that $\text{Leib}(L) \subseteq Z_l(L)$.

The definition of derivation for a Leibniz algebra is the same as in the case of Lie algebras.

Definition 1.2. A linear map $d: L \rightarrow L$ is a *derivation* of L if

$$d([x, y]) = [d(x), y] + [x, d(y)], \quad \forall x, y \in L.$$

An equivalent way to define a left Leibniz algebra L is to saying that the left adjoint maps $\text{ad}_x = [x, -]$ are derivations. Meanwhile the right adjoint maps $\text{Ad}_x = [-, x]$ are not derivations in general. The set $\text{Der}(L)$ of all derivations of L is a Lie algebra with the usual bracket $[d, d'] = d \circ d' - d' \circ d$ and the set $\text{Inn}(L)$ spanned by the left adjoint maps, which are called *inner derivations*, is an ideal of $\text{Der}(L)$. Moreover $\text{Aut}(L)$ is a Lie group and its Lie algebra is precisely $\text{Der}(L)$.

In [19] Loday introduced the notion of anti-derivation and biderivation for a Leibniz algebra.

Definition 1.3. A linear map $D: L \rightarrow L$ is an *anti-derivation* of L if

$$D([x, y]) = [x, D(y)] - [y, D(x)], \quad \forall x, y \in L.$$

The space $\text{ADer}(L)$ of anti-derivations of L has a $\text{Der}(L)$ -module structure with the extra multiplication $d \cdot D = d \circ D - D \circ d$, for any derivation d and for any anti-derivation D , and one can check that the right adjoint maps Ad_x are anti-derivations.

Definition 1.4. A *biderivation* of L is a pair $(d, D) \in \text{Der}(L) \times \text{ADer}(L)$ such that

$$[d(x) + D(x), y] = 0, \quad \forall x, y \in L.$$

The set $\text{Bider}(L)$ of all biderivations of L has a Leibniz algebra structure with the bracket

$$[(d, D), (d', D')] = ([d, d'], d \cdot D')$$

and it is defined a Leibniz algebra homomorphism

$$L \rightarrow \text{Bider}(L), x \mapsto (\text{ad}_x, \text{Ad}_x).$$

The pair $(\text{ad}_x, \text{Ad}_x)$ is called the *inner biderivation* associated with $x \in L$ and the set of all inner biderivations of L forms a Leibniz subalgebra of $\text{Bider}(L)$.

We recall the definitions of solvable and nilpotent Leibniz algebras.

Definition 1.5. Let L be a left Leibniz algebra over \mathbb{F} and let

$$L^0 = L, L^{k+1} = [L^k, L^k], \quad \forall k \geq 0$$

be the *derived series* of L . L is *n-step solvable* if $L^{n-1} \neq 0$ and $L^n = 0$.

Definition 1.6. Let L be a left Leibniz algebra over \mathbb{F} and let

$$L^{(0)} = L, L^{(k+1)} = [L, L^{(k)}], \quad \forall k \geq 0$$

be the *lower central series* of L . L is *n-step nilpotent* if $L^{(n-1)} \neq 0$ and $L^{(n)} = 0$.

When L is two-step nilpotent, it lies in different varieties of non-associative algebras, such as associative, alternative and Zinbiel algebras. In this case we refer at L as a *two-step nilpotent algebra* and we have the following.

Proposition 1.7. (i) *If L is a two-step nilpotent algebra, then $L^{(1)} = [L, L] \subseteq Z(L)$ and L is a symmetric Leibniz algebra.*

(ii) *If L is a left nilpotent Leibniz algebra with $\dim_{\mathbb{F}}[L, L] = 1$, then L is two-step nilpotent.*

In [16] the classification of nilpotent Leibniz algebras with one-dimensional derived subalgebra was established. The classification revealed that, up to isomorphism, there exist only three classes of indecomposable nilpotent Leibniz algebras of this type.

Definition 1.8 [16]. Let $f(x) \in \mathbb{F}[x]$ be a monic irreducible polynomial. Let $k \in \mathbb{N}$ and let $A = (a_{ij})_{i,j}$ be the companion matrix of $f(x)^k$. The *Heisenberg algebra* \mathfrak{h}_{2n+1}^A is the $(2n + 1)$ -dimensional Leibniz algebra with basis $\{e_1, \dots, e_n, f_1, \dots, f_n, z\}$ and the brackets are given by

$$[e_i, f_j] = (\delta_{ij} + a_{ij})z, \quad [f_j, e_i] = (-\delta_{ij} + a_{ij})z, \quad \forall i, j = 1, \dots, n.$$

When A is the zero matrix, then we obtain the $(2n + 1)$ -dimensional Heisenberg Lie algebra \mathfrak{h}_{2n+1} .

Definition 1.9 [16]. Let $n \in \mathbb{N}$. The *Kronecker algebra* \mathfrak{k}_n is the $(2n + 1)$ -dimensional Leibniz algebra with basis $\{e_1, \dots, e_n, f_1, \dots, f_n, z\}$ and the brackets are given by

$$\begin{aligned} [e_i, f_i] &= [f_i, e_i] = z, \quad \forall i = 1, \dots, n \\ [e_i, f_{i-1}] &= z, [f_{i-1}, e_i] = -z, \quad \forall i = 2, \dots, n. \end{aligned}$$

Definition 1.10 [16] Let $n \in \mathbb{N}$. The *Dieudonné* algebra \mathfrak{d}_n is the $(2n + 2)$ -dimensional Leibniz algebra with basis $\{e_1, \dots, e_{2n+1}, z\}$ and the brackets are given by

$$\begin{aligned} [e_1, e_{n+2}] &= z, \\ [e_i, e_{n+i}] &= [e_i, e_{n+i+1}] = z, \quad \forall i = 2, \dots, n, \\ [e_{n+1}, e_{2n+1}] &= z, \\ [e_i, e_{i-n}] &= z, \quad [e_i, e_{i-n-1}] = -z, \quad \forall i = n + 2, \dots, 2n + 1. \end{aligned}$$

We want to extend this classification by studying non-nilpotent Leibniz algebras with one-dimensional derived subalgebra.

2. Non-nilpotent Leibniz algebras with one-dimensional derived subalgebra

Let L be a non-nilpotent left Leibniz algebra over \mathbb{F} with $\dim_{\mathbb{F}} L = n$ and $\dim_{\mathbb{F}} [L, L] = 1$. We observe that such an algebra is two-step solvable since the derived subalgebra $[L, L]$ is abelian.

It is well known that a non-nilpotent Lie algebra with one-dimensional derived subalgebra is isomorphic to the direct sum of the two-dimensional non-abelian Lie algebra and an abelian algebra (see [12, Sect. 3]). Thus we are interested in the classification of non-Lie Leibniz algebras with these properties.

In [11, Theorem 2.6] the authors prove that a *complex* non-split non-nilpotent non-Lie Leibniz algebra with one-dimensional derived subalgebra is isomorphic to the two-dimensional algebra with basis $\{e_1, e_2\}$ and multiplication table $[e_2, e_1] = [e_2, e_2] = e_1$. Here we generalize this result when \mathbb{F} is a general field with $\text{char}(\mathbb{F}) \neq 2$.

Proposition 2.1. *Let L be a non-nilpotent left Leibniz algebra over \mathbb{F} with $\dim_{\mathbb{F}} [L, L] = 1$. Then L has a two-dimensional bilateral ideal S which is isomorphic to one of the following Leibniz algebras:*

- (i) $S_1 = \langle e_1, e_2 \rangle$ with $[e_2, e_1] = -[e_1, e_2] = e_1$;
- (ii) $S_2 = \langle e_1, e_2 \rangle$ with $[e_2, e_1] = [e_2, e_2] = e_1$.

Proof. Let $[L, L] = \mathbb{F}z$. Since L is not nilpotent, then

$$[L, [L, L]] \neq 0,$$

i.e. $z \notin Z_r(L)$. Since $[L, L]$ is an abelian algebra, there exists a vector $x \in L$, which is linearly independent than z , such that $[x, z] \neq 0$. Thus

$$[x, z] = \gamma z,$$

for some $\gamma \in \mathbb{F}^*$. The subspace $S = \langle x, z \rangle$ is an ideal of L and it is not nilpotent: in fact

$$0 \neq \gamma z = [x, z] \in [S, [S, S]].$$

Thus S is a non-nilpotent Leibniz algebra. Using the classification of two-dimensional Leibniz algebras given by C. Cuvier in [8], S is isomorphic either to S_1 or to S_2 . □

Remark 2.1. The algebras S_1 and S_2 are respectively the Leibniz algebras L_2 and L_4 of Sect. 3.1 in [1]. We observe that S_1 is a Lie algebra, meanwhile S_2 is a non-right left Leibniz algebra.

One can see L as an extension of the abelian algebra $L_0 = L/S \cong \mathbb{F}^{n-2}$ by S [18]

$$0 \longrightarrow S \xrightarrow{i} L \xrightleftharpoons[\sigma]{\pi} L_0 \longrightarrow 0. \tag{1}$$

It turns out that there exists an equivalence of Leibniz algebra extensions

$$\begin{array}{ccccccc} 0 & \longrightarrow & S & \xrightarrow{i_2} & L_0 \times_{\omega} S & \xrightleftharpoons[\iota_1]{\pi_1} & L_0 \longrightarrow 0 \\ & & \text{id}_S \downarrow & & \downarrow \theta & & \downarrow \text{id}_{L_0} \\ 0 & \longrightarrow & S & \xrightarrow{i} & L & \xrightleftharpoons[\sigma]{\pi} & L_0 \longrightarrow 0 \end{array}$$

where $L_0 \times_{\omega} S$ is the Leibniz algebra defined on the direct sum of vector spaces $L_0 \oplus S$ with the bilinear operation given by

$$[(x, a), (y, b)]_{(l,r,\omega)} = (0, [a, b] + l_x(b) + r_y(a) + \omega(x, y)),$$

where

$$\omega(x, y) = [\sigma(x), \sigma(y)]_L - \sigma([x, y]_{L_0}) = [\sigma(x), \sigma(y)]_L$$

is the Leibniz algebra 2-cocycle associated with (1) and

$$l_x(b) = [\sigma(x), i(b)]_L, \quad r_y(a) = [i(a), \sigma(y)]_L$$

define the action of L_0 on S ; i_1, i_2, π_1 are the canonical injections and projection. The Leibniz algebra isomorphism θ is defined by $\theta(x, a) = \sigma(x) + i(a)$, for every $(x, a) \in L_0 \oplus S$.

By [18, Proposition 4.2], the 2-cocycle $\omega: L_0 \times L_0 \rightarrow S$ and the linear maps $l, r: L_0 \rightarrow \text{gl}(S)$ must satisfy the following set of equations

- (L1) $l_x([a, b]) = [l_x(a), b] + [x, l_x(b)]$;
- (L2) $r_x([a, b]) = [a, r_x(b)] - [b, r_x(a)]$;
- (L3) $[l_x(a) + r_x(a), b] = 0$;
- (L4) $[l_x, l_y]_{\text{gl}(S)} - l_{[x,y]_{L_0}} = \text{ad}_{\omega(x,y)}$;
- (L5) $[l_x, r_y]_{\text{gl}(S)} - r_{[x,y]_{L_0}} = \text{Ad}_{\omega(x,y)}$;
- (L6) $r_y(r_x(a) + l_x(a)) = 0$;
- (L7) $l_x(\omega(y, z)) - l_y(\omega(x, z)) - r_z(\omega(x, y)) = \omega([x, y]_{L_0}, z) - \omega(x, [y, z]_{L_0}) + \omega(y, [x, z]_{L_0})$

for any $x, y \in L_0$ and for any $a, b \in S$. Notice that these equations were also studied in [6] in the case of Leibniz algebra *split extensions*.

Remark 2.2. The first three equations state that the pair (l_x, r_x) is a biderivation of the Leibniz algebra S , for any $x \in L_0$. Biderivations of low-dimensional Leibniz algebras were classified in [20] and it turns out that

- $\text{Bider}(S_1) = \{(d, -d) \mid d \in \text{Der}(S_1)\}$ and $\text{Der}(S_1) = \left\{ \begin{pmatrix} \alpha & \beta \\ 0 & 0 \end{pmatrix} \mid \alpha, \beta \in \mathbb{F} \right\}$;

$$\bullet \text{ Bider}(S_2) = \left\{ \left(\begin{pmatrix} \alpha & \alpha \\ 0 & 0 \end{pmatrix}, \begin{pmatrix} 0 & \beta \\ 0 & 0 \end{pmatrix} \right) \mid \alpha, \beta \in \mathbb{F} \right\}.$$

We study now in detail the non-abelian extension (1) in both cases that S is isomorphic either to S_1 or to S_2 .

2.1. S is a Lie algebra

When $S \cong S_1$, we have that $r_y = -l_y$, for any $y \in L_0$ and the bilinear operation of $L_0 \rtimes_{\omega} S_1$ becomes

$$[(x, a), (y, b)]_{(L, \omega)} = (0, [a, b] + l_x(b) - l_y(a) + \omega(x, y)).$$

The linear map l_x is represented by a 2×2 matrix

$$\begin{pmatrix} \alpha_x & \beta_x \\ 0 & 0 \end{pmatrix}$$

with $\alpha_x, \beta_x \in \mathbb{F}$. From equations (L4)-(L5) it turns out that

$$\omega(x, y) = (\alpha_x \beta_y - \alpha_y \beta_x) e_1, \quad \forall x, y \in L_0$$

and the 2-cocycle ω is skew-symmetric. Moreover, equations (L6)-(L7) are automatically satisfied and the resulting algebra $L_0 \rtimes_{\omega} S_1 \cong L$ is a Lie algebra. We conclude that L is isomorphic to the direct sum of S_1 and $L_0 \cong \mathbb{F}^{n-2}$.

2.2. S is not a Lie algebra

With the change of basis $e_2 \mapsto e_2 - e_1$, S_2 becomes the Leibniz algebra with basis $\{e_1, e_2\}$ and the only non-trivial bracket given by $[e_2, e_1] = e_1$. Now a biderivation of S_1 is represented by a pair of matrices

$$\left(\begin{pmatrix} \alpha & 0 \\ 0 & 0 \end{pmatrix}, \begin{pmatrix} 0 & \beta \\ 0 & 0 \end{pmatrix} \right)$$

with $\alpha, \beta \in \mathbb{F}$ and the pair $(l_x, r_x) \in \text{Bider}(S_2)$ is defined by $l_x(e_1) = \alpha_x e_1$ and $r_x(e_2) = \beta_x e_1$, for any $x \in L_0$.

Equation (L4) states that $[l_x, l_y]_{\text{gl}(S_2)} = [\omega(x, y), -]$, with

$$\begin{aligned} [l_x, l_y]_{\text{gl}(S_2)} &= l_x \circ l_y - l_y \circ l_x = \begin{pmatrix} \alpha_x & 0 \\ 0 & 0 \end{pmatrix} \begin{pmatrix} \alpha_y & 0 \\ 0 & 0 \end{pmatrix} - \begin{pmatrix} \alpha_y & 0 \\ 0 & 0 \end{pmatrix} \begin{pmatrix} \alpha_x & 0 \\ 0 & 0 \end{pmatrix} \\ &= \begin{pmatrix} \alpha_x \alpha_y & 0 \\ 0 & 0 \end{pmatrix} - \begin{pmatrix} \alpha_x \alpha_y & 0 \\ 0 & 0 \end{pmatrix} = \begin{pmatrix} 0 & 0 \\ 0 & 0 \end{pmatrix}, \end{aligned}$$

for any $x, y \in L_0$. Thus $\omega(x, y) \in Z_l(S_2) = \mathbb{F}e_1$.

From equation (L5) we have $[l_x, r_y]_{\text{gl}(S_2)} = [-, \omega(x, y)]_{S_2}$, with

$$[l_x, r_y]_{\text{gl}(S_2)} = l_x \circ r_y - r_y \circ l_x = \begin{pmatrix} 0 & \alpha_x \beta_y \\ 0 & 0 \end{pmatrix} - \begin{pmatrix} 0 & 0 \\ 0 & 0 \end{pmatrix} = \begin{pmatrix} 0 & \alpha_x \beta_y \\ 0 & 0 \end{pmatrix}.$$

Thus, for every $a = a_1 e_1 + a_2 e_2 \in S_2$ and for every $x, y \in L_0$, we have

$$[a, \omega(x, y)] = [l_x, r_y](a) = \alpha_x \beta_y a_2 e_1,$$

i.e. $\omega(x, y) = \alpha_x \beta_y e_1$. Finally, equations (L6) and (L7) are identically satisfied.

Summarizing we have

$$\begin{cases} l_x \equiv \begin{pmatrix} \alpha_x & 0 \\ 0 & 0 \end{pmatrix} \\ r_y \equiv \begin{pmatrix} 0 & \beta_y \\ 0 & 0 \end{pmatrix} \\ \omega(x, y) = \alpha_x \beta_y e_1 \end{cases}$$

for every $x, y \in L_0$ and the bilinear operation $[-, -]_{(l,r,\omega)}$ becomes

$$[(x, a), (y, b)]_{(l,r,\omega)} = (0, (a_2 b_1 + \alpha_x b_1 + \beta_y a_2 + \alpha_x \beta_y) e_1),$$

for any $x, y \in L_0$ and for any $a = a_1 e_1 + a_2 e_2, b = b_1 e_1 + b_2 e_2 \in S_2$.

If we fix a basis $\{f_3, \dots, f_n\}$ of L_0 and we denote by

$$\alpha_i = \alpha_{f_i}, \beta_i = \beta_{f_i}, \forall i = 3, \dots, n$$

then L is isomorphic to the Leibniz algebra with basis $\{e_1, e_2, f_3, \dots, f_n\}$ and non-zero brackets

$$\begin{aligned} [e_2, e_1] &= e_1 \\ [e_2, f_i] &= \beta_i e_1, \quad \forall i = 3, \dots, n \\ [f_i, e_1] &= \alpha_i e_1, \quad \forall i = 3, \dots, n \\ [f_i, f_j] &= \alpha_i \beta_j e_1, \quad \forall i, j = 3, \dots, n. \end{aligned}$$

With the change of basis $f_i \mapsto f'_i = \frac{f_i}{\beta_i} - e_1$, if $\beta_i \neq 0$, we obtain that

$$\begin{aligned} [e_2, f'_i] &= e_1 - [e_2, e_1] = 0, \\ [f'_i, e_1] &= \gamma_i e_1, \quad \text{where } \gamma_i = \frac{\alpha_i}{\beta_i}, \\ [f_i, f'_j] &= \alpha_i e_1 - [f_i, e_1] = 0, \\ [f'_i, f'_j] &= \gamma_i e_1 - \frac{1}{\beta_i} [f_i, e_1] = 0. \end{aligned}$$

If we denote again $f_i \equiv f'_i$ and $\alpha_i \equiv \gamma_i$ when $\beta_i \neq 0$, then L has basis $\{e_1, e_2, f_3, \dots, f_n\}$ and non-trivial brackets

$$[e_2, e_1] = e_1, [f_i, e_1] = \alpha_i e_1, \quad \forall i = 3, \dots, n.$$

Finally, when $\alpha_i \neq 0$, we can operate the change of basis

$$f_i \mapsto \frac{f_i}{\alpha_i} - e_2.$$

One can check that the only non-trivial bracket now is $[e_2, e_1] = e_1$ and L is isomorphic to the direct sum of S_2 and the abelian algebra $L_0 \cong \mathbb{F}^{n-2}$. This allows us to conclude with the following.

Theorem 2.2. *Let \mathbb{F} be a field with $\text{char}(\mathbb{F}) \neq 2$. Let L be a non-nilpotent non-Lie left Leibniz algebra over \mathbb{F} with $\dim_{\mathbb{F}} L = n$ and $\dim_{\mathbb{F}} [L, L] = 1$. Then L is isomorphic to the direct sum of the two-dimensional non-nilpotent non-Lie Leibniz algebra S_2 and an abelian algebra of dimension $n - 2$. We denote this algebra by L_n . \square*

If we suppose that L is a *non-split* algebra, i.e. L cannot be written as the direct sum of two proper ideals, then we obtain the following result, that is a generalization of [11, Theorem 2.6] and which is valid over a general field \mathbb{F} with $\text{char}(\mathbb{F}) \neq 2$.

Corollary 2.3. *Let L be a non-split non-nilpotent non-Lie left Leibniz algebra over \mathbb{F} with $\dim_{\mathbb{F}} L = n$ and $\dim_{\mathbb{F}}[L, L] = 1$. Then $n = 2$ and $L \cong S_2$. \square*

Now we study in detail the algebra $L_n = S_2 \oplus \mathbb{F}^{n-2}$ by describing the Lie algebra of derivations, its Lie group of automorphisms and the Leibniz algebra of biderivations. Moreover, when $\mathbb{F} = \mathbb{R}$, we solve the *coqueigruue problem* (see [7] and [15]) for L_n by integrating it into a Lie rack.

2.3. Derivations, Automorphisms and Biderivations of L_n

Let $n \geq 2$ and let $L_n = S_2 \oplus \mathbb{F}^{n-2}$. We fix the basis $\mathcal{B}_n = \{e_1, e_2, f_3, \dots, f_n\}$ of L_n and we recall that the only non-trivial commutator is $[e_2, e_1] = e_1$. A straightforward application of the algorithm proposed in [20] for finding derivations and anti-derivations of a Leibniz algebra as pair of matrices with respect to a fixed basis produces the following.

Theorem 2.4. (i) *A derivation of L_n is represented, with respect to the basis \mathcal{B}_n , by a matrix*

$$\left(\begin{array}{cc|cccc} \alpha & 0 & 0 & 0 & \dots & 0 \\ 0 & 0 & 0 & 0 & \dots & 0 \\ \hline 0 & a_3 & & & & \\ 0 & a_4 & & & & \\ \vdots & \vdots & & & & \\ 0 & a_n & & & & \end{array} \right) \begin{array}{c} \\ \\ A \\ \\ \end{array}$$

where $A \in M_{n-2}(\mathbb{F})$.

(ii) *The group of automorphisms $\text{Aut}(L_n)$ is the Lie subgroup of $\text{GL}_n(\mathbb{F})$ of matrices of the form*

$$\left(\begin{array}{cc|cccc} \beta & 0 & 0 & 0 & \dots & 0 \\ 0 & 1 & 0 & 0 & \dots & 0 \\ \hline 0 & b_3 & & & & \\ 0 & b_4 & & & & \\ \vdots & \vdots & & & & \\ 0 & b_n & & & & \end{array} \right) \begin{array}{c} \\ \\ B \\ \\ \end{array}$$

where $\beta \neq 0$ and $B \in \text{GL}_{n-2}(\mathbb{F})$.

(iii) *The Leibniz algebra of biderivations of L_n consists of the pairs (d, D) of linear endomorphisms of L_n which are represented by the pair of*

matrices

$$\left(\left(\begin{array}{cc|cccc} \alpha & 0 & 0 & 0 & \cdots & 0 \\ 0 & 0 & 0 & 0 & \cdots & 0 \\ \hline 0 & a_3 & & & & \\ 0 & a_4 & & & & \\ \vdots & \vdots & & & & \\ 0 & a_n & & & & \end{array} \right) A, \left(\begin{array}{cc|cccc} 0 & \alpha' & 0 & 0 & \cdots & 0 \\ 0 & 0 & 0 & 0 & \cdots & 0 \\ \hline 0 & a'_3 & & & & \\ 0 & a'_4 & & & & \\ \vdots & \vdots & & & & \\ 0 & a'_n & & & & \end{array} \right) A' \right)$$

where $A, A' \in M_{n-2}(\mathbb{F})$. □

3. The Integration of the Leibniz Algebra L_n

The *coquecigrue problem* is the problem formulated by Loday in [19] of finding a generalization of Lie third theorem to Leibniz algebras. Given a real Leibniz algebra L , one wants to find a manifold endowed with a smooth map, which plays the role of the adjoint map for Lie groups, such that the tangent space at a distinguished element, endowed with the differential of this map, gives a Leibniz algebra isomorphic to L . Moreover, when L is a Lie algebra, we want to obtain the simply connected Lie group associated with L . From now on, we assume that the underlying field of any algebra is $\mathbb{F} = \mathbb{R}$.

In [15] M. K. Kinyon shows that it is possible to define an algebraic structure, called *rack*, whose operation, differentiated twice, defines on its tangent space at the unit element a Leibniz algebra structure.

Definition 3.1. A *rack* is a set X with a binary operation $\triangleright: X \times X \rightarrow X$ which is left autodistributive

$$x \triangleright (y \triangleright z) = (x \triangleright y) \triangleright (x \triangleright z), \quad \forall x, y, z \in X$$

and such that the left multiplications $x \triangleright -$ are bijections.

A rack is *pointed* if there exists an element $1 \in X$ such that $1 \triangleright x = x$ and $x \triangleright 1 = 1$, for any $x \in X$.

A rack is a *quandle* if the binary operation \triangleright is idempotent.

The first example of a rack is any group G endowed with its conjugation

$$x \triangleright y = xyx^{-1}, \quad \forall x, y \in G.$$

We denote this rack by $\text{Conj}(G)$ and we observe that it is a quandle.

Definition 3.2. A pointed rack $(X, \triangleright, 1)$ is said to be a *Lie rack* if X is a smooth manifold, \triangleright is a smooth map and the left multiplications are diffeomorphisms.

M. K. Kinyon proved that the tangent space $T_1 X$ at the unit element 1 of a Lie rack X , endowed with the bilinear operation

$$[x, y] = \left. \frac{\partial^2}{\partial s \partial t} \right|_{s,t=0} \gamma_1(s) \triangleright \gamma_2(t)$$

where $\gamma_1, \gamma_2: [0, 1] \rightarrow X$ are smooth paths such that $\gamma_1(0) = \gamma_2(0) = 1$, $\gamma_1'(0) = x$ and $\gamma_2'(0) = y$, is a Leibniz algebra.

He also solved the coquecigrue problem for the class of *split Leibniz algebras*. Here a Leibniz algebra is said to be *split* if there exists an ideal

$$\text{Leib}(L) \subseteq I \subseteq Z_l(L)$$

and a Lie subalgebra M of L such that $L \cong (M \oplus I, \{-, -\})$, where the bilinear operation $\{-, -\}$ is defined by

$$\{(x, a), (y, b)\} = ([x, y], \rho_x(b))$$

and $\rho: M \times I \rightarrow I$ is the action on the M -module I . L is said to be the *demisemidirect product* of M and I . More precisely, we have the following.

Theorem 3.3 [15]. *Let L be a split Leibniz algebra. Then a Lie rack integrating L is $X = (H \oplus I, \triangleright)$, where H is the simply connected Lie group integrating M and the binary operation is defined by*

$$(g, a) \triangleright (h, b) = (ghg^{-1}, \phi_g(b)),$$

where ϕ is the exponentiation of the Lie algebra action ρ .

Some years later S. Covez generalized M. K. Kinyon’s results proving that every real Leibniz algebra admits an integration into a *Lie local rack* (see [7]). More recently it was showed in [16] that the integration proposed by S. Covez is global for any nilpotent Leibniz algebra. Moreover, when a Leibniz algebra L is integrated into a Lie quandle X , it turns out that L is a Lie algebra and $X = \text{Conj}(G)$, where G is the simply connected Lie group integrating L .

Our aim here is to solve the coquecigrue problem for the non-nilpotent Leibniz algebra $L_n = S_2 \oplus \mathbb{F}^{n-2}$. One can check that S_2 is a split Leibniz algebra, in the sense of M. K. Kinyon, with $I = Z_l(S_2) \cong \mathbb{R}$ and $M \cong \mathbb{R}$. Thus $L \cong (\mathbb{R}^2, \{-, -\})$ with the bilinear operation defined by

$$\{(x_1, x_2), (y_1, y_2)\} = (0, \rho_{x_1}(y_2))$$

and $\rho_{x_1}(y_2) = x_1 y_2$, for any $x_1, y_2 \in \mathbb{R}$. It turns out that a Lie rack integrating S_2 is $(\mathbb{R}^2, \triangleright)$, where

$$(x_1, x_2) \triangleright (y_1, y_2) = (y_1, y_2 + e^{x_1} y_2).$$

and the unit element is $(0, 0)$. Finally, one can check that the binary operation

$$(x_1, x_2, x_3, \dots, x_n) \triangleright (y_1, y_2, y_3, \dots, y_n) = (y_1, y_2 + e^{x_1} y_2, y_3, \dots, y_n)$$

defines on \mathbb{R}^n a Lie rack structure with unit element $1 = (0, \dots, 0)$, such that $(T_1 \mathbb{R}^n, \triangleright)$ is a Leibniz algebra isomorphic to L_n . This result, combined with the ones of [16, Section 4], completes the classification of Lie racks whose tangent space at the unit element gives a Leibniz algebra with one-dimensional derived subalgebra.

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Data Availability No datasets were generated or analysed during the current study.

Declarations

Conflict of interest Not applicable. There is no Conflict of interest.

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