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Numerical Simulation of Transcatheter Mitral Valve Replacement the Dynamic Implication of LVOT Obstruction in the Valve-In-Ring Case --Manuscript Draft--

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Corresponding Author:	Salvatore Pasta, Ph.D. University of Palermo Palermo, ITALY
First Author:	Salvatore Pasta, Ph.D.
Order of Authors:	Salvatore Pasta, Ph.D.
	Chiara Catalano
	Stefano Cannata
	Julius M. Guccione
	Caterina Gandolfo
Abstract:	<p>Transcatheter mitral valve replacement (TMVR) has been used for “off-label” treatment when annuloplasty band ring for mitral repair fails. However, the complex anatomy and function of the mitral valve may lead to fatal complications as a result of the left ventricular outflow tract (LVOT) obstruction in TMVR. We report the structural and hemodynamic response of LVOT obstruction resulting from TMVR with the Edwards SAPIEN 3 Ultra (S3) device. We modified the original Living Heart Human Model (LHHM) to account for a failed mitral valve with an annuloplasty band ring and simulated the cardiac beating condition in the setting of S3 device implantation. Findings demonstrated a high dynamic behavior of the newly formed LVOT (neo-LVOT) as confined by the displaced mitral valve and the interventricular septum. During the cardiac beat, the neo-LVOT area oscillated from a maximum of 472.1 mm² at early systole to the minimum of 183 mm² at end-systole. The profile of both anchoring force and contact pressure revealed that the band ring serves as the anchoring zone while mitral valve is primarily displaced by the deployed device. At early systole, computational flow dynamics highlighted hemodynamic disturbances associated with the LVOT obstruction, with a skewed flow towards the septum and a pressured drop of 4.5 mmHg between the left ventricular apex and the neo-LVOT region. This study can lead to a more accurate assessment of the risk induced by the LVOT obstruction when stratifying patient anatomic suitability for TMVR.</p>



Dear Editor,

The present paper shows a computational study to assess the feasibility to transcatheter mitral valve replacement as considered as off-label application of commercial devices.

This study adopts a realistic cardiac simulator as the living heart project and is supported by THV manufacturer.

All authors were fully involved in the study and preparation of the manuscript which contribution originality can be confirmed by members of University Collage San Francisco and the University of Palermo . All authors approve the submission.

The manuscript, or part of it, has neither been published (except in form of abstract or thesis) nor is currently under consideration for publication by any other journal.

we kindly suggests the name of few reviewers as expert on the field

Best Regards,

A handwritten signature in black ink, appearing to be 'S. R. Z.'.

Reviewer #2

We thank the reviewer for his or her valuable comments to our paper. The comments were constructive and have led to a remarkable improvement of the manuscript. We have attempted to maximize the utility of these comments and hope that the revised version of the paper addresses all the comments raised. All comments are highlighted in yellow with respect to previous version.

General comment

In this revision, the authors definitely improved the manuscript by including more details in the text. However, one of my comments, that the paper shows only one model of a specific case with no comparative study (comment 2), was not really addressed. I totally agree that this model cannot be validated, but parametric studies are feasible, and they can at least predict some clinically useful trends. I gave the authors several ideas on how to make the results of this model more meaningful, and at least one of those ideas is very straight-forward to implement (in comment 3, changing material properties of the device does not require any modification to the geometry/mesh). I understand the authors' preferences to investigate such changes in the future, but I still think that their decision makes this study much less interesting and useful than it could have been. I strongly encourage the authors to expand the scope of their current paper by adding such a simple model. It will vastly improve the paper and make it suitable for publication.

Reply: we thank the reviewer for encouraging us in performing additional simulations and believes that this has strongly improved the quality of the manuscript, if the reviewer agrees.

Specifically, we added the results of n.3 additional simulation on the resulting structural performance of the S3 Ultra device. These new simulations are:

1. A first model with a stiff band ring as opposed to the nitinol band ring as kindly suggested by the reviewer
2. A second model with an increased amount of balloon fluid-filling volume to simulate the device overexpansion that may be performed in the clinical setting
3. A third model with a translated device to simulate a change in the implantation depth.

In brief, we observed that the stiff band ring reduced the neo-LVOT area at diastole and systole but the highest reduction was observed with balloon overexpansion. In a different way, the high implantation depth determined high neo-LVOT area but slightly low contact pressure in the mitral valve leaflet. The results of such simulations were added, please see the new Table 2 and Figure 8. Several sentences were added in each section to describe these simulations and are here re-written:

Introduction: the following sentence was added in the last paragraph

“A comparative study was carried out by changing the material properties of the band ring, simulating the balloon overexpansion and altering the implantation depth.”

Section 2.1:

“An additional model was developed by changing the material behavior of the band ring to simulate the TMVR in a stiff band ring. Specifically, the band ring was simulated as a rigid material while other material descriptors of LHHM and S3 Ultra system were not changed. ”

Section 2.3:

“To further investigate the interaction of the S3 Ultra with the human host, the case of a high implantation depth in the left atrium was also investigated. This was obtained by translating the device and implantation system of 5 mm in the left atrium.”

and

“Balloon overexpansion may occur in clinical setting to increase the device adherence to the band ring. In this way, an additional simulation was developed increasing the fluid volume of 1 ml with respect to the reference one.”

Results

“The comparative study using the stiff band ring, high implantation depth and balloon overexpansion highlighted different TMVR simulation outcomes (Fig. 7). Table 2 summarizes the changes of neo-LVOT area and contact pressure with respect to the reference LHHM model. “

Table 2: Comparison of neo-LVOT area values among different parametric models

	Neo-LVOT area (mm ²)		Contact Pressure (MPa)	
	Max	Min	Ring	Mitral Valve
Reference Model	472.1	183.0	28.2	26.7
Stiff Band Ring	455.8	165.7	41.6	32.5
Balloon Overexpansion	434.6	151.4	32.8	29.4
High Implantation Depth	495.6	201.2	30.5	22.3

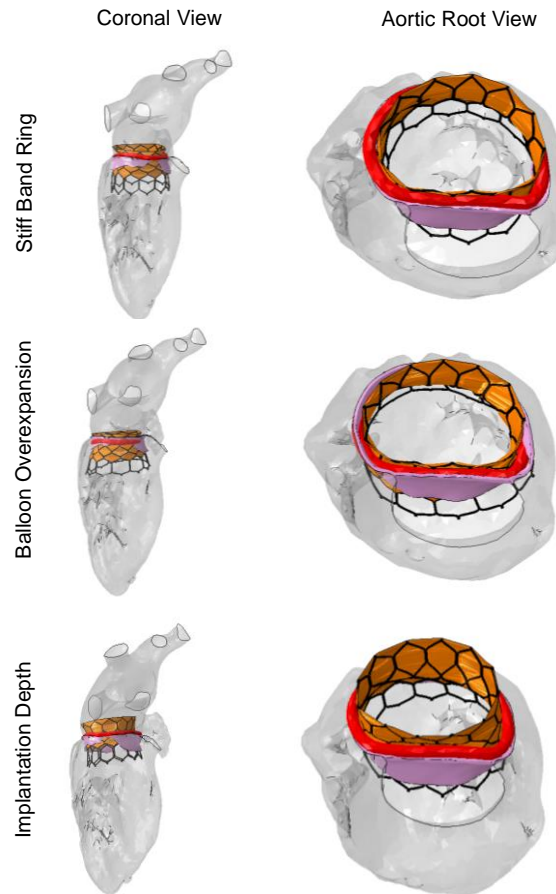


Fig 8 Changes in the TMVR simulations in case of a stiff band, balloon overexpansion and high implantation depth.

Discussion:

“The comparative study demonstrated that role of band ring material properties, device overexpansion and suboptimal implantation depth on the resulting device performance. Low magnitude of neo-LVOT area at systole and diastole were found for the stiff band ring and balloon overexpansion, with lowest area measurements when the fluid-filling volume was increased. In a different way, a shift of the implantation depth towards the left atrium led to larger neo-LVOT area but lower contact pressure on the mitral valve than that shown by the reference model following manufacturer guidelines”

Conclusion:

Future studies in patient-specific geometries including different mitral valve morphologies different sizes of mitral valve leaflets and stiff versus flexible band rings will help to achieve better translational clinical value by enhancing the pre-TMVR planning in borderline patient anatomy.

**Numerical Simulation of Transcatheter Mitral Valve Replacement:
the Dynamic Implication of LVOT Obstruction in the Valve-In-Ring Case**

Salvatore Pasta^{1,2}, Chiara Catalano¹, Stefano Cannata³, Julius M. Guccione⁴, Caterina Gandolfo³

¹Department of Engineering, Viale delle Scienze, Università degli Studi di Palermo, Palermo, Italy.

² Department of Bioengineering Research, IRCCS-ISMETT, Palermo, Italy.

³ Department for the Treatment and Study of Cardiothoracic Diseases and Cardiothoracic Transplantation, IRCCS-ISMETT, Palermo, Italy.

⁴Department of Surgery, University of California San Francisco, San Francisco, CA, United States.

*** Correspondence:**

Salvatore Pasta, PhD
Professor of Industrial Bioengineering,
Department of Engineering
University of Palermo
Phone: +39 091 3815681
FAX: +39 091 3815682
e-mail: salvatore.pasta@unipa.it

23 **Abstract**

24 Transcatheter mitral valve replacement (TMVR) has been used for “off-label” treatment when
25 annuloplasty band ring for mitral repair fails. However, the complex anatomy and function of the
26 mitral valve may lead to fatal complications as a result of the left ventricular outflow tract (LVOT)
27 obstruction in TMVR. We report the structural and hemodynamic response of LVOT obstruction
28 resulting from TMVR with the Edwards SAPIEN 3 Ultra (S3) device. We modified the original Living
29 Heart Human Model (LHHM) to account for a failed mitral valve with an annuloplasty band ring and
30 simulated the cardiac beating condition in the setting of S3 device implantation. Findings
31 demonstrated a high dynamic behavior of the newly formed LVOT (neo-LVOT) as confined by the
32 displaced mitral valve and the interventricular septum. During the cardiac beat, the neo-LVOT area
33 oscillated from a maximum of 472.1 mm² at early systole to the minimum of 183 mm² at end-
34 systole. The profile of both anchoring force and contact pressure revealed that the band ring
35 serves as the anchoring zone while mitral valve is primally displaced by the deployed device. At
36 early systole, computational flow dynamics highlighted hemodynamic disturbances associated with
37 the LVOT obstruction, with a skewed flow towards the septum and a pressured drop of 4.5 mmHg
38 between the left ventricular apex and the neo-LVOT region. This study can lead to a more accurate
39 assessment of the risk induced by the LVOT obstruction when stratifying patient anatomic
40 suitability for TMVR.

41

42 **Keywords:** Transcatheter Mitral Valve Replacement, Living Heart Human Model, Finite Element
43 (FE) Analysis, Computational Fluid Dynamic (CFD)

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47 **Statements and Declarations**

48 **Funding:** This study was funded by the grant “Sim4SAPIEN” from the Edwards Lifesciences SA
49 (THV-I20-532).

50

51 **1. Introduction**

52 Mitral valve regurgitation is the most common valvular disease worldwide with a prevalence of 10%
53 in the general population (Wu et al., 2018). A significant number of patients with mitral regurgitation
54 are also at high risk for surgical repair as advanced age and comorbidities can lead to mortality
55 ranging from 7.4% to 15.1% (Castillo-Sang et al., 2015). In the last few years, transcatheter mitral
56 valve replacement (TMVR) has evolved considerably towards becoming an effective therapy in the
57 setting of degenerated bioprostheses, failed annuloplasty band rings and mitral annular
58 calcifications (Bapat et al., 2018; Muller et al., 2017). The positive outcome of TMVR procedure
59 reported in recent studies (Muller et al., 2021; Whisenant et al., 2020) is partly due to clinician
60 experience and confidence on performing the well-established transcatheter aortic valve
61 replacement (TAVR). However, the current generation of transcatheter heart valves (THV) are not
62 specifically designed for mitral valve repair and are therefore used as “off-label” applications in
63 mitral implantations. As the THV is implanted in the diseased mitral valve, the native left ventricular
64 out flow tract (LVOT) is extended into the left ventricle by generating a modified anatomic region
65 (namely, the neo-LVOT). This region is confined to the permanently displaced THV and the native
66 anterior mitral valve leaflet together with the interventricular septum. LVOT obstruction is the major
67 complication after TMVR, with incidence rates ranging between 8.2% and 11.2%, and can
68 ultimately lead to hemodynamic impairment and death (Babaliaros et al., 2021). Simulating TMVR
69 is more challenging than simulating TAVR because the highly complex nature of mitral valve and
70 its dynamic behavior mean that simulation must be performed on a beating heart model. There is
71 therefore a limited literature on the computational modeling of TMVR. Computational fluid dynamic
72 was adopted to quantify the stenotic sub-aortic flow alterations and the pressure drop induced by
73 the prolonged THV protrusion as modeled by a rigid wall in the LVOT (Kohli et al., 2018). Similarly,
74 a parametric analysis of the impact of THV extension in the LVOT has revealed an increase in the
75 left ventricular afterload as the obstruction length is pronounced (De Vecchi et al., 2018).
76 Recently, computational flow analysis was used to evaluate the effectiveness of mitral valve
77 anterior leaflet laceration (ie, the LAMPOON mini-invasive surgery) for redistributing the flow
78 patterns and ultimately mitigating the impact of the LVOT obstruction. These studies do not

79 perform structural simulations and thus have not investigated the interaction of the device with the
80 human host. In this context, the Living Heart Human Model (LHHM) developed by Dassault
81 Systemes is an extremely realistic and accurate multiphysics model of an adult beating heart, and
82 is therefore the ideal cardiac tool to investigate the biomechanics of TMVR and the role of LVOT
83 obstruction on patient outcomes. The simulation of the cardiac beat with the LHHM can reveal
84 important insights in the THV post-deployment performance and ultimately offer a methodology to
85 facilitate the optimal design of THVs for mitral valve repair and enhance pre-operative planning for
86 improving the management of patient undergoing TMVR.

87

88 This study sought to assess the dynamic role of LVOT obstruction resulting from the TMVR
89 simulation using the LHHM. For this, we adapted the LHHM to mimic the case of a patient who
90 underwent transcatheter mitral valve-in-ring implantation. This was accomplished by changing the
91 left ventricular material response to model the failed heart condition and then simulating the
92 presence of the annuloplasty band ring. Next, the balloon-expandable Edwards SAPIEN 3 Ultra
93 (S3) device (Edwards Lifesciences, USA) was virtually deployed in the LHHM to assess the
94 anchoring device performance and the neo-LVOT area over the cardiac beat. A comparative study
95 was carried out by changing the material properties of the band ring, simulating the balloon
96 overexpansion and altering the implantation depth. Finally, a computational fluid dynamic analysis
97 was carried out using the end-systolic LHHM deformed configuration to evaluate the sub-aortic
98 flow and pressure drop in correspondence of LVOT obstruction.

99

100 **2. Methods**

101 The simulation study of TMVR in the failed annuloplasty band ring consisted of the following steps:

- 102 1. Adapting the original LHHM to account for a failed mitral valve by inhibiting the active
103 contraction of the myocardial wall near the posterior papillary muscle.

2. Modeling the suturing of the annuloplasty band ring into the mitral annulus using wire connections and contact conditions.
3. Simulating the deployment of the S3 Ultra device by virtually inflating the balloon and then modeling the heartbeat of repaired mitral valve apparatus.
4. Computational flow analysis of the left heart hemodynamics to quantify the sub-aortic flow and pressure gradient near the LVOT obstruction.

2.1 Band ring and THV models

The band ring was derived from a prototype previously investigated by our group (Baillargeon et al., 2015) and is characterized by a nitinol annular material with cross-sectional circular geometry ($d=3$ mm). The original prototype was downscaled to accommodate the MV annulus of LHHM geometry, and then meshed with unstructured tetrahedral elements. For material properties, the constitutive law reported by Morganti and collaborators (Morganti et al., 2016) was used. An additional model was developed by changing the material behavior of the band ring to simulate the TMVR in a stiff band ring. Specifically, the band ring was simulated as a rigid material while other material descriptors of LHHM and S3 Ultra system were not changed.

In accordance with mitral annulus geometry of LHHM, the S3 Ultra with diameter of 23 mm was used in this study. Specifically, the S3 Ultra stent frame was modeled using micro-CT images and then meshed with nearly 60,000 structured hexahedral solid elements with reduced integration and hourglass control (Pasta et al., 2020a; Pasta et al., 2020b). To avoid mesh distortion and ensure solution convergence, the THV skirt was modeled after the crimping phase by closing the device frame cells at mid-thickness of the S3 frame geometry (Fig. 1B). Then, triangular shell elements with a thickness of 0.1 mm were used to model the sealing skirt during the S3 deployment. The constitutive model of the S3 metallic frame was a bilinear elasto-plastic material ($\rho=8000$ kg/m³, $E=233$ GPa, $\sigma_Y=414$ MPa, $\sigma_{ult}=930$ MPa, $\epsilon_p=0.45$ and $\nu=0.35$) and the skirt had a perfect elasto-plastic model to account for the polyethylene terephthalate material ($\rho=8000$ kg/m³, $E=55$ MPa, $\sigma_Y=$ $\sigma_{ult}=6.6$ MPa, $\epsilon_p=0.6$ and $\nu=0.45$) (Pasta et al., 2020a). For the THV, the valve leaflet geometry

131 assumed a parametric model with linear-elastic material properties ($\rho=1060 \text{ kg/m}^3$, $E=8 \text{ MPa}$ and
132 $\nu=0.45$) as reported by Auricchio et al (Auricchio et al., 2014). Reverse engineering was used to
133 acquire the balloon shape profile using a laser scanner (Hexagon Manufacturing Intelligence,
134 Cobham, Great Britain), and then to revolve the generative curve around the balloon axis in the
135 commercial software Rhinoceros, (Robert McNeel & Associates, USA). The balloon was
136 discretized with membrane elements (M3D4) with thickness of 0.1mm and linear-elastic material
137 properties ($\rho=1060 \text{ kg/m}^3$, $E=600 \text{ MPa}$ and $\nu=0.3$) (Bailey et al., 2016).

138

139 **2.2 LHHM description**

140 The LHHM developed by SIMULIA Living Heart Project (Fig. 1) is an advanced cardiac tool in
141 which the geometry is a realistic and accurate representation of an adult male anatomy
142 (Baillargeon et al., 2014). The LHHM includes all ventricular and atrial chambers, heart valves and
143 major vessels (i.e., the aorta, pulmonary artery and vena cava) and the biomechanical response is
144 governed by an electrical potential activating the contraction of myocardial wall. The coupling with
145 a 1-D lumped parameter model allows one to consider the interaction between the circulating blood
146 and the deforming myocardium and thus obtain the pressure-volume loop. Anatomical parts are
147 meshed with tetrahedral elements and linear truss elements (only for chordae tendineae) for a total
148 of 443,564 mechanical degrees of freedom.

149 In the LHHM, the electrical potential is first computed for the whole heart and then transferred to
150 the mechanical model using both active contraction and passive material properties to simulate the
151 cardiac beat. The active stress in the cardiac fiber direction is generated by a time-varying
152 elastance model where the active force is a function of the current sarcomere length, peak
153 intracellular calcium concentration, and fiber activation time. The passive behavior of heart
154 chambers is modelled with the anisotropic hyperelastic constitutive model proposed by Ogden and
155 Holzapfel (Holzapfel and Ogden, 2009), which has been widely used in several cardiac simulation
156 studies (Guccione et al., 2001; Walker et al., 2005).

157 Since the current study was focused on the mitral function and the TMVR feasibility, additional
 158 attention was given to the mechanical properties of mitral valve leaflets and chordae. Specifically,
 159 the mitral valve was modeled using the following strain energy function with strain invariants I_1 , I_4 ,
 160 I_{4s} , and I_{8fs} :

$$\psi_{dev} = \frac{a}{2b} \exp[b(I_1 - 3)] + \sum_{i=f,s} \frac{a_i}{2b_i} \{ \exp[b_i((I_{4i} - 1)^2)] - 1 \} + \frac{a_{fs}}{2b_{fs}} [\exp(b_{fs}I_{8fs}^2) - 1] \quad \text{Eq1}$$

161 The eight material parameters a , b , a_f , b_f , a_s , b_s , a_{fs} , b_{fs} , were fit using the biaxial mechanical
 162 characterization on the porcine aorta proposed by MayNewman and Yin (May-Newman and Yin,
 163 1995). The chordae constitutive behavior chosen was hyperelastic with a Marlow form of strain
 164 energy potential using uniaxial test data from Kunzelmann and Cochran (Kunzelman et al., 1993).
 165 The chordae are coupled to the ventricular papillary muscles using tie constraints. In the LHHM,
 166 the mitral valve failure was obtained modifying the left ventricular material properties in the
 167 myocardial wall region near the posterior papillary muscle (see inset of Fig. 1A). Specifically, active
 168 contraction was deactivated in an element set near the papillary muscle during the cardiac beat to
 169 simulate a failed heart condition. The extension and position of the failed myocardial wall region
 170 was decided according to the pathological remodeling of the heart infarction as characterized by an
 171 ischemic area near the papillary muscle of the anterior left ventricular wall. The passive heart
 172 behavior constitutive law has the form shown by Eq.1. Thus, the dysfunction of the failed
 173 myocardial region was modeled by increasing the isotropic response of 30% as done previously
 174 (Guccione et al., 2003). Similarly, the end-systolic dysfunction was modeled by reducing the
 175 parameter representing the peak intracellular calcium concentration (C_{a0}) of 20%. Table 1
 176 summarize the material parameters of the left heart, ischemic region and mitral valve. In the
 177 LHHM, the heart rate is fixed to 60 bpm resulting in a systolic phase of 0.5 s and diastolic phase of
 178 0.5 s. As boundary conditions, the LHHM is constrained in space by fixed node sets at cut planes
 179 of the ascending aorta, pulmonary trunk, and superior vena cava.

180

181 2.3 TMVR modeling

182 The LHHM adopts the ABAQUS/Explicit solver for simulating the cardiac beat. The simulation
183 begins with filling the LHHM with blood to a state consistent with being at 70% through the diastolic
184 phase of the cardiac cycle (time of 0.5 s). Then, the implantation of the band ring is obtained by
185 generating frictionless contact conditions between the band ring and the MV annulus. The
186 presence of sutures is considered using several wires connecting the band ring periphery to the
187 MV annulus in the radial direction. Then, the S3 Ultra was placed in the LHHM and crimped by a
188 rigid dodecahedral surface gradually moved along the radial direction from the initial device
189 diameter to the final diameter of 4.5 mm. Frictionless contact conditions were set between the
190 crimping surface and the S3 Ultra while tie contact conditions were used to fix the skirt surfaces to
191 the crimped THV device. Similarly, the balloon is deflated by radial displacement of a cylindrical
192 crimper and constraining distal ends in all directions (Fig. 1B) (Pasta et al., 2020b). The crimped
193 S3 Ultra and folded balloon was placed in the LHHM following manufacturer recommendations with
194 1/3 of S3 Ultra frame in the left atrium and the remaining part on the left ventricular chamber. To
195 further investigate the interaction of the S3 Ultra with the human host, the case of a high
196 implantation depth in the left atrium was also investigated. This was obtained by translating the
197 device and implantation system of 5 mm in the left atrium. Frictionless contact conditions were
198 used to replicate the interaction of S3 Ultra with the balloon surface.

199 In a third step, the S3 Ultra was expanded using the fluid-cavity-based approach to ensure a
200 realistic volume-controlled inflation upon the nominal fluid volume of 17 ml. Balloon overexpansion
201 may occur in clinical setting to increase the device adherence to the band ring. In this way, an
202 additional simulation was developed increasing the fluid volume of 1 ml with respect to the
203 reference one. The device expansion was carried out with the mitral valve at fully opened position
204 to warrant the relative position of S3 Ultra system into the mitral valve annulus. The bioprosthetic
205 valve leaflets were mapped on the device frame after the deployment process, and then the heart
206 completed three cardiac cycles to reach a steady-state solution. Contacts among components
207 were defined according to the general contact algorithm implemented in the LHHM.

208

209 **2.3 Computational flow analysis**

210 After TMVR simulation, deformed geometries of the left heart and deployed THV were exported at
211 the end-systolic cardiac phase for computational fluid dynamic analysis. The inner heart volume
212 was meshed with 3,715,183 tetrahedral elements using the ICEM CFD (v21.0, ANSYS Inc.,
213 Canonsburg, PA). Laminar flow condition and non-Newtonian viscosity described by the Carreau
214 model were assumed (Pasta et al., 2017). Computational flow analysis was carried out using an
215 implicit algorithm in FLUENT (v21, ANSYS Inc., Canonsburg, PA, USA). For boundary conditions
216 (see Fig. 2), flow velocity inlets were set at each pulmonary vein and then split, assuming
217 proportionality of each pulmonary vein cross-sectional area and mass balance conservation. For
218 outflow, a pressure outlet profile was imposed at the aortic root of the LHHM using published data
219 (Pasta et al., 2020b). Three cardiac beats were simulated to reduce instabilities related to the
220 transient flow, and the last cycle was used for flow analysis.

221

222 **3. Results**

223 Figure 3 shows several steps of S3 Ultra deployment in the LHHM as the expandable balloon is
224 inflated by the fluid-filling volume to guide the device anchoring. Both the band ring and mitral valve
225 represent the key anchoring zones with the device being in contact first with the band ring (Fig.
226 3D). The S3 Ultra and balloon surface displaced the native mitral valve towards the myocardium,
227 with the anterior mitral valve leaflet moving towards the native LVOT anatomy (Fig. 3E). It is also
228 noted that the opening and closing of the mitral valve is reduced thanks to the presence of the
229 virtual ischemic region near the papillary muscle (ie, reduced passive and active heart contractility).
230 The last step shows the balloon filling phase at maximum expansion in the mitral position (Fig. 3F).
231 To evaluate the biomechanical performance of TMVR, the contact pressure and stent-anchoring
232 contact area over one cardiac beat were computed for both the mitral valve and band ring (Fig. 4).
233 For the band ring, both the contact pressure and area had a sharp rise during the S3 deployment
234 and then decreased during cardiac beating. For the mitral valve, contact pressure was high during

235 the passive left ventricular filling. Fig. 4C also shows the opened and closed configurations of
236 bioprosthesis valve leaflets at both end-systolic and end-diastolic cardiac phases.

237 Fig. 4D and E highlights the distribution of the mitral valve displacements and Von Mises stress
238 distribution at the end-diastole. The anterior mitral valve leaflet experienced a peak displacement
239 of 23 mm as compared to the closed configuration before device deployment. The leaflet free edge
240 is mostly displaced to the interventricular septum as compared to those the mitral annulus
241 constrained by the stiff band ring. The peak values of the Von Mises stress were observed near the
242 mitral valve annulus as caused by anatomic constraints. No considerable changes were observed
243 for mitral valve displacement and stress distributions during the cardiac beat (data not shown).

244 The neo-LVOT obstruction and resulting anatomic area were computed according to the workflow
245 suggested by Blanke and collaborators (Fig. 5) [4]. We generated the geometric centerline of the
246 aortic root and native LVOT anatomy, and then developed the cross-sectional plane perpendicular
247 to the centerline in correspondence with the smallest neo-LVOT area that was formed by the S3
248 Ultra frame and the interventricular septum. The mean value of the neo-LVOT area over a cardiac
249 beat was 367.7 mm^2 , but the numerical simulation revealed a high dynamic behavior of device-
250 related obstruction. Fig. 6 shows that the neo-LVOT area changed significantly over the cardiac
251 beat, with nearly a 50% reduction at peak systolic myocardial contraction (end-systole) with
252 respect to the relaxed myocardium (end-diastole). The comparative study using the stiff band ring,
253 high implantation depth and balloon overexpansion highlighted different TMVR simulation
254 outcomes (Fig. 7). Table 2 summarizes the changes of neo-LVOT area and contact pressure with
255 respect to the reference LHHM model.

256 Fig. 8 shows the blood flow velocity disturbances and pressure distribution encompassing the neo-
257 LVOT obstruction at the early systole. Hemodynamics evinced pronounced flow velocity near the
258 periphery of interventricular septum confined by the implanted device. Nested helical flow was
259 observed near the S3 skirt and the anterior mitral valve leaflet. A drop in the pressure field of 4.5
260 mmHg between the left ventricle and neo-LVOT region was computed.

261

262 4. Discussion

263 In this study, a realistic and high-fidelity computational tool of cardiac biomechanics was used to
264 virtually simulate the transcatheter mitral valve-in-ring replacement and then investigate the
265 hemodynamic and structural mechanics of LVOT obstruction. The most striking finding is the
266 assessment of the dynamic behavior of the neo-LVOT area over the cardiac cycle, suggesting that
267 the risk stratification of patients undergoing TMVR should not only be based on pre-TMVR imaging
268 criteria at end-systole. This finding improves our understanding of the impact that LVOT
269 obstruction has on THV performance and offers a computational approach to better assess the
270 anatomic suitability of patients undergoing TMVR. Ultimately, this knowledge has the potential to
271 enhance procedural planning to yield better clinical outcomes and to inform the way we design the
272 next-generation of transcatheter heart valves.

273

274 LVOT obstruction is a major concern in TMVR, but limited data exist regarding its biomechanical
275 implication on cardiac function. Major findings from computational analyses were related to the
276 computational fluid dynamic in left ventricular geometries with obstructions idealized as a rigid wall
277 protrusion (De Vecchi et al., 2018; Kohli et al., 2018). This approach made it possible to derive new
278 metrics for quantifying the hemodynamic alteration near the LVOT region and its effect on cardiac
279 function, as characterized by an increase in ventricular afterloads and a deterioration of systolic
280 flow efficiency. Recently, fluid-solid interaction analysis was developed to first simulate the THV
281 deployment and then evaluate the resulting hemodynamic environment (Pasta et al., 2020a).
282 However, the computational simulation run until the deployment phase, thereby not considering the
283 importance of the beating heart. Using the LHHM in the setting of TAVR, Ghosh and collaborators
284 (Ghosh et al., 2020) found that if the simulation is stopped short upon the deployment phase, the
285 anchoring behavior is unchanged as the device is virtually implanted at different heights. As the
286 heart starts beating, the important interaction between the tissue and device frame can be
287 realistically revealed to provide the performance of the implanted device in the aortic root. For pre-
288 TMVR assessment of patient anatomic suitability, computer-aided-design (CAD) principles and 3D

289 printing of human models were implemented to predict the impact of LVOT obstruction (Wang et
290 al., 2016). The workflow consisted of overlapping a cylindrical surface representing the THV
291 geometry on the segmented left ventricular patient anatomy at end-systole and then measuring the
292 neo-LVOT area using CAD tools. Different angles and implantation depths can be quickly obtained
293 by manipulation (ie, rotation and translation) of the cylindrical device geometry in the left ventricle.
294 The left heart is then manufactured in a rigid phantom to allow visual inspection of LVOT
295 obstruction from the aortic root view. Though neo-LVOT area predictions were found in good
296 agreement with those seen from post-TMVR imaging (Wang et al., 2018), this approach does not
297 consider the interaction of the deforming myocardial wall with the stiff THV stent frame.

298

299 A careful CT-based analysis of anatomic features in a patient is therefore the standard approach to
300 stratify patients at high risk of developing hemodynamic impairment associated with the neo-LVOT.
301 Blanke and collaborators (Blanke et al., 2017) therefore developed a workflow to virtually implant
302 the device model in the mitral valve and measure the smallest neo-LVOT area on the CT image.
303 Subsequently, the predictive performance of the cutoff value of the neo-LVOT area for
304 discriminating the risk of adverse events associated with the device elongation was demonstrated
305 in several clinical reports . However, the CT-based analysis described by Blanke et al (Blanke et
306 al., 2017) cannot consider the dynamic changes of the estimated neo-LVOT over the cardiac cycle.
307 In this study, we demonstrated a remarkable change in the neo-LVOT area ranging from a
308 maximum of 472.1 mm² at early systole to a minimum of 183.0 mm² at end-systole. The minimum
309 value of neo-LVOT area is therefore close to the clinical cut-off of 170 mm². The comparative study
310 demonstrated that role of band ring material properties, device overexpansion and suboptimal
311 implantation depth on the resulting device performance. Low magnitude of neo-LVOT area at
312 systole and diastole were found for the stiff band ring and balloon overexpansion, with lowest area
313 measurements when the fluid-filling volume was increased. In a different way, a shift of the
314 implantation depth towards the left atrium led to larger neo-LVOT area but lower contact pressure
315 on the mitral valve than that shown by the reference model following manufacturer guidelines. We

316 also observed that the mitral valve displacement does not vary during cardiac beating and thus
317 speculate that the changes in the neo-LVOT area are mainly caused by the myocardial contraction
318 occurring during systole rather than a motion of the S3 device. During systolic contraction, the
319 contact pressure and anchoring area of the S3 device revealed a slightly increase due to the
320 compression of the surrounding tissue on the band ring surface. The latter serves as the key
321 anchoring zone while the mitral valve is primally displaced by the deployed device. When observed
322 from the aortic root, the S3 device is partially covered by the mitral valve, which, together with the
323 sealing skirt, can lead to hemodynamic alteration in the neo-LVOT region. Our computational flow
324 analysis revealed a sub-stenotic aortic stenotic flow and a pressure drop at the neo-LVOT region.
325 These parameters may allow for more accurate prediction of the LVOT obstruction in TMVR,
326 particularly for patients considered to have a borderline risk of obstruction. The implanted device
327 frame presented distorted cells likely caused by the fact that the S3 Ultra is not specifically
328 designed to treat the mitral valve, and this may prevent correct functioning. Clinical studies have
329 demonstrated the feasibility of TMVR with the S3 device (Babaliaros et al., 2021), but the long-term
330 outcome have been not addressed yet. Findings as here reported can be used as input to design
331 the next generation of THV with unique design features for TMVR procedures.

332

333 Though the most advanced cardiac tool was used for a deep investigation of the neo-LVOT
334 biomechanics, this study presents several limitations caused by the complexity of TMVR. The
335 LHHM anatomic geometry and function are likely different from those of the patient undergoing
336 TMVR. A fully-coupled fluid-solid interaction analysis for assessing the hemodynamic disturbances
337 induced by LVOT obstruction is highly desirable, albeit hugely challenging. The mitral valve leaflets
338 of LHHM are relatively short even if they are considered in the normal physiological range. The last
339 version of LHHM allows the change of mitral valve geometry and mesh but only the left atrial and
340 ventricular chambers are implemented in the numerical cardiac tool. A frictionless contact condition
341 was assumed between the device and human host while literature data suggests friction coefficient
342 in the range of 0.1 and 0.2. Most importantly, the present computational simulation lacks of a

validation and verification assessment to assess the accuracy of the model predictions. This is not feasible as the LHHM is based on ideal adult geometry. A comparative analysis with measurements done by post-TMVR imaging demonstrates that our prediction of the neo-LVOT area agrees well with data reported by Yoon et al (Yoon et al., 2019), who suggested values of neo-LVOT area ranging from 220 mm² to 430 mm² in a large cohort of valve-in-ring patient cases. Verification on the mesh and model setting should be carried out to establish the simulation credibility and reliability. Though element convergence was not performed, the LHHM was found to provide a steady-state solution with stable stress values after three cardiac cycles with the mesh volume here used. The constitutive model of passive and active contraction as well as the electrical model were validated against experimental data. Finally, current validation studies of LHHM have shown a good agreement with clinical data in terms of left and right ventricular ejection, maximum and minimum blood pressure for the four heart chambers and maximum left ventricular apex-base shortening (Baillargeon et al., 2014).

356

357 **5. Conclusion**

Our findings are relevant to a) reduce the gap in the knowledge of TMVR when THVs are used off label for mitral implantation, and b) provide relevant structural and hemodynamic metrics to develop THVs specifically designed to accommodate the challenging mitral valve function. Future studies in patient-specific geometries including different mitral valve morphologies different sizes of mitral valve leaflets and stiff versus flexible band rings will help to achieve better translational clinical value by enhancing the pre-TMVR planning in borderline patient anatomy.

364

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369 SimInSitu project (No 101017523) for supporting her research fellowship.

370

371 **Conflict of interest statement**

372 The authors declare that they have no known competing financial interests or personal
373 relationships that could have appeared to influence the work reported in this paper.

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480

481 **Figure Captions**

482 **Fig 1** (A) LHHM model with insets showing the mitral valve and chordae as well as the ischemic
483 region (red color) of the left ventricle generated for developing the mitral valve regurgitation; (B)
484 unfolded and folded balloon surface model and crimped S3 model

485 **Fig 2** Flow boundary conditions at both inlets and outlets; the inflow velocity is a representative
486 flow profile imposed on the pulmonary vein while other inflow profiles branches are scaled version
487 of the present one and are obtained from proportionality of each pulmonary vein cross-sectional
488 area and mass balance conservation. For outlet, the physiological pressure profile seen by the left
489 ventricle was applied to aortic root outflow surface.

490 **Fig 3** Various steps of the S3 THV deployment for the mitral valve in-ring treatment

491 **Fig 4** Profiles of the contact pressure and area exerted on both the (A) band ring and (B) mitral
492 valve; (C) opened and closed configuration of S3 valve leaflets as mapped after the deployment
493 phase, map of (D) displacement and (E) Mises stress distribution of mitral valve at end-systole

494 **Fig 5** Different 3D views of the neo-LVOT area (top left shows the calculation approach) at end-
495 systole

496 **Fig 6** Profiles of the neo-LVOT area changes over the cardiac beat; insets shows neo-LVOT area
497 at end-systole and end-diastole

498 **Fig 7** Changes in the TMVR simulations in case of a stiff band, balloon overexpansion and high
499 implantation depth.

500 **Fig 8** End-systolic distribution of blood-flow velocity showing subaortic flow stenosis in the neo-
501 LVOT and blood pressure with the drop computed between the left ventricle neo-LVOT area

502

503

504 **Table 1:** Material parameters of mitral valve, left ventricle and ischemic region

	a (MPa)	b	a _f (MPa)	b _f	a _s (MPa)	b _s	a _{fs} (MPa)	b _{fs}	C _{a0} (μmol/L)
Mitral Valve	8.7e-4	2.7	5.0e-4	12.0	3.8e-3	7.6e-1	3.8e-3	7.6e-1	
Left ventricle	4.0e-1	12.0	5.0e-1	5.0	2.0e-1	2.0	1.1e-2	2.0	2.66
Ischemic region	5.2e-1	12.0	5.0e-1	5.0	2.0e-1	2.0	1.1e-2	2.0	2.12

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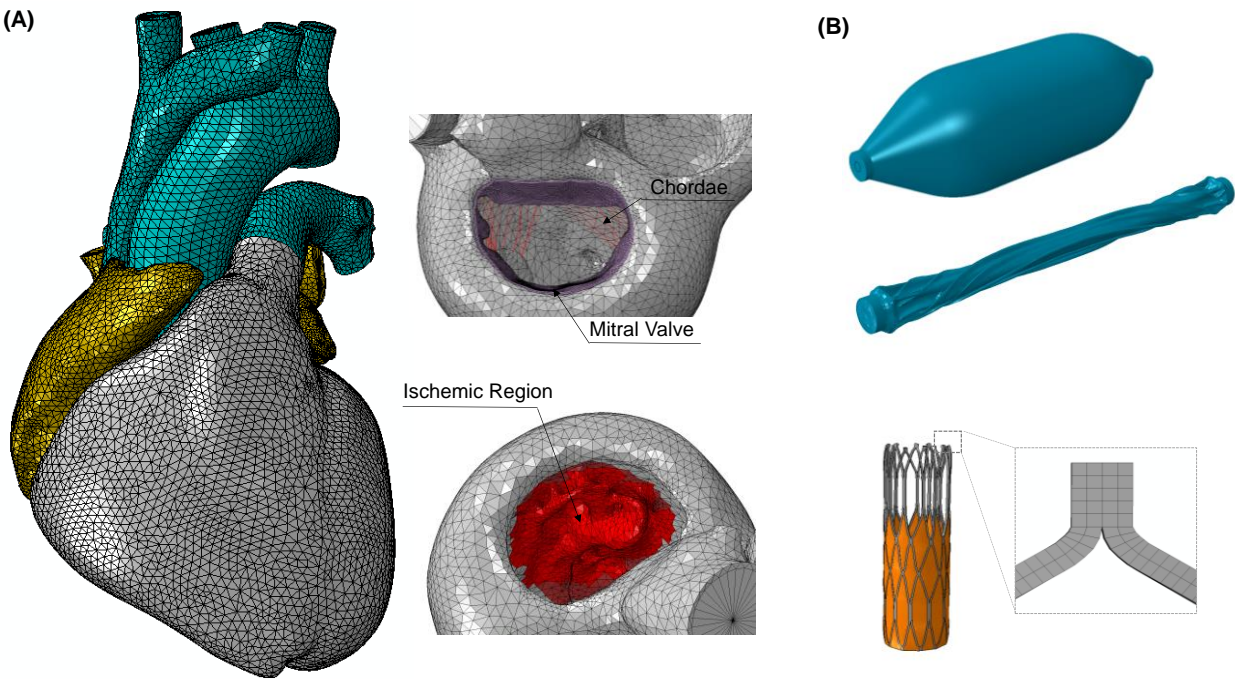
510 **Table 2:** Comparison of neo-LVOT area values among different parametric models

	Neo-LVOT area (mm ²)		Contact Pressure (MPa)	
	Max	Min	Ring	Mitral Valve
Reference Model	472.1	183.0	28.2	26.7
Stiff Band Ring	455.8	165.7	41.6	32.5
Balloon Overexpansion	434.6	151.4	32.8	29.4
High Implantation Depth	495.6	201.2	30.5	22.3

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512

513 **Fig. 1**

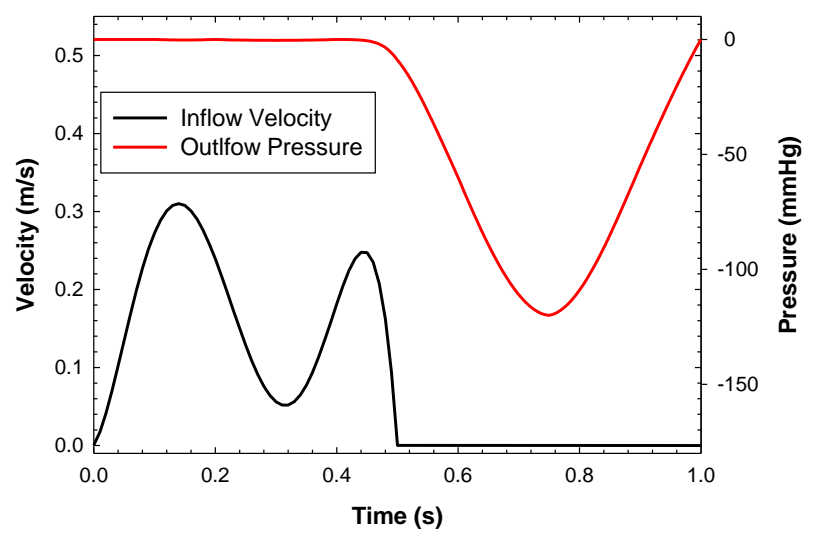


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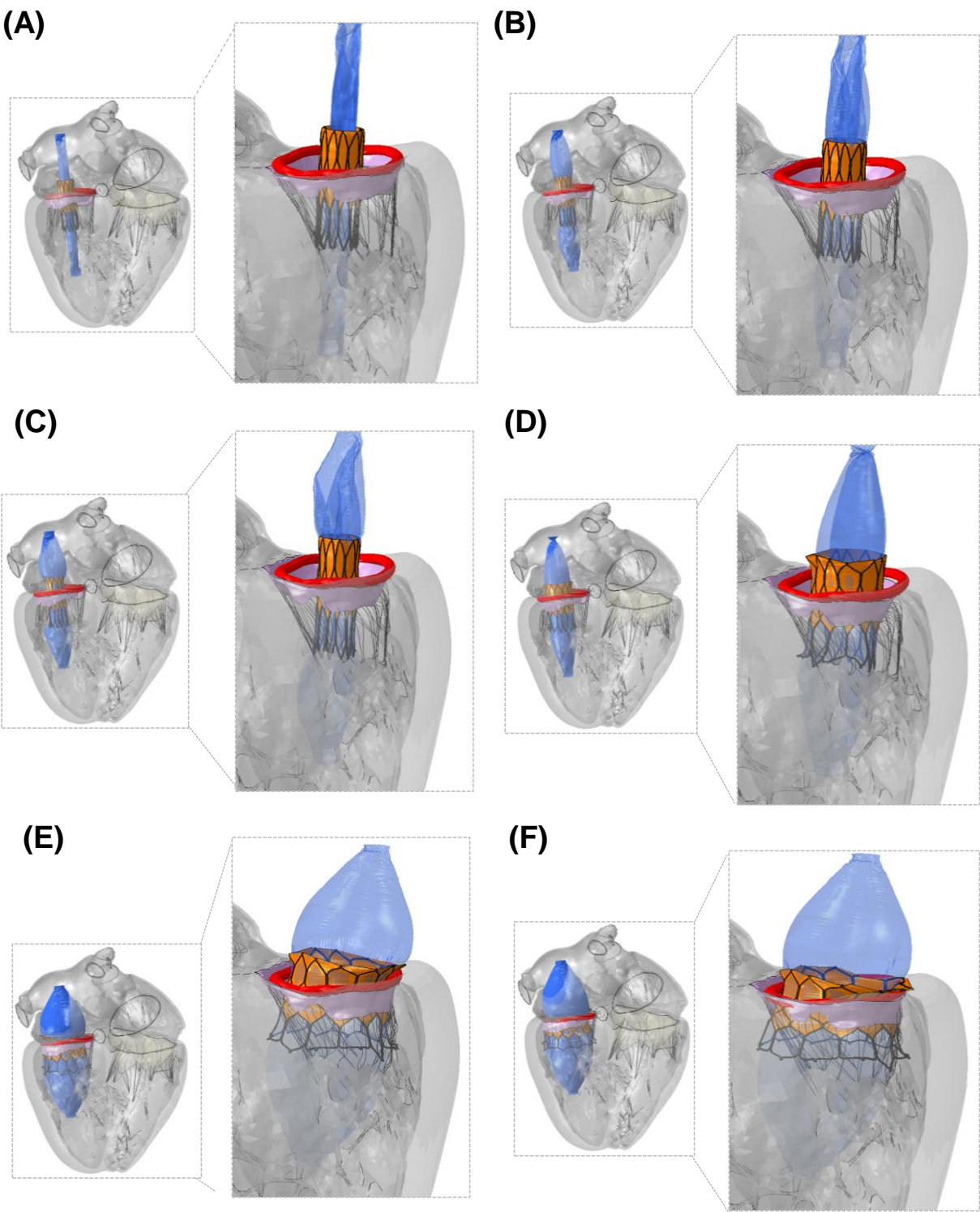
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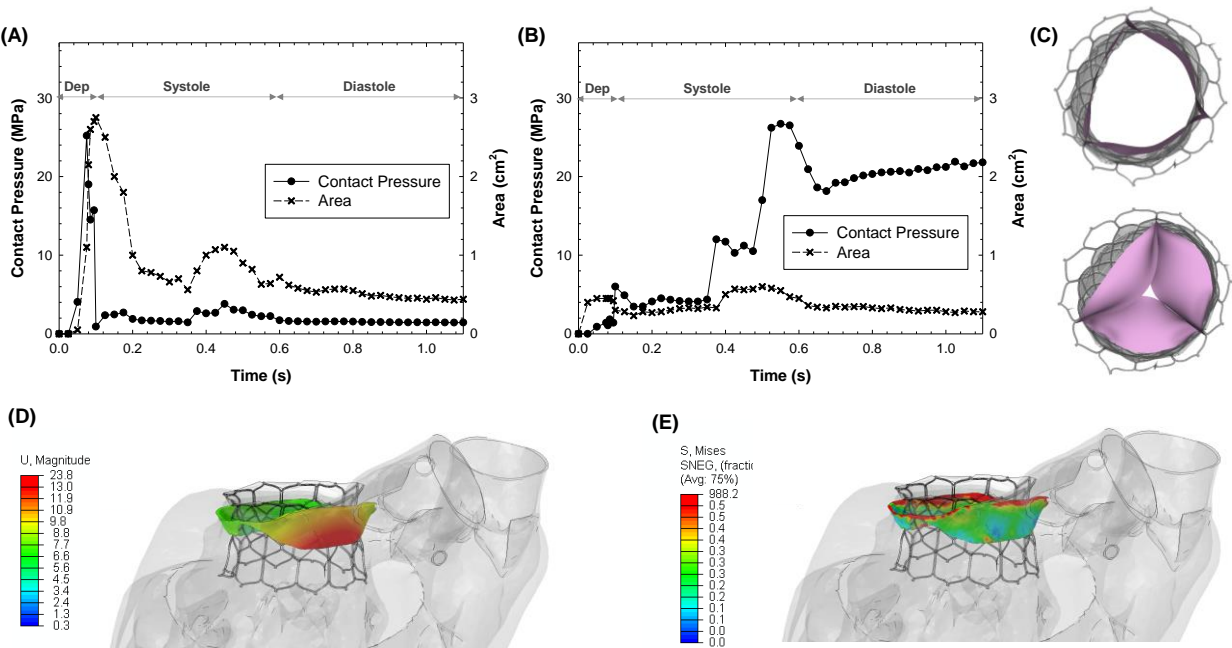
517 **Fig.2**

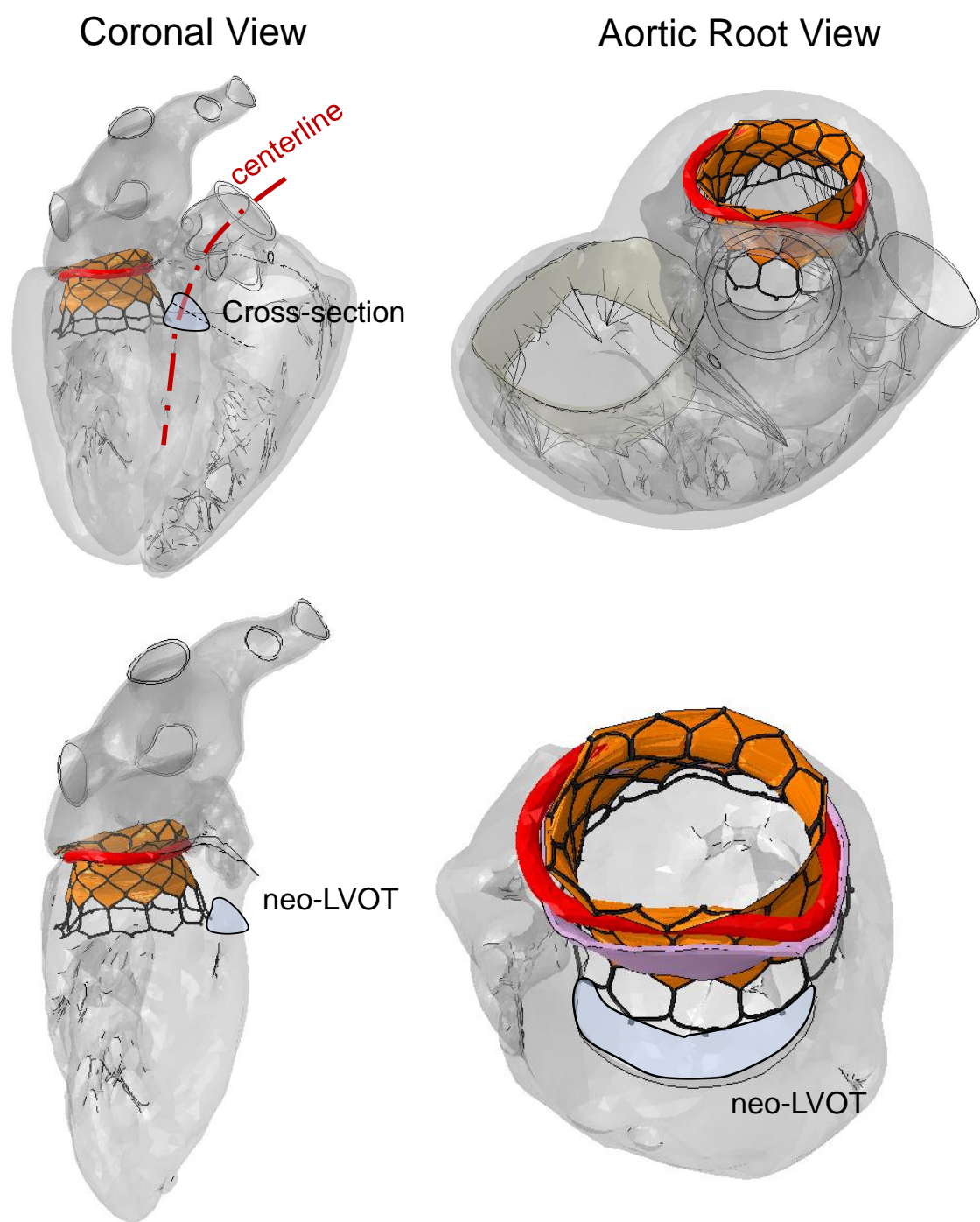


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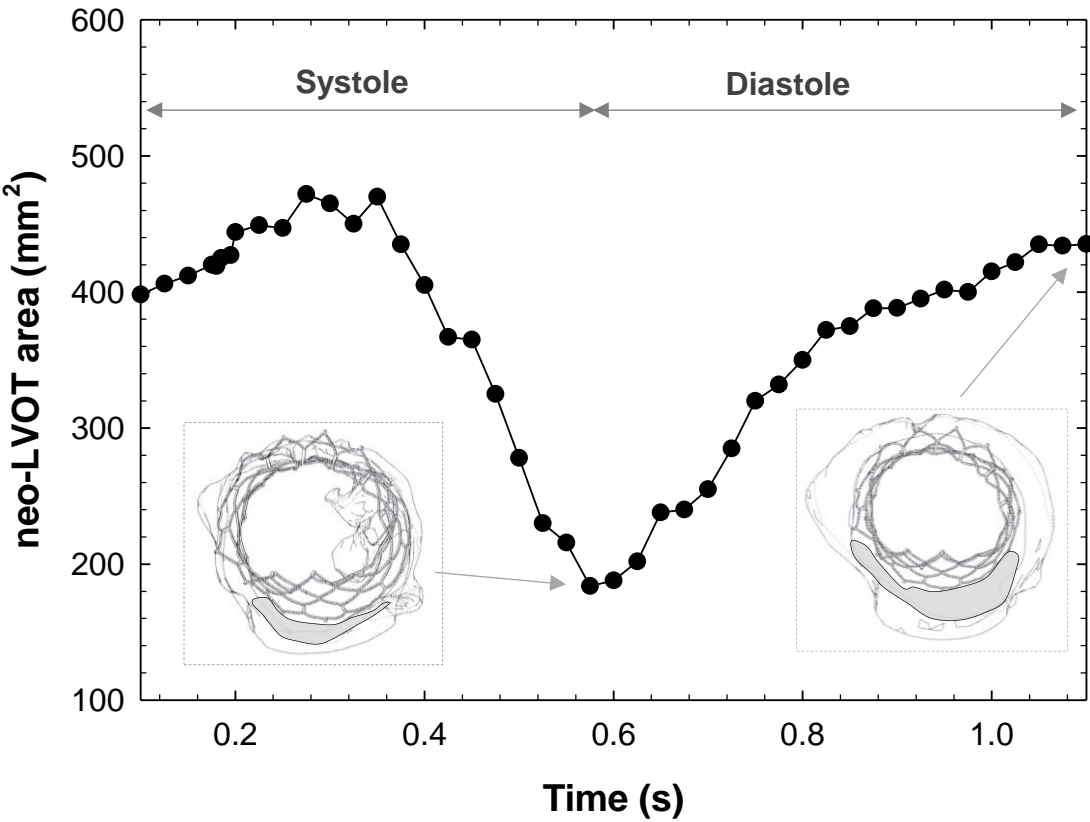


522 **Fig. 4**





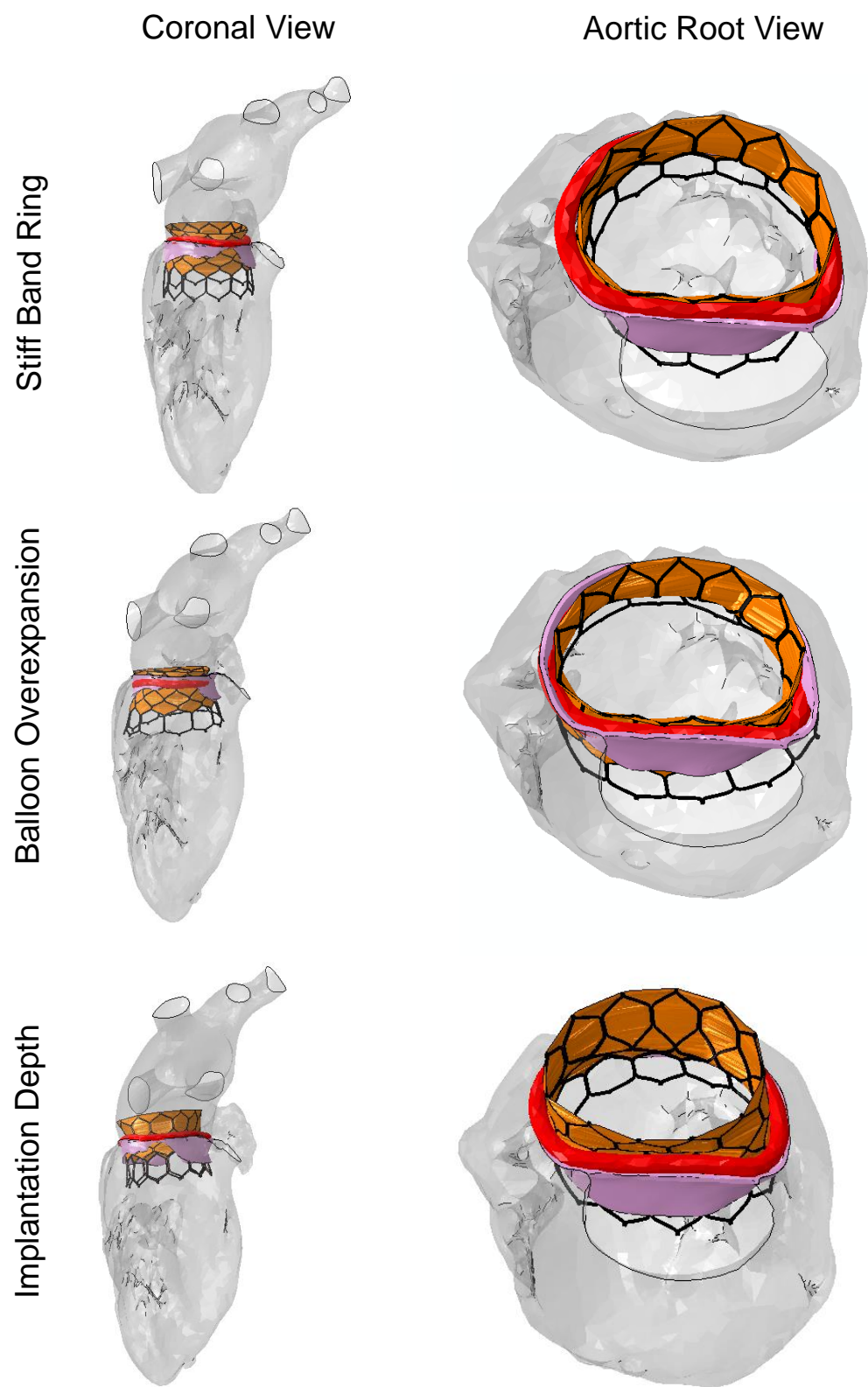
529 **Fig. 6**



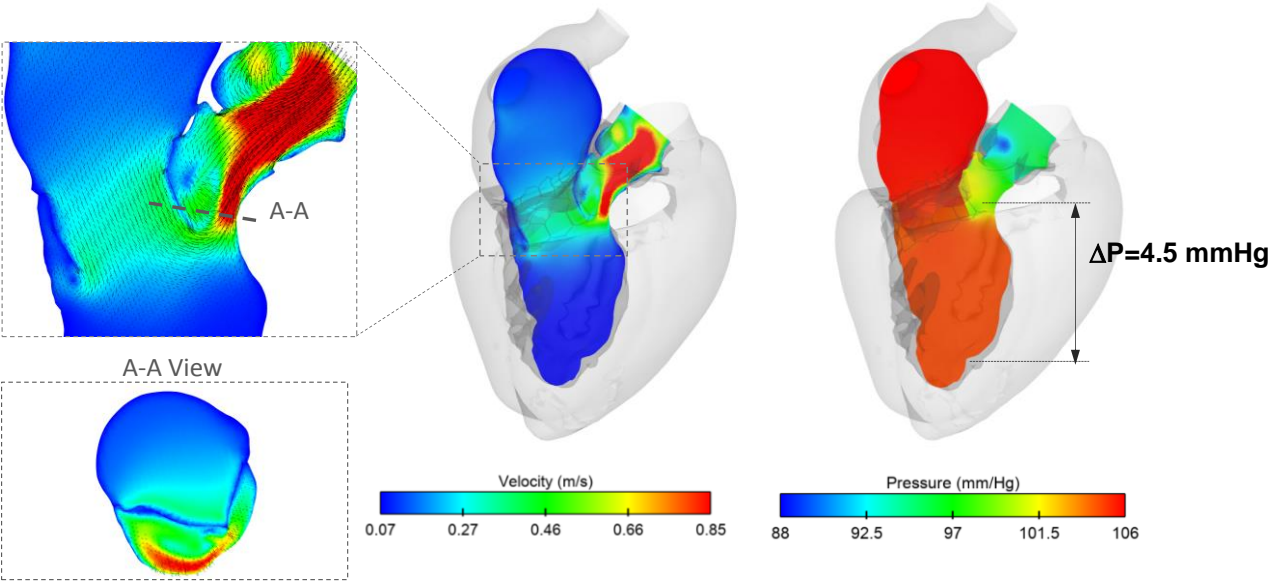
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535 **Fig. 8**



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Dear Editor,

On the behalf of all authors, the present letter asserts that authors did not have any financial and personal relationships with other people or organisations that could inappropriately influence (bias) their work.

Best Regards,

The image shows two handwritten signatures in black ink. The first signature on the left is 'SP' for Salvatore Pasta, and the second signature on the right is 'RR' for another author. Both are written in a cursive, stylized font.

Salvatore Pasta, Ph.D.,
Università di Palermo
Viale delle Scienze
Italy